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# PSB

## Pipelined Synchronising Buffer Module

9U-Version

H. Bergauer, K. Kastner, M. Padrta, A. Taurok



Aug-05

Version 1.1  
with  
PSB chip V0005

# 1 PSB Module 9U description

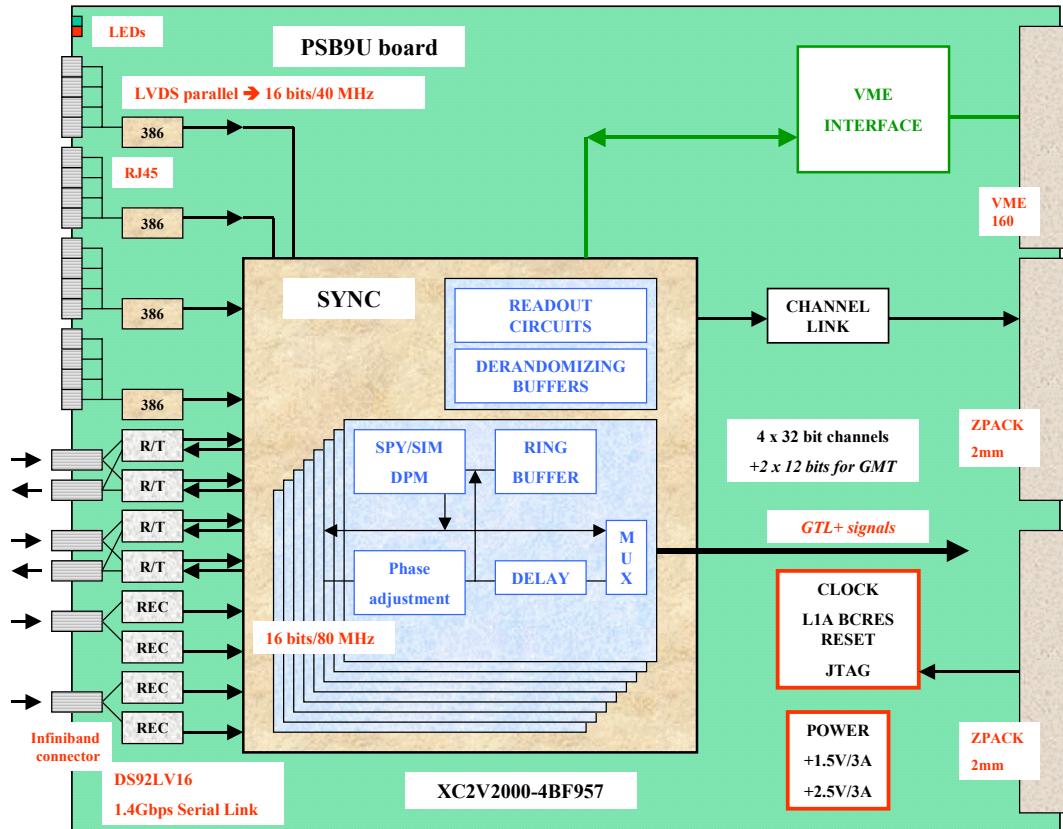


Figure 1 : PSB Overview

The PSB9U board receives 1.4 Gbps serial data from the Calorimeter trigger system, converts the serial bits into 16 bit words, synchronizes the words to the local clock, applies a programmable delay and sends the trigger objects as 80 MHz GTL<sub>p</sub> signals via the back-plane to the destination boards. Therefore each data channel contains the data bits of two time-multiplexed trigger objects.

The PSB9U boards are used by the Global Trigger as well as by the Global Muon Trigger. Four Infiniband connectors forward the serial data to 8 DS92LV16 interface chips. After the serial to parallel conversion the 80 MHz data streams enter two Synchronization chips (=SYNC) where all the synchronization and monitoring logic is implemented.

The Synchronization Chip contains the over-sampling circuit that samples each word 4 times that means every  $12.5/4 = 3.01$  ns. The sample furthest from the data switching time is connected to the following programmable delay. After the delay the trigger words go through a multiplexer and then as terminated GTL<sub>p</sub> signals to the back-plane. The multiplexer circuit allows sending test data instead of trigger data to the back-plane.

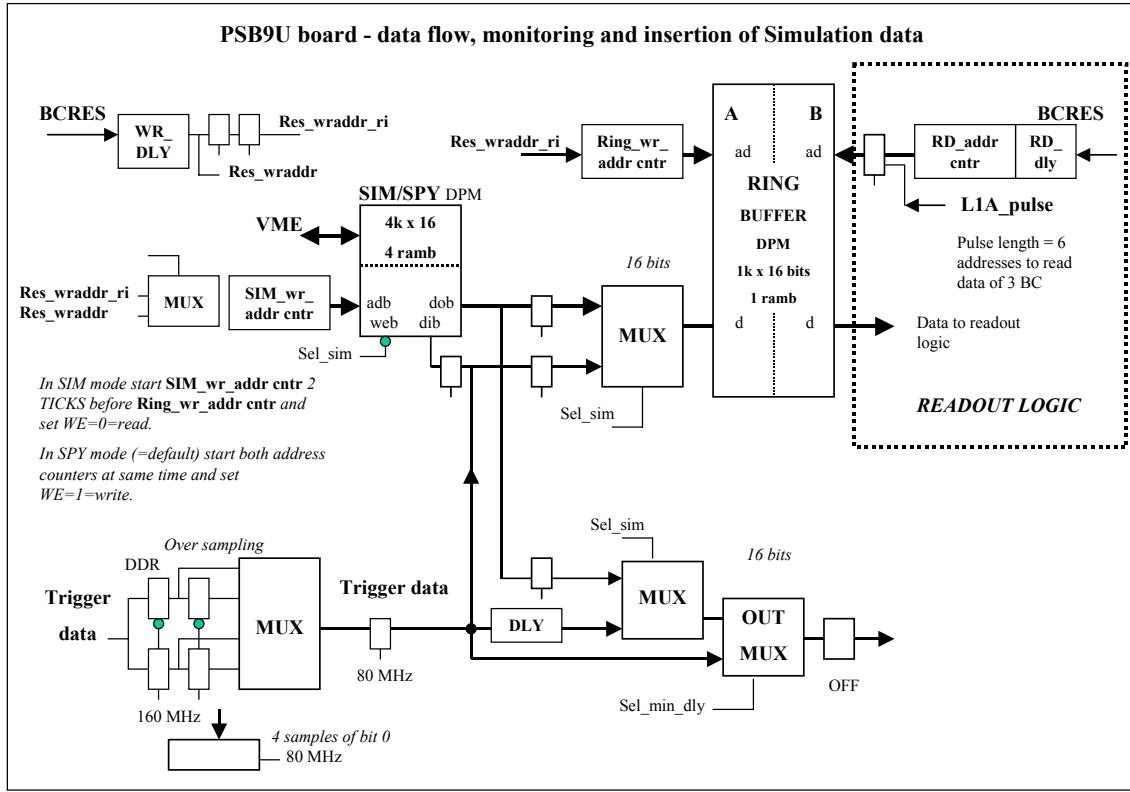


Figure 2 PSB9U data flow and monitoring scheme

For each 16-bit data stream a Ring Buffer memory monitors the trigger data. The memory runs in dual port mode. At one side the delayed trigger data are written continuously into the memory using addresses generated by a counter. The common Bunch Crossing Reset (BCRES) signal clears the counter synchronously to the clock thereby locking the addresses to the LHC orbit. After the end of the memory the DAQ-readout circuit applies a read address to get the data of the bunch crossing that has generated a L1A trigger signal. The read address is also supplied by a counter running synchronously to the LHC orbit. But a delayed BRES signal clears the read counter later than the write counter to compensate the trigger latency, that is the period between the writing time and a read access due to a L1A signal generated by trigger data of this bunch crossing. The length of the Ring Buffer memory (256 words) far exceeds the trigger latency.

Each (pair of) 16-bit channel(s) is locked separately to the LHC clock and to the orbit to compensate different cable delays.

The SYNC chip contains a second set of memories to load test or simulation data and to send them either once or repeatedly instead of trigger data to the Ring-Buffer and via the backplane to the GTL respectively to the GMT board.

The readout circuits and a Derandomizing Buffer are either implemented in the SYNC chip or in a dedicated ROP chip if more than one SYNC chip per board is required.

## 1.1 Parallel LVDS input data

The PSB9U accepts also up to 64 bits of parallel trigger data alternatively to data from one Infiniband cable. The 40 MHz parallel input bits are accepted as LVDS signals received by 16 RJ45 connectors, each accepting 4 signals. The PSB board expects negative logic for

differential signals. **Trigger bit =1 is expected with a negative voltage difference.** The SYNC chip inverts the values back to the true input levels before transmission.

### 1.1.1 Synchronization of 40 MHz parallel trigger data

As the precise arrival time of the data bits is unknown the SYNC chip first samples the input bits 4 times per bunch-crossing period (~25 ns) to find the switching point of the input data. Phase selection and delay adjustment are done separately for each 4-bit group to consider time skew between cables and link chips. The SYNC chip takes the sample furthest away from the switching time, delays it for a programmable period, multiplexes the data into a 80 MHz data stream and sends the data as GTL+ signals over the back-plane to the logic board (GTL).

The SYNC chip also writes the input data into a RING BUFFER and in addition into a SPY memory for monitoring. The Ring Buffer runs continuously overwriting old data. If a Level-1 Accept (L1A) signal arrives at the PSB board, data are moved from the Ring Buffer into a Derandomizing Memory to be transferred later by the Readout Processor (ROP) to the readout board (GTFE).

#### 1.1.1.1 Totem Trigger bits

Up to 16 bits are booked be the TOTEM Trigger (May 2004).

#### 1.1.1.2 Free trigger bits (48)

48 bits are free (May 2004).

### 1.1.2 Synchronization of Technical Trigger bits

One PSB module accepts ‘Technical Trigger’ signals, which might not arrive as 40 MHz pulses. Therefore an edge sensing circuit generates synchronously to the system clock signal a 25ns pulse if either a rising or falling edge has been detected.

## 2 Keywords

### 2.1 RESET Signals

#### POWER OFF and ON

To switch the GT-crate off is the last option to reset non-working Global Trigger electronics.

**NSYSRES** → configuration of FPGAs

The common crate-reset signal NSYSRES starts the configuration procedure for all FPGAs except the VME64 chip. It pulls the NPROG net to a low voltage level forcing the VME and the PSB chip to reconfigure from Proms.

#### RESET\_DCM\_PSB

The VME chip sends **RESET\_DCM\_PSB** to resynchronize the clock in the PSB chip to the board CLK.

#### RESET\_PSB and INACTIVE → STARTUP of PSB chip

The VME chip sends **RESET\_PSB** to reset the STARTUP module inside the PSB chip and the common INACTIVE signal enables the IO-pins to switch from high-Z to active mode.

**RESET\_PSB** → GSR pin of STARTUP → set initial default values of registers

**INACTIVE** → GTS pin of STARTUP

The **RESET\_PSB** should reload the initial default values into all registers.

#### L1RES, BCRES, L1A → reset State Machines and Counters

The Trigger Control System sends via the backplane the signals L1RES, BCRES, L1A and Event Counter Reset to reset state machines and counters

- L1RES clears the event data in the FIFOs.
- The ROC state machine returns always to IDLE state and cannot be reset. It stays in IDLE mode when the FIFOs are empty or when READY =0 (defined by software).

## **2.2 BCRES signal**

It is possible that the distributed BCRES signal does not arrive every LHC orbit. An internal BC-counter and an Orbit\_Length register are used to generate an internal BCRES signal running in phase with the distributed signal. Every circuit uses the internal BCRES signal to remain locked to the LHC orbit.

## **2.3 Sync check for BC0 data**

Spy logic stores the arrival time of the SYNC bits as defined in the interface note CMS-IN-02-069.pdf for each 16 bit word. The number can be read by VME. A difference to a default value will be flagged as an error.

## **2.4 Phase check with over-sampling bits**

All four samples of bit 0 are spied and compared to each other to find the time when the input data change their state. Four phase counters are incremented to check the stability of trigger data. At the end of every LHC orbit the counter contents are saved to be read by VME and the counters cleared. The contents are used to decide which sample should be taken as reliable data input.

## **2.5 Private Monitoring (option)**

The 8kwords long SIM memory can run also in SPY mode to store a complete LHC orbit. In spy-mode the SIM/SPY memory will be written in parallel with the Ring-Buffer but can be read by VME. It can be used to get a ‘snap shot’ of the input data.

## **2.6 Test modes**

- Read-back registers and memories in the SYNC chip allow checking VME accesses.
- The SIM/SPY memory is used to send test- or simulation data to other boards.
- VME generated BCRES pulses and an on-board 40 MHz oscillator are used to run tests also in stand-alone mode.

## **2.7 SIM/SPY Memories and serial outputs**

For each channel a 8kW SIM/SPY memory can be used either to spy input data or to send simulation data to the back-plane and for channels 0...3 also to the transmitter part of four DS92LV16 Serial Link Chips. Two output connectors are foreseen to send test data to channels 4 to 7 on the same board or to other PSB boards.

## **2.8 Configuration modes**

### **2.8.1 PROM and JTAG**

PROMS contain the default configuration that is loaded

- at start-up time or whenever
- a SYSRESET signal arrives from the VME or by a
- NPROG command sent by software.

The Proms are be loaded by JTAG.

- JTAG connectors are foreseen for the Parallel-CableIV interface that is used to download the configuration file from a Notebook-PC.
- JTAG via VME loads the PROMS via the emulated JTAG interface in the VME chip. A configuration program takes the configuration files and loads the data serially into the Proms.

The configuration options above require that the PSB chip has been set by solder-jumpers to MASTER MODE.

## 2.8.2 Other configuration options

For tests other configuration options are possible, but then the PSB chip has to be re-soldered to SLAVE mode. Using an optional modification on the PSB Mezzanine board it will/might also be possible to switch by a software command to Slave Mode.

## 2.9 Power

+5V and +3.3V are provided by the backplane. Linear voltage generators provide +2.5V and +1.5V for the FPGA chips.

## 2.10 Front Panel

**240 mm** = 4x60mm ... 4 4-fold Ethernet connectors

**80 mm** = 6 x 15 ... 6 Infiniband conn

**7 mm** LEMO connector

**0mm** = LEDs mounted above Infiniband connectors

= **327 mm**

## 2.11 Sync IO-pins, ram-blocks

**XC2V2000-4 BF957** mounted on MEZZ957 board

56 ramb; Mezz957: 641 io-pins connected to PSB9U board

**565** IO-pins:

8x16 in+ 4x16 par\_in + 4x16 out (DS92LV16; test)

+ (128+24)GTLp + 21 VREF+ 59 VME(32bit)

+ 29 ChLink + 16 RO-bus

+ 3(L1A,BCRES,L1RESET) +4 Status + 5Config + 20 VRN/VRP

**50** RAM blocks:

8x4 Spy + 8 Ring + 8 Derand + (1Ring+1Derand for BCnr)

*Other chip types: xc2v1500: 48 ramb; xc2v3000: 96 ramb; Mezz896: ca 600io*

**It might be required to use a XC2V3000-4 BF957 to implement all circuits.**

# 3 VME chip PSB - V1000

## 4 PSB chip Adresses

### 4.1 Overview VME Addresses

A23-20: = 0001 ...PSB chip

(A23-20: = 0002 ...PSB chip memories is not used in present design)

19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0	0	Register space	(1kx16 readback)									
0	0	0	0	0	0	0	0	1	Read only status registers										
0	0	1	0	0	0				Sim_Spy_memory 0	(8kx16)									
0	0	1	0	0	1				Sim_Spy_memory 1	(8kx16)									
0	0	1	0	1	0				Sim_Spy_memory 2	(8kx16)									
0	0	1	0	1	1				Sim_Spy_memory 3	(8kx16)									
0	0	1	1	0	0				Sim_Spy_memory 4	(8kx16)									
0	0	1	1	0	1				Sim_Spy_memory 5	(8kx16)									
0	0	1	1	1	0				Sim_Spy_memory 6	(8kx16)									
0	0	1	1	1	1				Sim_Spy_memory 7	(8kx16)									

### 4.2 Sim Spy Memories

*Remark: In present chip design the memories are also in same address space as the registers.*

BB12 0000	SIM_SPY_MEM0	w/r
BB12 4000	SIM_SPY_MEM1	w/r
BB12 8000	SIM_SPY_MEM2	w/r
BB12 C000	SIM_SPY_MEM3	w/r
BB13 0000	SIM_SPY_MEM4	w/r
BB13 4000	SIM_SPY_MEM5	w/r
BB13 8000	SIM_SPY_MEM6	w/r
BB13 C000	SIM_SPY_MEM7	w/r

### 4.3 Register overview

BB10 0000	CHAN_REG0	w/r
BB10 0002	CHAN_REG1	w/r
BB10 0004	CHAN_REG2	w/r
BB10 0006	CHAN_REG3	w/r
BB10 0008	CHAN_REG4	w/r
BB10 000A	CHAN_REG5	w/r
BB10 000C	CHAN_REG6	w/r
BB10 000E	CHAN_REG7	w/r

#### \*\*\* Delay Registers for Serial Link channels\*\*\*

BB10 0010	CHAN_DELAY0	w/r
BB10 0012	CHAN_DELAY1	w/r
BB10 0014	CHAN_DELAY2	w/r
BB10 0016	CHAN_DELAY3	w/r

BB10 0018	CHAN_DELAY4	w/r
BB10 001A	CHAN_DELAY5	w/r
BB10 001C	CHAN_DELAY6	w/r
BB10 001E	CHAN_DELAY7	w/r
<b>*** Delay Registers for parallel LVDS data channels***</b>		
BB10 0020	LVDS_DELAY0	w/r // bit 3-0
BB10 0022	LVDS_DELAY1	w/r // bit 7-4
BB10 0024	LVDS_DELAY2	w/r
BB10 0026	LVDS_DELAY3	w/r
BB10 0028	LVDS_DELAY4	w/r
BB10 002A	LVDS_DELAY5	w/r
BB10 002C	LVDS_DELAY6	w/r
BB10 002E	LVDS_DELAY7	w/r
BB10 0030	LVDS_DELAY8	w/r
BB10 0032	LVDS_DELAY9	w/r
BB10 0034	LVDS_DELAY10	w/r
BB10 0036	LVDS_DELAY11	w/r
BB10 0038	LVDS_DELAY12	w/r
BB10 003A	LVDS_DELAY13	w/r
BB10 003C	LVDS_DELAY14	w/r
BB10 003E	LVDS_DELAY15	w/r // bit 63-60
<b>*** Setup Registers ***</b>		
BB10 0040	BOARD_ID	w/r
BB10 0042	BCRES_DELAY	w/r
BB10 0044	LATENCY_DELAY	w/r
BB10 0046	ROP_SETUP	w/r
BB10 0048	MAX_BC_NUMBER	w/r //=orbit length -1
BB10 004A	SEL_PHASE3100	w/r // select phases for LVDS data
BB10 004C	SEL_PHASE6332	w/r // select phases for LVDS data
BB10 004E	IDLE_ID_LOW	w/r // idle identifier low part
BB10 0050	IDLE_ID_HIGH	w/r // idle identifier high part
BB10 0052	TESTMASK0	w/r // tespoint 0 bits
BB10 0054	TESTMASK1	w/r // tespoint 1 bits
BB10 0056	TESTMASK2	w/r // tespoint 2 bits
BB10 0058	TESTMASK3	w/r // tespoint 3 bits
BB10 005A	TESTMASK4	w/r // tespoint 4 bits
BB10 005C	TESTMASK5	w/r // tespoint 5 bits
BB10 005E	TESTMASK6	w/r // tespoint 6 bits
<b>*** Write Only Command Pulses ***</b>		
BB10 0070	CMD_PULSE	w/-
<b>+++++ READ ONLY ADDRESSES +++++</b>		
<b>*** Phase Counters for Serial Link channels ***</b>		
BB10 0800	PHASE_CNTR_A0	-/r // compares ph1-ph0 and ph0-pre3
BB10 0802	PHASE_CNTR_A1	-/r
BB10 0804	PHASE_CNTR_A2	-/r
BB10 0806	PHASE_CNTR_A3	-/r
BB10 0808	PHASE_CNTR_A4	-/r
BB10 080A	PHASE_CNTR_A5	-/r

BB10 080C	PHASE_CNTR_A6	-/r
BB10 080E	PHASE_CNTR_A7	-/r
BB10 0810	PHASE_CNTR_B0	-/r
BB10 0812	PHASE_CNTR_B1	-/r
BB10 0814	PHASE_CNTR_B2	-/r
BB10 0816	PHASE_CNTR_B3	-/r
BB10 0818	PHASE_CNTR_B4	-/r
BB10 081A	PHASE_CNTR_B5	-/r
BB10 081C	PHASE_CNTR_B6	-/r
BB10 081E	PHASE_CNTR_B7	-/r

**\*\*\* Phase Counters for parallel LVDS data channels \*\*\***

BB10 0820	PHASE_CNTR_A0_3	// compares ph1-ph0 and ph0-pre3 of bits 0-3
BB10 0822	PHASE_CNTR_A4_7	// compares ph1-ph0 and ph0-pre3 of bits 4-7
BB10 0824	PHASE_CNTR_A8_11	
BB10 0826	PHASE_CNTR_A12_15	
BB10 0828	PHASE_CNTR_A16_19	
BB10 082A	PHASE_CNTR_A20_23	
BB10 082C	PHASE_CNTR_A24_27	
BB10 082E	PHASE_CNTR_A28_31	
BB10 0830	PHASE_CNTR_A32_35	
BB10 0832	PHASE_CNTR_A36_39	
BB10 0834	PHASE_CNTR_A40_43	
BB10 0836	PHASE_CNTR_A44_47	
BB10 0838	PHASE_CNTR_A48_51	
BB10 083A	PHASE_CNTR_A52_55	
BB10 083C	PHASE_CNTR_A56_59	
BB10 083E	PHASE_CNTR_A60_63	// compares ph1-ph0 and ph0-pre3 of bits 60_63
BB10 0840	PHASE_CNTR_B0_3	// compares ph3-ph2 and ph2-1 of bits 0-3
BB10 0842	PHASE_CNTR_B4_7	// compares ph3-ph2 and ph2-1 of bits 4-7
BB10 0844	PHASE_CNTR_B8_11	
BB10 0846	PHASE_CNTR_B12_15	
BB10 0848	PHASE_CNTR_B16_19	
BB10 084A	PHASE_CNTR_B20_23	
BB10 084C	PHASE_CNTR_B24_27	
BB10 084E	PHASE_CNTR_B28_31	
BB10 0850	PHASE_CNTR_B32_35	
BB10 0852	PHASE_CNTR_B36_39	
BB10 0854	PHASE_CNTR_B40_43	
BB10 0856	PHASE_CNTR_B44_47	
BB10 0858	PHASE_CNTR_B48_51	
BB10 085A	PHASE_CNTR_B52_55	
BB10 085C	PHASE_CNTR_B56_59	
BB10 085E	PHASE_CNTR_B60_63	// compares ph3-ph2 and ph2-1 of bits 60_63

**\*\*\* Status registers \*\*\***

BB10 0860	PSB_STATUS	-/r
BB10 0862	ROP_STATUS	-/r
BB10 0864	CHIP_ID	-/r
BB10 0866	VERSION_NR	-/r
BB10 0868	CHIP_IDH	-/r

\*\*\*\*\* END OF OVERVIEW \*\*\*\*\*

## 4.4 8 Channel Registers

write & read	functions
BB10 0000 CHAN_REG0	rx tx lvds
BB10 0002 CHAN_REG1	rx tx lvds
BB10 0004 CHAN_REG2	rx tx
BB10 0006 CHAN_REG3	rx tx
BB10 0008 CHAN_REG4	rx
BB10 000A CHAN_REG5	rx
BB10 000C CHAN_REG6	rx
BB10 000E CHAN_REG7	rx

Channels 0,1: Parallel LVDS data can be received instead of the serial input data.

Channels 0,1,2,3: Simulation data can also be sent via the serial transmitter circuits to two front panel connectors.

Channels 4,5,6,7: receive serial data only.

If we select simulation mode (**sel\_sim\_mode=1**) for these channels then LVDS data are not transferred to the FDL board (Technical trigger bits) and not to the GTL board (TOTEM trigger bits).

- bits 15-6 : free
  - bit 5: **en\_trx\_data**
    - =1: send data from SIM\_SPY memory also via DS92LV16 Serial Link transmitter to the Frontpanel connector.
  - bit 4: **sel\_contin\_mode**
    - =1: The SIM\_SPY memory runs continuously either sending simulation data or storing input data
    - =0: The SIM\_SPY memory runs for one orbit only and stops afterwards.
  - bit 3: **sel\_sim\_mode**
    - =1: The SIM\_SPY memory sends simulation data to the backplane and if enabled in channels 0-3 also to the DS92LV16 Serial Link transmitters.
    - =0: The SIM\_SPY memory stores input data for monitoring tasks.
    - For channels 0 and 1 the simulation data will replace either serial or parallel trigger data.*
  - bit 2: **sel\_lvdsdata**
    - ...is valid for channels 0 and 1 only. For channels 2...7 it has to be set =0 otherwise no data will be transferred.
    - =1: Send parallel LVDS data to the backplane (Technical Trigger data)
    - =0: Send data from the DS92LV16 Serial Link to the backplane (Calorimeter trigger data)
  - bit 1: **sel\_phase(1)**
  - bit 0: **sel\_phase(0)**
    - Select Phase in over-sampling circuit to forward the trigger input data from the serial link. Take the sample that is most far from the data switching time.
    - V0005: Only phases 0 and 2 can be selected because of timing problems in the chip.*
- 00** = take phase 0, **10** = take phase 2, **01** = inhibit data, **11** = inhibit data

## 4.5 8 Delay Registers for Serial Link Channels

write & read

BB10 0010	CHAN_DELAY0
BB10 0012	CHAN_DELAY1
BB10 0014	CHAN_DELAY2
BB10 0016	CHAN_DELAY3
BB10 0018	CHAN_DELAY4
BB10 001A	CHAN_DELAY5
BB10 001C	CHAN_DELAY6
BB10 001E	CHAN_DELAY7

### 4.5.1 Programming Guideline for DELAYS

15 - 12	11 - 8	7 - 4	3 - 0	
Delay C	Delay B	Delay A	Delay= 0...3	

**Total Delay = Delay C + Delay B + Delay A + (0...3)**

- DELAY =0 → 0000 0000 0000 0000
- DELAY =1 → 0000 0000 0000 0001
- DELAY =2 → 0000 0000 0000 0010
- DELAY =3 → 0000 0000 0000 0011
- DELAY =C+B+A+3 → CCCC BBBB AAAA 0011

**-- For DELAY <4 the bits 15-4 have to be =0 !!**

**-- Bits 3,2 are always =0; are not decoded**

Remark about tests with different delays:

The SRL16 works like a shift register with an output multiplexer that can switch each shift register bit to the output as selected by A3,2,1,0.

If we change from a short to a long delay then it is possible that the shifted signal appears a second time at the output. Therefore we have to wait until the signal has been moved out before applying the new longer delay. However in real life the delay will not be changed during a run.

## 4.6 16 Delay Registers for parallel LVDS data channels

BB10 0020	LVDS_DELAY0	w/r // bit 3-0
BB10 0022	LVDS_DELAY1	w/r // bit 7-4
BB10 0024	LVDS_DELAY2	w/r
BB10 0026	LVDS_DELAY3	w/r
BB10 0028	LVDS_DELAY4	w/r
BB10 002A	LVDS_DELAY5	w/r
BB10 002C	LVDS_DELAY6	w/r
BB10 002E	LVDS_DELAY7	w/r
BB10 0030	LVDS_DELAY8	w/r
BB10 0032	LVDS_DELAY9	w/r
BB10 0034	LVDS_DELAY10	w/r
BB10 0036	LVDS_DELAY11	w/r
BB10 0038	LVDS_DELAY12	w/r
BB10 003A	LVDS_DELAY13	w/r
BB10 003C	LVDS_DELAY14	w/r

BB10 003E LVDS\_DELAY15 w/r // bit 63-60

#### 4.6.1 Programming Guideline for DELAYS

15 - 12	11 - 8	7 - 4	3 - 0	
Delay C	Delay B	Delay A	Delay= 0...3	

**Total Delay = Delay C + Delay B + Delay A + (0...3)**

- DELAY =0 → 0000 0000 0000 0000
- DELAY =1 → 0000 0000 0000 0001
- DELAY =2 → 0000 0000 0000 0010
- DELAY =3 → 0000 0000 0000 0011
- DELAY =C+B+A+3 → CCCC BBBB AAAA 0011

-- For DELAY <4 the bits 15-4 have to be =0 !!

-- Bits 3,2 are always =0; are not decoded

#### 4.7 Board Identifier

BB10 0040 BOARD\_ID **write & read**

16 bit word to identify the PSB board in the data record for CMS readout.

#### 4.8 BCRES Delay

BB10 0042 BCRES\_DELAY **write & read**

--

15 - 12	11 - 8	7 - 4	3 - 0	
Delay C	Delay B	Delay A	Delay= 0...3	

**Total Delay = Delay C + Delay B + Delay A + (0...3)**

- DELAY =0 → 0000 0000 0000 0000
- DELAY =1 → 0000 0000 0000 0001
- DELAY =2 → 0000 0000 0000 0010
- DELAY =3 → 0000 0000 0000 0011
- DELAY =C+B+A+3 → CCCC BBBB AAAA 0011

-- For DELAY <4 the bits 15-4 have to be =0 !!

-- Bits 3,2 are always =0; are not decoded

#### 4.9 Latency Delay

BB10 0044 LATENCY\_DELAY **write & read**

15 - 12	11 - 8	7 - 4	3 - 0	
Delay C	Delay B	Delay A	Delay= 0...3	

**Total Delay = Delay C + Delay B + Delay A + (0...3)**

- DELAY =0 → 0000 0000 0000 0000
- DELAY =1 → 0000 0000 0000 0001
- DELAY =2 → 0000 0000 0000 0010

-- DELAY =3 → 0000 0000 0000 0011  
-- DELAY =C+B+A+3 → CCCC BBBB AAAA 0011

-- For DELAY <4 the bits 15-4 have to be =0 !!  
-- Bits 3,2 are always =0; are not decoded

## 4.10 ROP Setup register

BB10 0046 ROP\_SETUP write & read

Bit 15 – 4 are not used

Bit 3:en\_robust =0 (default)

=1 enable the Bgo commands as the TIM board sends via the ROBUS

=0 the PSB uses the encoded command (L1Res, Bres, L1A) signals sent by the TIM board.

Bit 2: five\_bx\_event =0 (default)

=1: A readout record contains data from 5 bunch crossings around the triggering bx (-2, -1, 0, +1, +2).

=0: A readout record contains data from 3 bunch crossings around the triggering bx (-1, 0, +1)

**Bit 1 and bit 0: PSB\_MODE**

= 0 0 PSB is **DISCONNECTED** from readout (=default)

= 0 1 PSB is **BUSY** with other tasks and cannot receive any L1A for the time being. But the ROP, all counters and registers are correct to continue the data taking run.

= 1 0 PSB is **READY** and waits for the Bgo command ‘RUN’ to receive L1A and to send events to the GTFE board. For tests the ‘RUN’ command can also be simulated by a vme cmd pulse.

= 1 1 PSB sends **BAD CODE**...should never be set except for a test

## 4.11 MAX\_BC\_NUMBER

BB10 0048 MAX\_BC\_NUMBER w/r //=orbit length -1

Default value = 3563 dec = DEB hex

The number is used by a comparator to generate an internal bunch counter reset signal.

If it does not agree with external BCRES signal from the TIM board then a BC\_ERROR flag will be set.

A BC\_ERROR appears always with the first external BCRES and when sending a BCRes\_vme signal. It has to be cleared by the command pulse ‘Res\_BC\_error’.

**Remark: If MAX\_BC\_NUMBER = 0 then no BCRES will be generated inside the chip and the power consumption increases by 1-2 A.**

## 4.12 SEL\_PHASES for LVDS bits 63-00

BB10 004A SEL\_PHASE3100 w/r // select phases for LVDS data  
BB10 004C SEL\_PHASE6332 w/r // select phases for LVDS data

SEL_PHASE3100	15,14	13,12	11,10	9,8	7,6	5,4	3,2	1,0
Selects phases for LVDS bits:	31-28	27-24	23-20	19-16	15-12	11-8	7-4	3-0
SEL_PHASE6332	15,14	13,12	11,10	9,8	7,6	5,4	3,2	1,0

Selects phases for LVDS bits:	63-60	59-56	55-52	51-48	47-44	43-40	39-36	35-32

- 00 → selects phase sample 0
- 01 → selects phase sample 1
- 10 → selects phase sample 2
- 11 → selects phase sample 3

#### 4.13 Idle Identifier low

BB10 004E IDLE\_IDL write & read

IDLE\_IDL(15:0) defines the bits 15-0 that are sent between data records over the Channel Links to the GTFE readout board.

#### 4.14 Idle Identifier high

BB10 0050 IDLE\_IDH write & read

IDLE\_IDH(11:0) defines the bits 27-16 that are sent between data records over the Channel Links to the GTFE readout board.

IDLE\_IDH(15:12) = B"0000" are not used.

### 4.15 TESTPOINTS

BB10 0052	TESTMASK0	w/r	// tespoint 0 bits
BB10 0054	TESTMASK1	w/r	// tespoint 1 bits
BB10 0056	TESTMASK2	w/r	// tespoint 2 bits
BB10 0058	TESTMASK3	w/r	// tespoint 3 bits
BB10 005A	TESTMASK4	w/r	// tespoint 4 bits
BB10 005C	TESTMASK5	w/r	// tespoint 5 bits
BB10 005E	TESTMASK6	w/r	// tespoint 6 bits

TESTMASK0...6 select the signals that should be connected to the test points to be monitored with an oscilloscope. If more than one signal per test point are selected then the signals are merged with an OR-function.

Changed for V0005:

bits	TESTMASK 0	TESTMASK 1	TESTMASK 2	TESTMASK 3
15	Clk40	Clk80	'0'	clr =/locked
14	BCRes_int	bc_error	bcres_dlyed	bcres_dlyed1
13	Res_Evnr	Res_Orbitnr_i	L1Res_int	run_rop
12	Run_next_orbit(0)	en_spy_0	we_spy_0	chout0(15)
11	L1Res_vme	L1A_int	L1A_int	L1A_int
10	psb_status(0)	psb_status(1)	psb_status(2)	psb_status(3)
9	'0'	'0'	vme_wr	vme_en_spy
8	daq_data(24)	daq_data(25)	daq_data(26)	daq_data(27)
7	write_fifo	read_fifo	store_fifo_data	sclr_fifo
6	clr_ring_rdaddr	clr_ring_waddr	'0'	inc_event_nr
5	rop_status(11)	rop_status(12)	rop_status(14)	rop_status(15)
4	rop_status(7)	rop_status(8)	rop_status(9)	rop_status(10)
3	inc_phas4(3)	inc_phas5(3)	inc_lvd0sph(3)	stat_reg0(3)
2	inc_phas4(2)	inc_phas5(2)	inc_lvd0sph(2)	stat_reg0(2)
1	inc_phas4(1)	inc_phas5(1)	inc_lvd0sph(1)	stat_reg0(1)
0	inc_phas4(0)	inc_phas5(0)	inc_lvd0sph(0)	stat_reg0(0)

See ROP\_STATUS bits: 15=roc\_is\_idle, 14=run\_rop, 13=0, 12=out\_of\_sync, 11=error, 10=warning, 9=full\_fifo, 8-0 = empty fifos.

ROP internal signals:

- write\_fifo
- read\_fifo, sclr\_fifo
- store\_fifo\_data
- inc\_event\_nr
- clr\_ring\_rdaddr, clr\_ring\_waddr

bits	TESTMASK 4	TESTMASK 5	TESTMASK6
15	'0'	vme_en	vme_en
14	'0'	dtack	vme_wr
13	'0'	vme_we_spy(0)	vme_rd_spy(0)
12	'0'	rd_chan_reg(0)	wr_chan_reg(0)
11	'0'	rd_chan_delay(0)	wr_chan_delay(0)
10	'0'	rd_lvds_delay(0)	wr_lvds_delay(0)
9	'0'	rd_setup_reg(0)	wr_setup_reg(0)
8	'0'	rd_setup_reg1(0)	wr_setup_reg1(0)
7	'0'	rd_stat_regs(0)	w_cmd_pulse
6	'0'	rd_phase_cntb(0)	rd_phase_cta(0)
5	'0'	rd_phase_a6332(0)	rd_phase_a3100(0)
4	'0'	rd_phase_b6332(0)	rd_phase_b3100(0)
3	'0'	Start_rop_vme	Stop_rop_vme
2	'0'	ResOrbnr_vme	reset_error_flag
1	'0'	ResEvnr_vme	res_bc_error
0	'0'	BCRes_vme	run_next_orbit

## 4.16 Command Pulses

### BB10 0070 PSB\_CMD\_PULSE write only

A data bit =1 generates a spurious pulse to start any action in the PSB chip.

Bit 15: reset\_error\_flag

Bit14: stop_rop_vme	// stop ROP state machine = 'stop run'
Bit13: start_rop_vme	// start ROP state machine making and sending events
Bit12: Res_BC_error	// reset BC error after startup and after BCRes_vme
Bit 11: Res_Evnr_vme	// reset Event Number Counter per software
Bit 10: Res_Orbitnr_vme	// <b>reset Orbit Number Counter per software (not used)</b>
Bit 9: BCRes_vme	// BCRES per software (for test only)
Bit 8: L1Res_vme	// simulate a L1Res (Resync) pulse

// in chip design: 'run_next_orbit(7:0)' = start sim_spy7...0 at next orbit	
Bit 7: start sim_spy7 at next orbit	//Start Sim_Spy memory at begin of next orbit
Bit 6: start sim_spy6 at next orbit	
Bit 5: start sim_spy5 at next orbit	
Bit 4: start sim_spy4 at next orbit	
Bit 3: start sim_spy3 at next orbit	
Bit 2: start sim_spy2 at next orbit	
Bit 1: start sim_spy1 at next orbit	
Bit 0: start sim_spy0 at next orbit	

## 4.17 Phase Counters for Serial data

### read only 32 8bit-counters

BB10 0800	PHASE_CNTR_A0	// compares ph1-ph0 and ph0-pre3 of chann 0
BB10 0802	PHASE_CNTR_A1	// compares ph1-ph0 and ph0-pre3 of chann 1
BB10 0804	PHASE_CNTR_A2	
BB10 0806	PHASE_CNTR_A3	
BB10 0808	PHASE_CNTR_A4	
BB10 080A	PHASE_CNTR_A5	
BB10 080C	PHASE_CNTR_A6	
BB10 080E	PHASE_CNTR_A7	
BB10 0810	PHASE_CNTR_B0	// compares ph3-ph2 and ph2-1 of chann 0
BB10 0812	PHASE_CNTR_B1	// compares ph3-ph2 and ph2-1 of chann 1
BB10 0814	PHASE_CNTR_B2	
BB10 0816	PHASE_CNTR_B3	
BB10 0818	PHASE_CNTR_B4	
BB10 081A	PHASE_CNTR_B5	
BB10 081C	PHASE_CNTR_B6	
BB10 081E	PHASE_CNTR_B7	// compares ph3-ph2 and ph2-1 of chann 7

15 - 8	7 - 0	
Phase Counter 10	Phase Counter 0p3	PHASE_CNTR_Ax
Phase Counter 32	Phase Counter 21	PHASE_CNTR_Bx

x = 0...7 = Channel number

If the incoming data bit switches between two consecutive samples then a 8 bit Phase Counter will be incremented. If a phase counter becomes ‘FF’ then counting stops, showing an overflow. Reading of phase counters also clears their content.

Phase Counter A checks between sample pre3 and 0.

Phase Counter B checks between sample 0 and 1.

Phase Counter C checks between sample 1 and 2.

Phase Counter D checks between sample 2 and 3.

/pre3 = sample 3 of preceding 12.5 ns tick

## 4.18 Phase Counters for parallel LVDS data

### read only 32 words for 64 8bit-counters

BB10 0820	PHASE_CNTR_A0_3	// compares ph1-ph0 and ph0-pre3 of bits 0-3
BB10 0822	PHASE_CNTR_A4_7	// compares ph1-ph0 and ph0-pre3 of bits 4-7
BB10 0824	PHASE_CNTR_A8_11	
BB10 0826	PHASE_CNTR_A12_15	
BB10 0828	PHASE_CNTR_A16_19	
BB10 082A	PHASE_CNTR_A20_23	
BB10 082C	PHASE_CNTR_A24_27	
BB10 082E	PHASE_CNTR_A28_31	
BB10 0830	PHASE_CNTR_A32_35	
BB10 0832	PHASE_CNTR_A36_39	
BB10 0834	PHASE_CNTR_A40_43	
BB10 0836	PHASE_CNTR_A44_47	
BB10 0838	PHASE_CNTR_A48_51	
BB10 083A	PHASE_CNTR_A52_55	
BB10 083C	PHASE_CNTR_A56_59	
BB10 083E	PHASE_CNTR_A60_63	// compares ph1-ph0 and ph0-pre3 of bits 60_63

BB10 0840	PHASE_CNTR_B0_3	// compares ph3-ph2 and ph2-1 of bits 0-3
BB10 0842	PHASE_CNTR_B4_7	// compares ph3-ph2 and ph2-1 of bits 4-7
BB10 0844	PHASE_CNTR_B8_11	
BB10 0846	PHASE_CNTR_B12_15	
BB10 0848	PHASE_CNTR_B16_19	
BB10 084A	PHASE_CNTR_B20_23	
BB10 084C	PHASE_CNTR_B24_27	
BB10 084E	PHASE_CNTR_B28_31	
BB10 0850	PHASE_CNTR_B32_35	
BB10 0852	PHASE_CNTR_B36_39	
BB10 0854	PHASE_CNTR_B40_43	
BB10 0856	PHASE_CNTR_B44_47	
BB10 0858	PHASE_CNTR_B48_51	
BB10 085A	PHASE_CNTR_B52_55	
BB10 085C	PHASE_CNTR_B56_59	
BB10 085E	PHASE_CNTR_B60_63	// compares ph3-ph2 and ph2-1 of bits 60_63

## 4.19 PSB Status register

BB10 0860 PSB\_STATUS **read only**

Bit 15- 5 unused

Bit 4: BC\_error

- =1 if the external BCRES signal and the BC-counter disagree. The length of the orbit is defined by the MAX\_BC\_NUMBER content.
- BC\_error appears always after the initial power-up or DCM(clock) reset, the first external BCRES or after a BCRES\_vme command.
- If BC\_error becomes =1 during normal run then there are serious hardware problems, due to instable electronics.
- It has to be cleared by the **command pulse ‘Res\_BC\_error’** before starting a run.
- The **‘Res\_BC\_error’** pulse has to be sent at least *1 orbit after having loaded a new value* into the MAX\_BC\_NUMBER register.

Bit 3 -0 : encoded 4 bit status sent via FDL to the TCS Trigger Control board.

Bit3 Ready	Bit2 Busy	Bit1 Out_of_Sync	Bit0 Warning	Status of PSB
0	0	0	0	Disconnected
0	0	0	1	Warning
0	0	1	0	Out_of_Sync error
0	0	1	1	----
0	1	0	0	Busy
0	1	0	1	---
0	1	1	0	---
0	1	1	1	---
1	0	0	0	Ready
1	0	0	1	---
1	0	1	0	---
1	0	1	1	---
1	1	0	0	Error (not used by PSB)

1	1	0	1	---
1	1	1	0	---
1	1	1	1	Disconnected

Encoded Status of PSB board

The table agrees with the TCS Note.

## 4.20 ROP Status register

BB10 0862 ROP\_STATUS **read only**

```

Bit 15: roc_is_idle    // The ROC Readout Controller state machine is in idle mode
Bit 14: run_flag        // 1= ROC is running when software sets the
                         // ROP SETUP register = B"....10" = PSB READY=1
                         // 0= either software or Bgo command has stopped
                         // the ROC readout controller to extract and send events
Bit 13: 0
Bit 12: out_of_sync   // empty bits of readout FIFOs did not appear at same time
Bit 11: error          // currently not implemented
Bit 10: warning         // more than 75% of the readout FIFO has been filled
Bit 9: full_fifo       // readout FIFOs are full → error!!
Bit 8: empty(8)         // empty bit of readout FIFO 8 (BC number)
Bit 7: empty(7)         // empty bit of readout FIFO for channel 7
Bit 6: empty(6)
Bit 5: empty(5)
Bit 4: empty(4)
Bit 3: empty(3)
Bit 2: empty(2)
Bit 1: empty(1)
Bit 0: empty(0)         // empty bit of readout FIFO for channel 0

```

## 4.21 CHIP Identifier

BB10 0864 CHIP\_ID **read only**

The 16 bit identifier is defined in the VHDL code for the PSB chip and cannot be changed by software.

**CHIPID = 8131** 8= PSB board, 1=cardnr, 3 = PSB chip, 1=chipnr (only one psb chip per board)

## 4.22 Version Number

BB10 0866 VERSION\_NR **read only**

The 16 bit identifier is defined in the VHDL code for the PSB chip and cannot be changed by software.

**VERSION\_NR = 0001**...and higher

## 4.23 CHIP Identifier H

BB10 0868 CHIP\_IDH **read only**

The 16 bit identifier is defined in the VHDL code for the PSB chip and cannot be changed by software.

**CHIPIDH = 0001** 1= Global Trigger crate

# 5 PSB logic functions

## 5.1 Data Format of Channel Link

The table is defined for 5 bx per event. For normal events the record contains the parts for bx-1, bx+0, bx+1 only.

Normal record length=24 x 3 +1 = 73

Debug record length = 24 x 5 +1 = 121

Transfer time: 73 x 25 ns = 1800 ns resp. 121x 25= 3025 ns per event for 40 MHz Channel Link.

27-24	23-20	19-16	15-12	11-8	7-4	3-0	Name	Comment	Example
I	I	I	I	I	I	I	IDLE	Between records	555AAAAA
A	0	0	e	e	e	e	HEADER A	EVNr(15:0)	A000001
B	0	0	0	0	e	e	HEADER B	EVNr(23:16)	0000000
C	0	0	bx-2	b	b	b	HEADER C	Bx_in_ev/bx of fifo	C00E017
D	0	0	n	n	n	n	HEADER D	Board identifier	D00ABCD
1	0	0	d	d	d	d	A_data ch0 of bx-2		
1	0	0	d	d	d	d	A_data ch1 of bx-2		
1	0	0	d	d	d	d	A_data ch2 of bx-2		
1	0	0	d	d	d	d	A_data ch3 of bx-2		
1	0	0	d	d	d	d	A_data ch4 of bx-2		
1	0	0	d	d	d	d	A_data ch5 of bx-2		
1	0	0	d	d	d	d	A_data ch6 of bx-2		
1	0	0	d	d	d	d	A_data ch7 of bx-2		
1	0	0	d	d	d	d	B_data ch0 of bx-2		
1	0	0	d	d	d	d	B_data ch1 of bx-2		
1	0	0	d	d	d	d	B_data ch2 of bx-2		
1	0	0	d	d	d	d	B_data ch3 of bx-2		
1	0	0	d	d	d	d	B_data ch4 of bx-2		
1	0	0	d	d	d	d	B_data ch5 of bx-2		
1	0	0	d	d	d	d	B_data ch6 of bx-2		
1	0	0	d	d	d	d	B_data ch7 of bx-2		
E	0	0	000b	b	b	b	End of bx-2	Ring addr of B_data	E000018
E	0	0	0	0	0	0	End of bx-2		E000000
E	0	0	0	0	0	0	End of bx-2		E000000
E	0	0	0	0	0	0	End of bx-2		E000000
A	0	0	e	e	e	e	HEADER A	EVNr(15:0)	A000001
B	0	0	0	0	e	e	HEADER B	EVNr(23:16)	0000000
C	0	0	bx-1	b	b	b	HEADER C	Bx_in_ev/bx of fifo	C00F019
D	0	0	n	n	n	n	HEADER D	Board identifier	D00ABCD
1	0	0	d	d	d	d	A_data ch0 of bx-1		
1	0	0	d	d	d	d	A_data ch1 of bx-1		
1	0	0	d	d	d	d	A_data ch2 of bx-1		
1	0	0	d	d	d	d	A_data ch3 of bx-1		
1	0	0	d	d	d	d	A_data ch4 of bx-1		
1	0	0	d	d	d	d	A_data ch5 of bx-1		
1	0	0	d	d	d	d	A_data ch6 of bx-1		
1	0	0	d	d	d	d	A_data ch7 of bx-1		
1	0	0	d	d	d	d	B_data ch0 of bx-1		
1	0	0	d	d	d	d	B_data ch1 of bx-1		
1	0	0	d	d	d	d	B_data ch2 of bx-1		
1	0	0	d	d	d	d	B_data ch3 of bx-1		
1	0	0	d	d	d	d	B_data ch4 of bx-1		
1	0	0	d	d	d	d	B_data ch5 of bx-1		
1	0	0	d	d	d	d	B_data ch6 of bx-1		
1	0	0	d	d	d	d	B_data ch7 of bx-1		
E	0	0	000b	b	b	b	End of bx-1	Ring addr of B_data	E00001A
E	0	0	0	0	0	0	End of bx-1		E000000
E	0	0	0	0	0	0	End of bx-1		E000000
E	0	0	0	0	0	0	End of bx-1		E000000
A	0	0	e	e	e	e	HEADER A	EVNr(15:0)	A000001
B	0	0	0	0	e	e	HEADER B	EVNr(23:16)	0000000

C	0	0	bx+0	b	b	b	HEADER C	Bx_in_ev/bx of fifo	C00001B
D	0	0	n	n	n	n	HEADER D	Board identifier	D00ABCD
1	0	0	d	d	d	d	A_data ch0 of bx+0		
1	0	0	d	d	d	d	A_data ch1 of bx+0		
1	0	0	d	d	d	d	A_data ch2 of bx+0		
1	0	0	d	d	d	d	A_data ch3 of bx+0		
1	0	0	d	d	d	d	A_data ch4 of bx+0		
1	0	0	d	d	d	d	A_data ch5 of bx+0		
1	0	0	d	d	d	d	A_data ch6 of bx+0		
1	0	0	d	d	d	d	A_data ch7 of bx+0		
E	0	0	000b	b	b	b	End of bx	Ring addr of B_data	E00001C
E	0	0	0	0	0	0	End of bx		E000000
E	0	0	0	0	0	0	End of bx		E000000
E	0	0	0	0	0	0	End of bx		E000000
A	0	0	e	e	e	e	HEADER A	EVNr(15:0)	A000001
B	0	0	0	0	e	e	HEADER B	EVNr(23:16)	0000000
C	0	0	bx+1	b	b	b	HEADER C	Bx_in_ev/bx of fifo	C00101D
D	0	0	n	n	n	n	HEADER D	Board identifier	D00ABCD
1	0	0	d	d	d	d	A_data ch0 of bx+1		
1	0	0	d	d	d	d	A_data ch1 of bx+1		
1	0	0	d	d	d	d	A_data ch2 of bx+1		
1	0	0	d	d	d	d	A_data ch3 of bx+1		
1	0	0	d	d	d	d	A_data ch4 of bx+1		
1	0	0	d	d	d	d	A_data ch5 of bx+1		
1	0	0	d	d	d	d	A_data ch6 of bx+1		
1	0	0	d	d	d	d	A_data ch7 of bx+1		
1	0	0	d	d	d	d	B_data ch0 of bx+1		
1	0	0	d	d	d	d	B_data ch1 of bx+1		
1	0	0	d	d	d	d	B_data ch2 of bx+1		
1	0	0	d	d	d	d	B_data ch3 of bx+1		
1	0	0	d	d	d	d	B_data ch4 of bx+1		
1	0	0	d	d	d	d	B_data ch5 of bx+1		
1	0	0	d	d	d	d	B_data ch6 of bx+1		
1	0	0	d	d	d	d	B_data ch7 of bx+1		
E	0	0	000b	b	b	b	End of bx+1	Ring addr of B_data	E00001E
E	0	0	0	0	0	0	End of bx+1		E000000
E	0	0	0	0	0	0	End of bx+1		E000000
E	0	0	0	0	0	0	End of bx+1		E000000
A	0	0	e	e	e	e	HEADER A	EVNr(15:0)	A000001
B	0	0	0	0	e	e	HEADER B	EVNr(23:16)	0000000
C	0	0	bx+2	b	b	b	HEADER C	Bx_in_ev/bx of fifo	C00201F
D	0	0	n	n	n	n	HEADER D	Board identifier	D00ABCD
1	0	0	d	d	d	d	A_data ch0 of bx+2		
1	0	0	d	d	d	d	A_data ch1 of bx+2		
1	0	0	d	d	d	d	A_data ch2 of bx+2		
1	0	0	d	d	d	d	A_data ch3 of bx+2		
1	0	0	d	d	d	d	A_data ch4 of bx+2		
1	0	0	d	d	d	d	A_data ch5 of bx+2		
1	0	0	d	d	d	d	A_data ch6 of bx+2		
1	0	0	d	d	d	d	A_data ch7 of bx+2		
1	0	0	d	d	d	d	B_data ch0 of bx+2		

1	0	0	d	d	d	d	B data ch1 of bx+2		
1	0	0	d	d	d	d	B data ch2 of bx+2		
1	0	0	d	d	d	d	B data ch3 of bx+2		
1	0	0	d	d	d	d	B data ch4 of bx+2		
1	0	0	d	d	d	d	B data ch5 of bx+2		
1	0	0	d	d	d	d	B data ch6 of bx+2		
1	0	0	d	d	d	d	B data ch7 of bx+2		
E	0	0	000b	b	b	b	End of bx+2	Ring addr of B data	E000020
E	0	0	0	0	0	0	End of bx+2		E000000
E	0	0	0	0	0	0	End of bx+2		E000000
E	0	0	0	0	0	0	End of bx+2		E000000
F	F	F	F	F	F	F	END of RECORD		FFFFFFF
I	I	I	I	I	I	I	IDLE	Between records	555AAAAA

## 5.2 RESET LOGIC

### L1Res:

- **Clears FIFOs** (derandomizing buffers)  
L1Res either from backplane or from VME clears the FIFO content so that the ROC Readout Controller stays in IDLE mode after having finished the current event.

## 5.3 ROP logic

- ROC State Machine cannot be reset, it returns always to IDLE state. ROC starts only when FIFO is not empty and PSB is READY.

TTCrx receives BGo commands and sends them via the ROBUS to the boards.

Bit #	Signal name	Internal action when high	Coarse delay value 1=bits<3:0> 2=bits<7:4>	Output synchronised with 1: Clock40Des1 2: Clock40Des2	Output pin name
0	Bunch counter reset	Resets internal bunch counter	1	1	BcntRes
1	Event counter reset	Resets internal event counter	1	1	EvCntRes
<5:2>	System message	-	1	1	Brcst<5:2>
<7:6>	User message	-	2	1 or 2	Brcst <7:6>

## TIM CHIP V1004, V1005 from July 2004

The TIM board sends via the RO bus to all boards

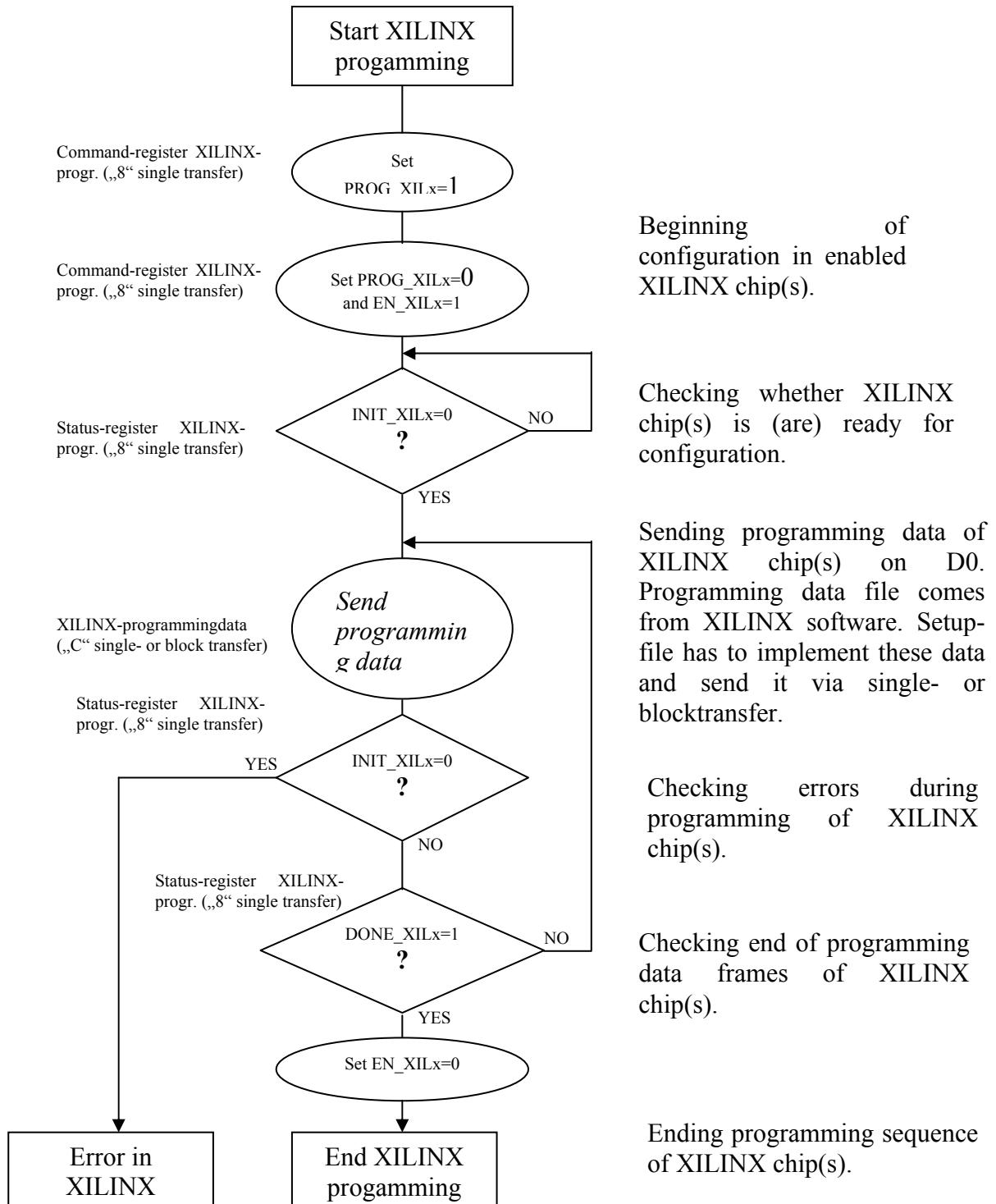
- BGo commands from TTCrx or VME on TIM
- Monitoring Request Identifier
- Test data that where loaded into the TIM register.

ROBUS	BGO cmd	Monitoring	Tests	
RDRQST	1	1	1	OR_STROBES
STROBE 2	0	0	1	TEST_STROBE
STROBE 1	0	1	0	MON_RQST_STROBE
STROBE 0	1	0	0	BGO_CMD_STROBE
BX 11	USER_MSG3	MON_RQST_ID 11	TEST 11	
BX 10	USER_MSG2	MON_RQST_ID 10	TEST 10	
BX 9	USER_MSG1	MON_RQST_ID 9	TEST 9	

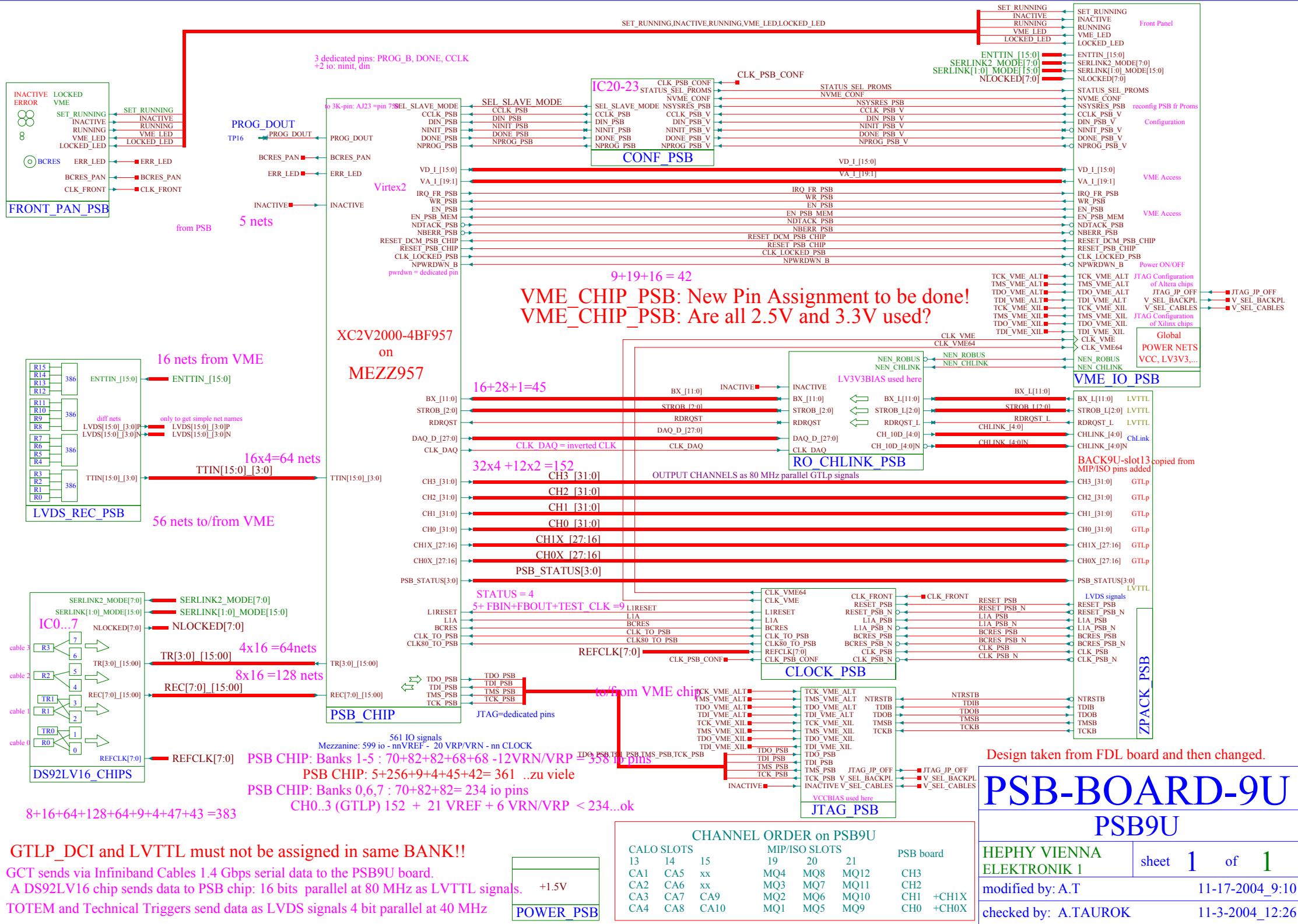
BX 8	USER_MSG0	MON_RQST_ID 8	TEST 8	
BX 7	0	MON_RQST_ID 7	TEST 7	
BX 6	STOP_RUN	MON_RQST_ID 6	TEST 6	
BX 5	START_RUN	MON_RQST_ID 5	TEST 5	
BX 4	RES_ORBITNR	MON_RQST_ID 4	TEST 4	
BX 3	HARD_RES	MON_RQST_ID 3	TEST 3	
BX 2	PRIVATE_ORBIT	MON_RQST_ID 2	TEST 2	
BX 1	PRIVATE_GAP	MON_RQST_ID 1	TEST 1	
BX 0	TEST_ENABLE	MON_RQST_ID 0	TEST 0	

## 6 Flowchart of XILINX-programming

The XILINX chips on PSB-card are programmed via VME-instructions, this programming sequence has to happen every time after power up. There is no PROM on board for power-up-programming! The following instructions should be implemented in the control software.

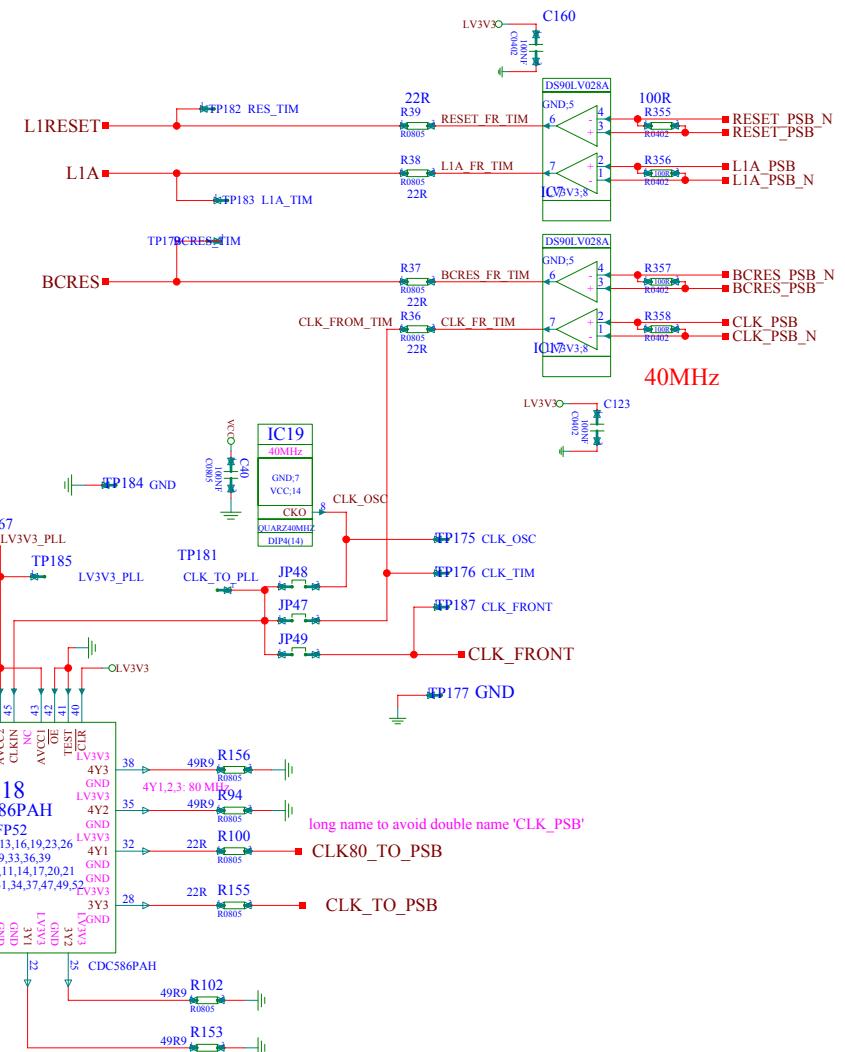
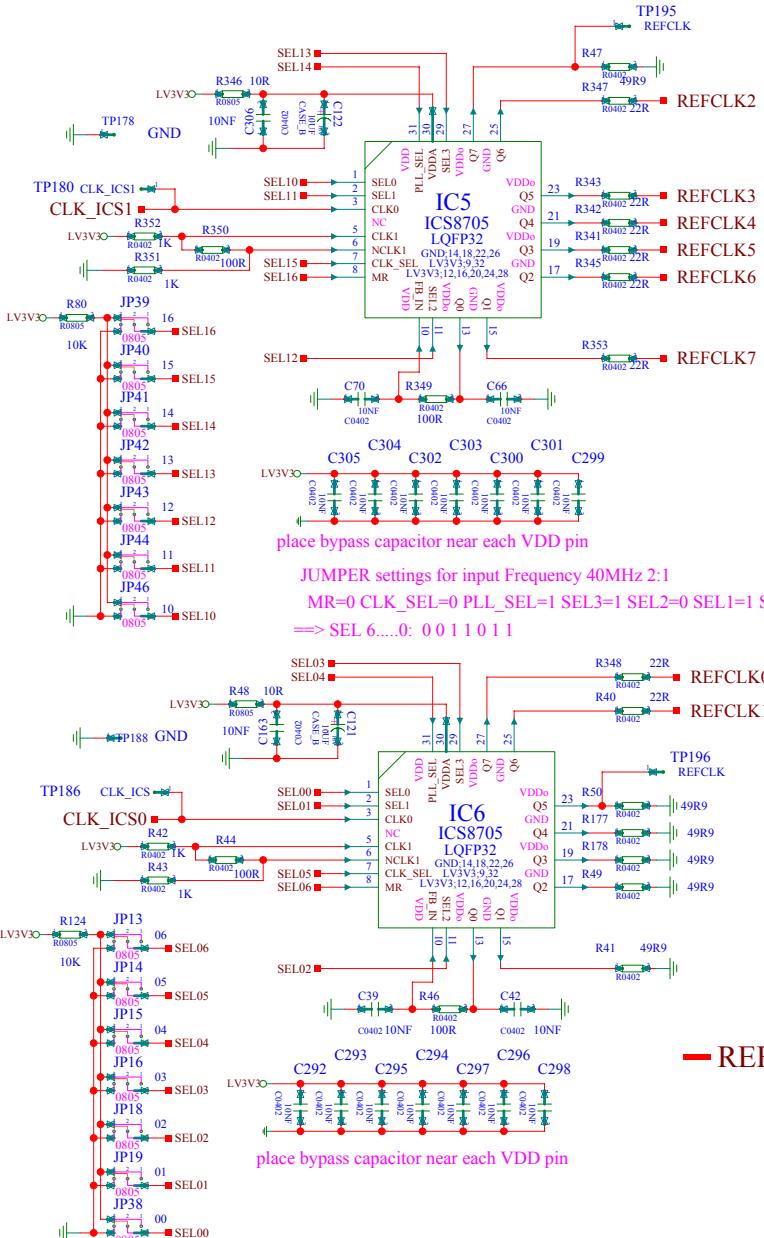


After the XILINX programming sequence all other VME-accesses on card are possible, e. g. DPM-access or FIFO-access in XILINX chips and so on.



Optionally the ECL signals L1A\_X and CLK\_X might be used  
Frontpanel ECL signals  
LVDS signals from TIM card via Backplane

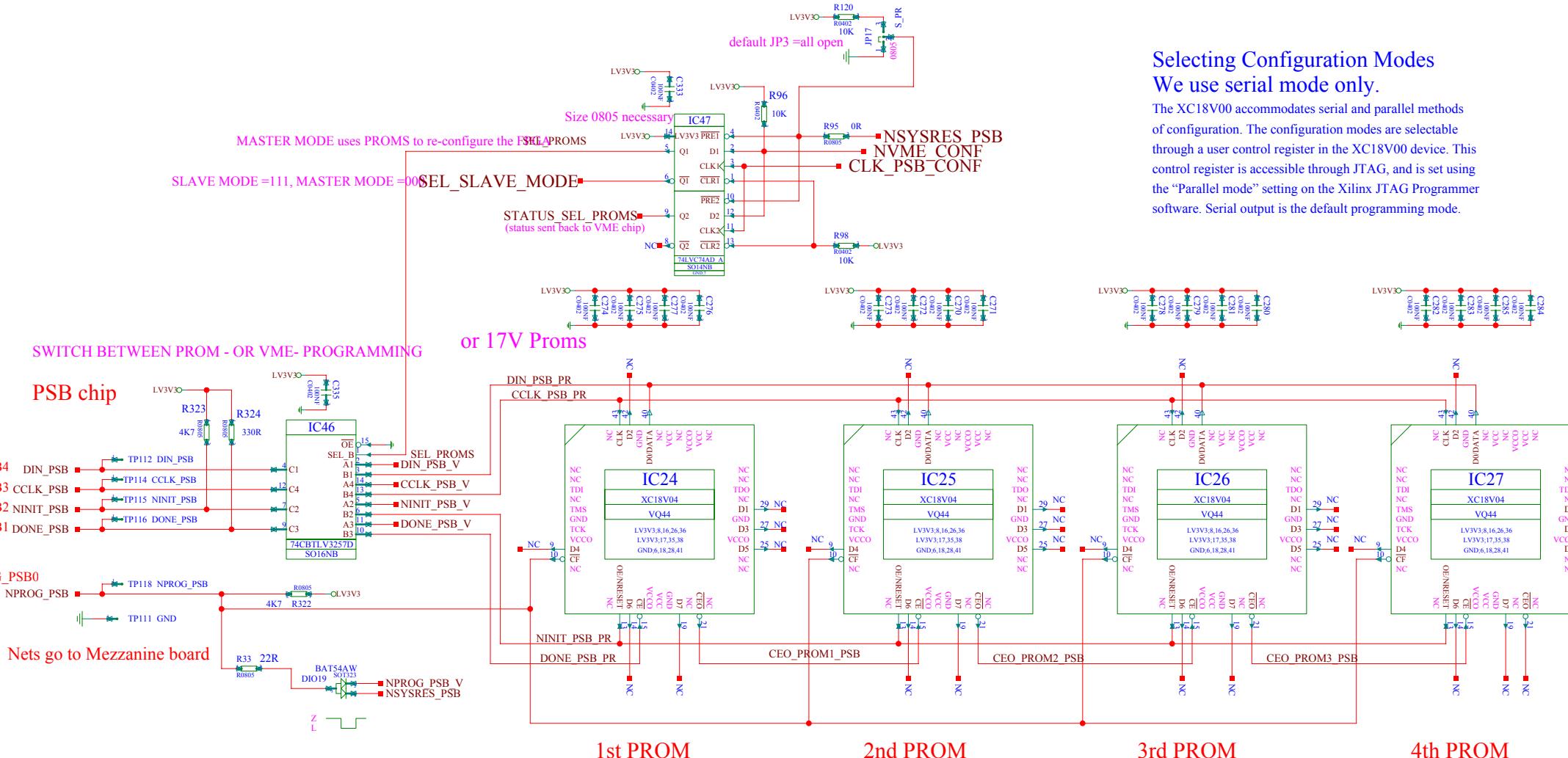
JUMPER settings for input Frequency 40MHz 2:1  
MR=0 CLK\_SEL=0 PLL\_SEL=1 SEL3=1 SEL2=0 SEL1=1 SEL0=1  
=> SEL 16....10: 0 0 1 1 0 1 1



## Selecting Configuration Modes

We use serial mode only.

The XC18V00 accommodates serial and parallel methods of configuration. The configuration modes are selectable through a user control register in the XC18V00 device. This control register is accessible through JTAG, and is set using the "Parallel mode" setting on the Xilinx JTAG Programmer software. Serial output is the default programming mode.



See PSB\_CHIP schematic to find:

HSWAP\_EN\_PSB  
NPWRDWN\_B  
DOUT\_PSB

On Mezzanine board for PSB you find: M0,M1,M2

CLK: IN

/CF: OUT: OPEN DRAIN

/CF: Allows JTAG CONFIG instruction to initiate FPGA configuration without powering down FPGA. This is an open-drain output that is pulsed Low by the JTAG CONFIG command.

OE/RESET: BIDIR and OPEN DRAIN

OE/RESET: When Low, this input holds the address counter reset and the DATA output is in a Low while the PROM is reset. Polarity is NOT programmable.

high-impedance state. This is a bidirectional open-drain pin that is held

/CE: IN

/CE: When CE is High, the device is put into low-power standby mode, the address counter is reset, and the DATA pins are put in a high-impedance state.

/CEO: OUT

/CEO Chip Enable Output (CEO) is connected to the CE input of the next PROM in the chain. This output is Low when CE is Low and OE/RESET input is High, AND the internal address counter has been incremented beyond its Terminal Count (TC) value. CEO returns to High when OE/RESET goes Low or CE goes High.

JTAG pins of PROMs : See JTAG circuits

**PSB-CARD-9U**

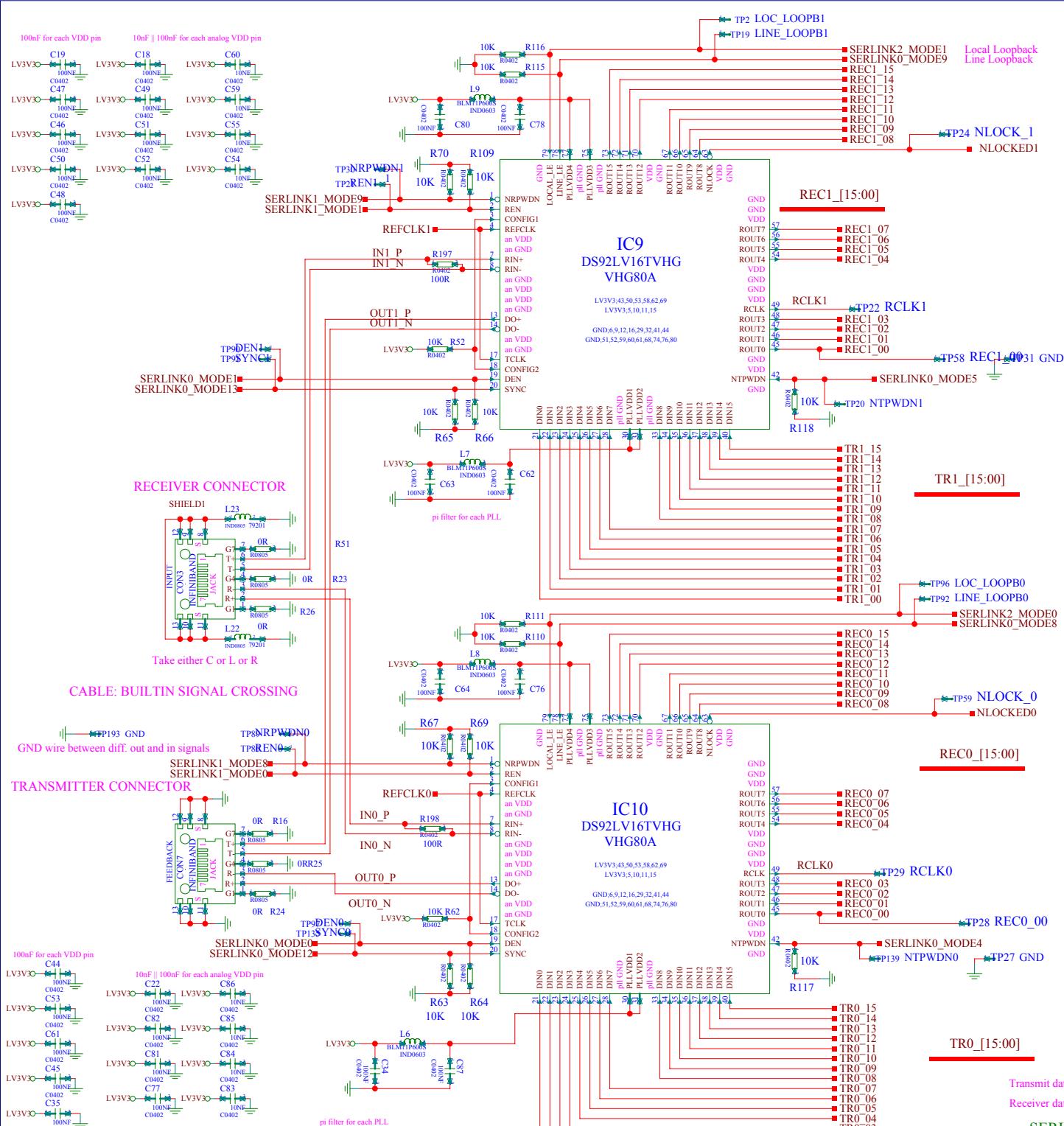
**CONF\_PS\_B**

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 1

modified by: A.TAUROK 11-11-2004\_18:49

checked by: A.TAUROK 11-11-2004\_18:47



**SERLINK2**

- Bit 7: LOCAL\_LOOPBACK7
- Bit 6: LOCAL\_LOOPBACK6
- Bit 5: LOCAL\_LOOPBACK5
- Bit 4: LOCAL\_LOOPBACK4
- Bit 3: LOCAL\_LOOPBACK3
- Bit 2: LOCAL\_LOOPBACK2
- Bit 1: LOCAL\_LOOPBACK1
- Bit 0: LOCAL\_LOOPBACK0

**SERLINK1**

- Bit 15: NRPWRDWN7
- Bit 14: NRPWRDWN6
- Bit 13: NRPWRDWNS
- Bit 12: NRPWRDWN4
- Bit 11: NRPWRDWN3
- Bit 10: NRPWRDWN2
- Bit 9: NRPWRDWN1
- Bit 8: NRPWRDW0
- Bit 7: ENREC7
- Bit 6: ENREC6
- Bit 5: ENREC5
- Bit 4: ENREC4
- Bit 3: ENREC3
- Bit 2: ENREC2
- Bit 1: ENREC1
- Bit 0: ENRECO

**SERLINK0**

- Bit 15: SEND\_SYNC\_PATTERN3
- Bit 14: SEND\_SYNC\_PATTERN2
- Bit 13: SEND\_SYNC\_PATTERN1
- Bit 12: SEND\_SYNC\_PATTERN0
- Bit 11: LINE\_LOOPBACK3
- Bit 10: LINE\_LOOPBACK2
- Bit 9: LINE\_LOOPBACK1
- Bit 8: LINE\_LOOPBACK0
- Bit 7: NTPWRDWN3
- Bit 6: NTPWRDWN2
- Bit 5: NTPWRDWN1
- Bit 4: NTPWRDWN0
- Bit 3: ENTR3
- Bit 2: ENTR2
- Bit 1: ENTR1
- Bit 0: ENTR0

**PULL DOWN/UP RESISTORS: Default values for register:**

TPWDN* <sup>0</sup> ==> pull down	TPWDN* <sup>0</sup> ==> default
RPWDN* <sup>0</sup> ==> pull down	RPWDN* <sup>1</sup> ==> default
REN=0 ==> pull down	REN=1 ==> default
DEN=0 ==> pull down	DEN=1 ==> default
SYNC=0 ==> pull down	SYNC=0 ==> default
LINE LE=0 ==> pull down	LINE LE=0 ==> default
LOCAL LE=0 ==> pull down	LOCAL LE=0 ==> default
CONFIG1 and 2 = 1 ==> pull high	

/LOCK=0 ==> Rec-PLL is locked  
 TPWDN\*<sup>0</sup> ==> Serializer enter power down mode: Ser PLL stops, outputs into 3-state  
 RPWDN\*<sup>0</sup> ==> Deserializer enter power down mode: PLL stops, outputs 3-state  
 REN=0 ==> Serializer outputs ROUT[15:0] into tri-state; Rec-PLL remains locked.  
 DEN=0 ==> Serializer LVDS outputs into tri-state; Trans-PLL remains locked.  
 SYNC=1 ==> Transm. sends SYNC pattern.  
 LINE LE=1 ==> Line Loopback: serial RIN+/ back to serial DO+/-  
 LOCAL LE=1 ==> Local Loopback: DIN[...] back to ROUT[...]  
 CONFIG1 and 2 = 1 ==> reserved; pull to high level

# PSB-9U-CARD

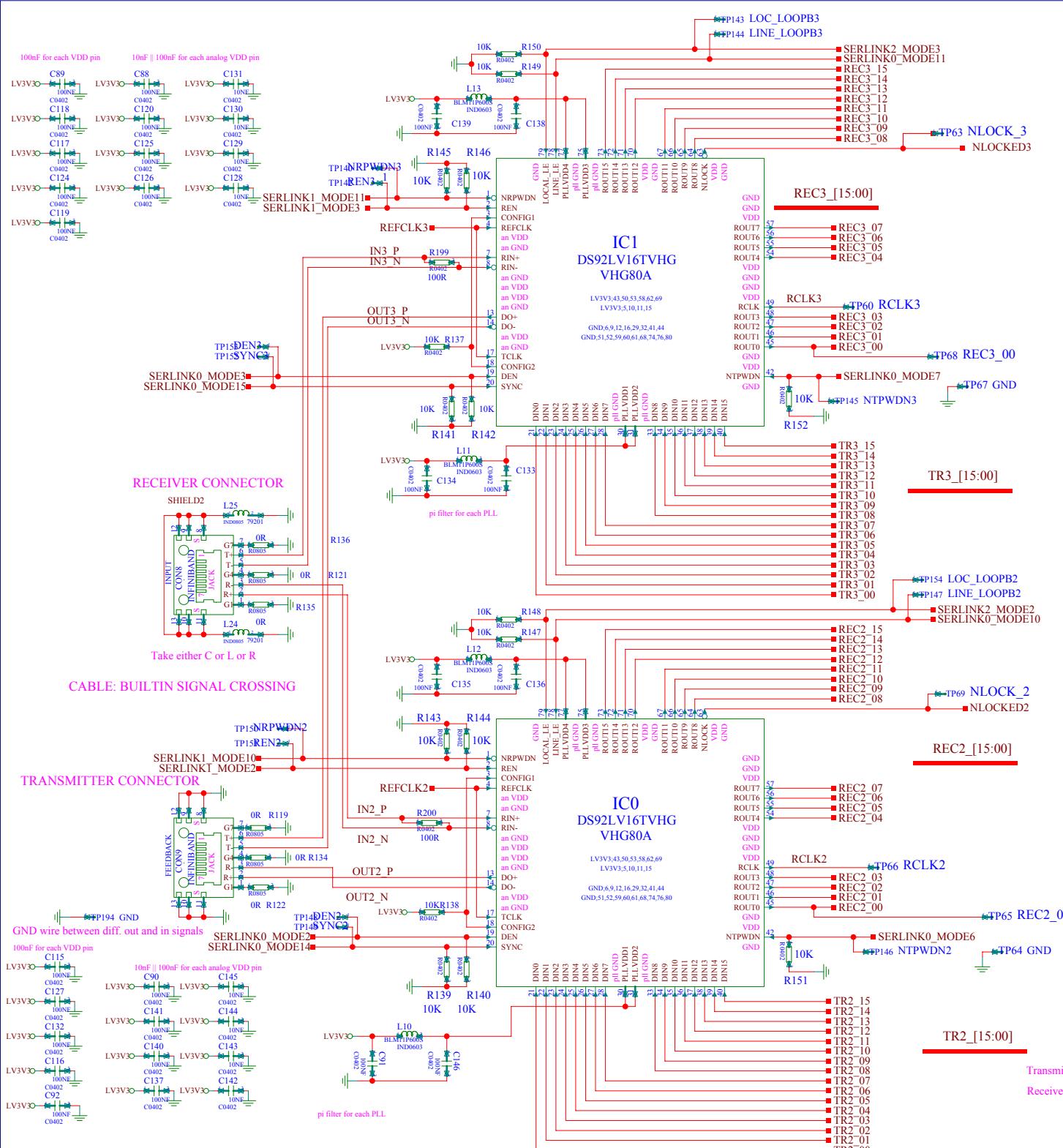
## DS92LV16\_CHIPS

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 4

modified by: AT, JULY 04 11-17-2004\_9:11

checked by: AT 121104



**SERLINK2**

- Bit 7: LOCAL\_LOOPBACK7
- Bit 6: LOCAL\_LOOPBACK6
- Bit 5: LOCAL\_LOOPBACK5
- Bit 4: LOCAL\_LOOPBACK4
- Bit 3: LOCAL\_LOOPBACK3
- Bit 2: LOCAL\_LOOPBACK2
- Bit 1: LOCAL\_LOOPBACK1
- Bit 0: LOCAL\_LOOPBACK0

**SERLINK1**

- Bit 15: NRPWRDN7
- Bit 14: NRPWRDN6
- Bit 13: NRPWRDN5
- Bit 12: NRPWRDN4
- Bit 11: NRPWRDN3
- Bit 10: NRPWRDN2
- Bit 9: NRPWRDN1
- Bit 8: NRPWRDN0
- Bit 7: ENREC7
- Bit 6: ENREC6
- Bit 5: ENREC5
- Bit 4: ENREC4
- Bit 3: ENREC3
- Bit 2: ENREC2
- Bit 1: ENREC1
- Bit 0: ENREC0

**SERLINK0**

- Bit 15: SEND\_SYNC\_PATTERN3
- Bit 14: SEND\_SYNC\_PATTERN2
- Bit 13: SEND\_SYNC\_PATTERN1
- Bit 12: SEND\_SYNC\_PATTERN0
- Bit 11: LINE\_LOOPBACK3
- Bit 10: LINE\_LOOPBACK2
- Bit 9: LINE\_LOOPBACK1
- Bit 8: LINE\_LOOPBACK0
- Bit 7: NTPWRDN3
- Bit 6: NTPWRDN2
- Bit 5: NTPWRDN1
- Bit 4: NTPWRDN0
- Bit 3: ENTR3
- Bit 2: ENTR2
- Bit 1: ENTR1
- Bit 0: ENTR0

**PULL DOWN/UP RESISTORS: Default values for register:**

TPWDN*=0 => pull down	TPWDN*=0 default
RPWDN*=0 => pull down	RPWDN*=1 default
REN=0 => pull down	REN=1 default
DEN=0 => pull down	DEN=0 default
SYNC=1 => pull down	SYNC=0 default
LINE_LE=1 => pull down	LINE_LE=0 default
LOCAL_LE=1 => pull down	LOCAL_LE=0 default
CONFIG1 and 2 = 1 => pull high	

/LOCK=0 => Rec-PLL is locked  
 TPWDN\*=0 => Serializer enter power down mode: Ser.PLL stops, outputs into 3-state  
 RPWDN\*=0 => Deserializer enter power down mode: PLL stops, outputs=3-state  
 REN=0 => Deserializer outputs ROUT[15:0] into tri-state; Rec-PLL remains locked.  
 DEN=0 => Serializer LVDS outputs into tri-state; Trans-PLL remains locked.  
 SYNC=1 => Transm. sends SYNC pattern.  
 LINE\_LE=1 => Line Loopback: serial RIN+/ back to serial DO+/  
 LOCAL\_LE=1 => Local Loopback: DIN[...] back to ROUT[...]  
 CONFIG1 and 2 = 1 => reserved; pull to high level

# PSB-9U-CARD

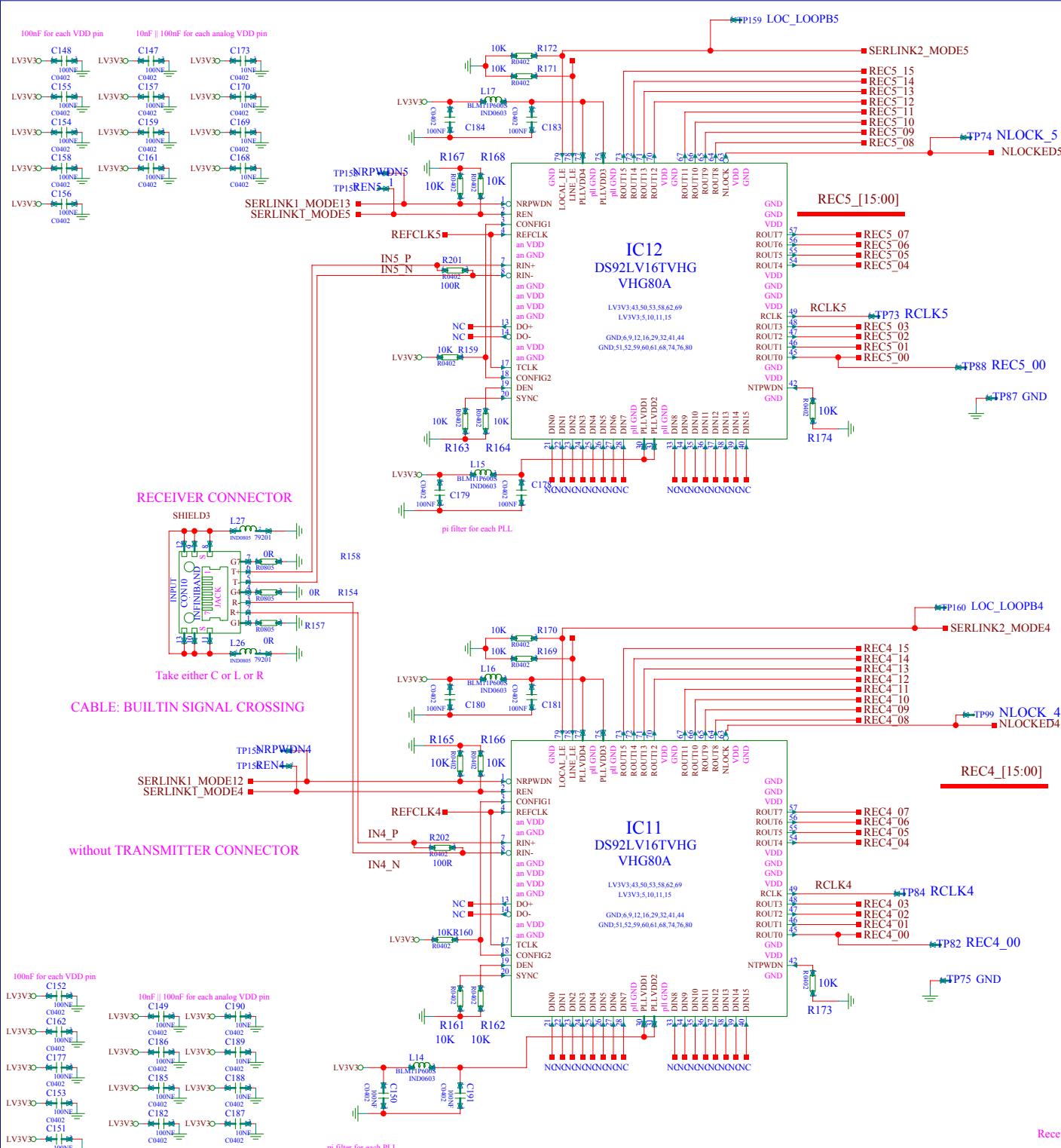
## DS92LV16\_CHIPS

HEPHY VIENNA  
ELEKTRONIK 1

sheet 2 of 4

modified by: AT, JULY 04 11-16-2004\_18:52

checked by: AT 121104



SERLINK0	
Bit 15:	SEND_SYNC_PATTERN3
Bit 14:	SEND_SYNC_PATTERN2
Bit 13:	SEND_SYNC_PATTERN1
Bit 12:	SEND_SYNC_PATTERN0
Bit 11:	LINE_LOOPBACK3
Bit 10:	LINE_LOOPBACK2
Bit 9:	LINE_LOOPBACK1
Bit 8:	LINE_LOOPBACK0
Bit 7:	NTPWRDWN3
Bit 6:	NTPWRDWN2
Bit 5:	NTPWRDWN1
Bit 4:	NTPWRDWN0
Bit 3:	ENTR3
Bit 2:	ENTR2
Bit 1:	ENTR1
Bit 0:	ENTR0

SERLINK2	
Bit 7:	LOCAL_LOOPBACK7
Bit 6:	LOCAL_LOOPBACK6
Bit 5:	LOCAL_LOOPBACK5
Bit 4:	LOCAL_LOOPBACK4
Bit 3:	LOCAL_LOOPBACK3
Bit 2:	LOCAL_LOOPBACK2
Bit 1:	LOCAL_LOOPBACK1
Bit 0:	LOCAL_LOOPBACK0

SERLINK1	
Bit 15:	NRPWRDWN7
Bit 14:	NRPWRDWN6
Bit 13:	NRPWRDWN5
Bit 12:	NRPWRDWN4
Bit 11:	NRPWRDWN3
Bit 10:	NRPWRDWN2
Bit 9:	NRPWRDWN1
Bit 8:	NRPWRDWN0
Bit 7:	ENREC7
Bit 6:	ENREC6
Bit 5:	ENREC5
Bit 4:	ENREC4
Bit 3:	ENREC3
Bit 2:	ENREC2
Bit 1:	ENREC1
Bit 0:	ENREC0

PULL DOWN/UP RESISTORS: Default values for register:

TPWDN*0 ==> pull down	TPWDN*0 ==> default
RPWDN*0 ==> pull down	RPWDN*1 ==> default
REN=0 ==> pull down	REN=1 ==> default
DEN=0 ==> pull down	DEN=0 ==> default
SYNC=0 ==> pull down	SYNC=0 ==> default
LINE_LE=0 ==> pull down	LINE_LE=0 ==> default
LOCAL_LE=0 ==> pull down	LOCAL_LE=0 ==> default
CONFIG1 and 2 =1 ==> pull high	

/LOCK=0 ==> Rec-PLL is locked  
 TPWDN\*0 ==> Serializer enter power down mode: Ser.PLL stops, outputs into 3-state  
 RPWDN\*0 ==> Deserializer enter power down mode: PLL stops, outputs=3-state  
 REN=0 ==> Serializer outputs ROUT[15:0] into tri-state; Rec-PLL remains locked.  
 DEN=0 ==> Serializer LVDS outputs into tri-state; Transm-PLL remains locked.  
 SYNC=1 ==> Transm. sends SYNC pattern.  
 LINE\_LE=1 ==> Line Loopback: serial RIN+/- back to serial DO+/-  
 LOCAL\_LE=1 ==> Local Loopback: DIN[...] back to ROUT[...]  
 CONFIG1 and 2 =1 ==> reserved; pull to high level

Receiver data  
 REC[7:0]\_[15:00]  
 REFCLK[7:0]  
 NLOCKED[7:0]

HEPHY VIENNA  
ELEKTRONIK 1

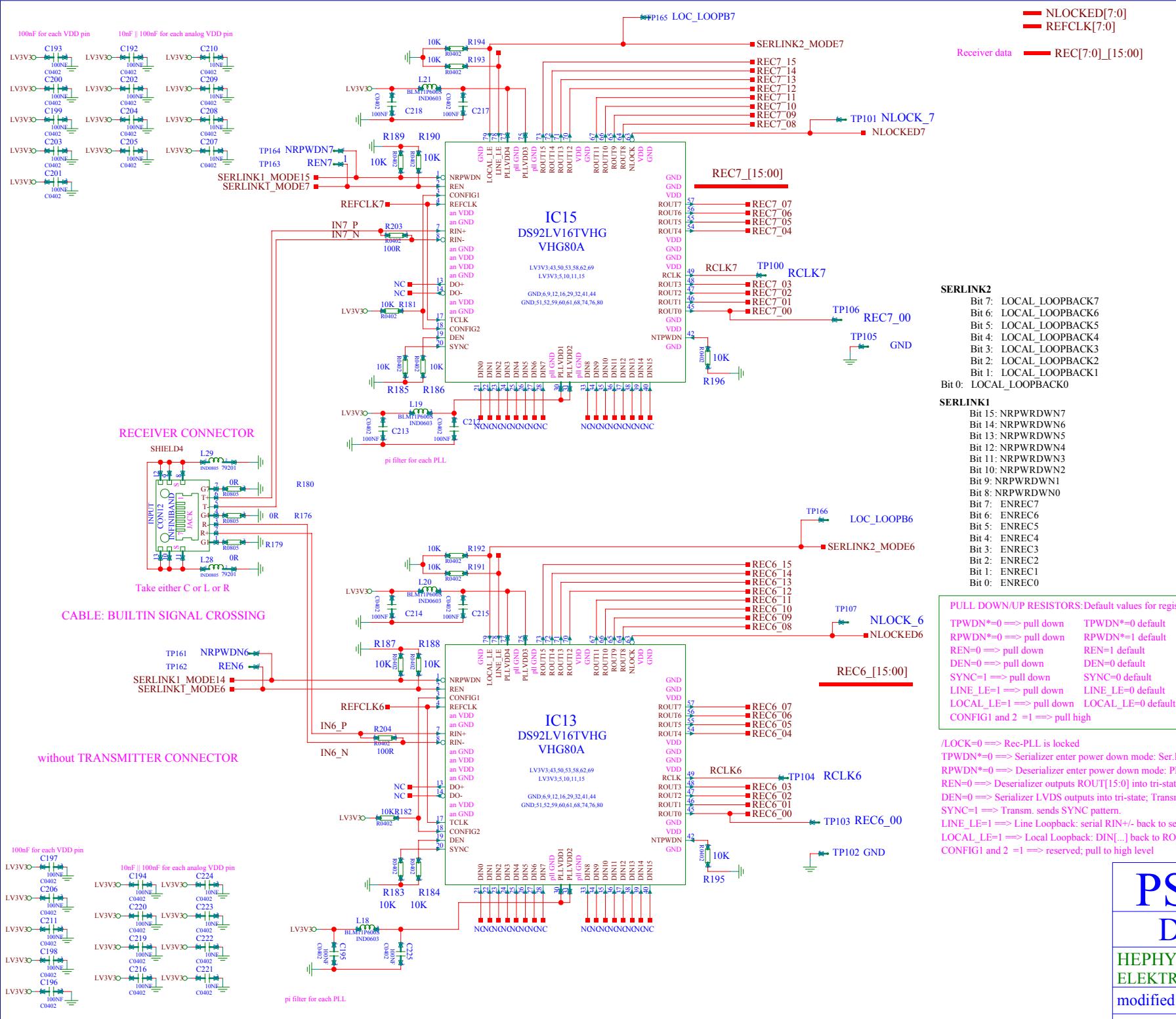
sheet 3 of 4

modified by: AT, JULY 04

11-16-2004\_18:52

checked by: AT

121104



# PSB-9U-CARD

## DS92LV16\_CHIPS

HEPHY VIENNA  
ELEKTRONIK 1

sheet 4 of 4

modified by: AT, JULY 04 11-16-2004\_18:52

checked by: AT 121104

<b>SERLINK2</b>
Bit 7: LOCAL_LOOPBACK7
Bit 6: LOCAL_LOOPBACK6
Bit 5: LOCAL_LOOPBACK5
Bit 4: LOCAL_LOOPBACK4
Bit 3: LOCAL_LOOPBACK3
Bit 2: LOCAL_LOOPBACK2
Bit 1: LOCAL_LOOPBACK1
Bit 0: LOCAL_LOOPBACK0
<b>SERLINK1</b>
Bit 15: NRPWRDWN7
Bit 14: NRPWRDWN6
Bit 13: NRPWRDWN5
Bit 12: NRPWRDWN4
Bit 11: NRPWRDWN3
Bit 10: NRPWRDWN2
Bit 9: NRPWRDWN1
Bit 8: NRPWRDWN0
Bit 7: ENREC7
Bit 6: ENREC6
Bit 5: ENREC5
Bit 4: ENREC4
Bit 3: ENREC3
Bit 2: ENREC2
Bit 1: ENREC1
Bit 0: ENREC0

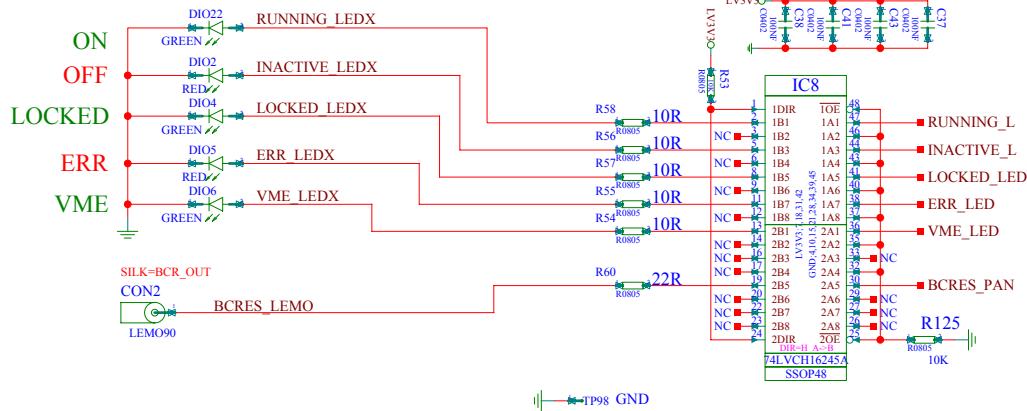
PULL DOWN/UP RESISTORS: Default values for register:  
TPWDN\*=0 => pull down      TPWDN\*=0 default  
RPWDN\*=0 => pull down      RPWDN\*=1 default  
REN=0 => pull down      REN=1 default  
DEN=0 => pull down      DEN=0 default  
SYNC=1 => pull down      SYNC=0 default  
LINE\_LE=1 => pull down      LINE\_LE=0 default  
LOCAL\_LE=1 => pull down      LOCAL\_LE=0 default  
CONFIG1 and 2 = 1 => pull high

/LOCK=0 => Rec-PLL is locked  
TPWDN\*=0 => Serializer enter power down mode: Ser.PLL stops, outputs into 3-state  
RPWDN\*=0 => Deserializer enter power down mode: PLL stops, outputs=3-state  
REN=0 => Deserializer outputs ROUT[15:0] into tri-state; Rec-PLL remains locked.  
DEN=0 => Serializer LVDS outputs into tri-state; Trans-PLL remains locked.  
SYNC=1 => Transm. sends SYNC pattern.  
LINE\_LE=1 => Line Loopback: serial RIN+/- back to serial DO+/-  
LOCAL\_LE=1 => Local Loopback: DIN[...] back to ROUT[...]  
CONFIG1 and 2 = 1 => reserved; pull to high level

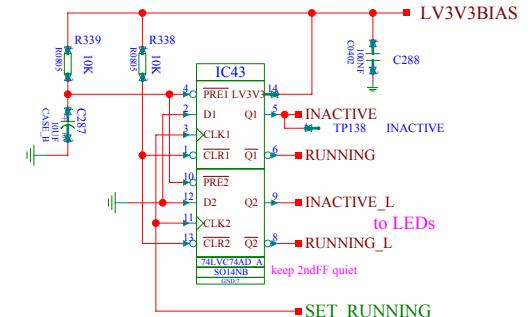
# DISPLAY

leds mounted above all connectors on frontpanel

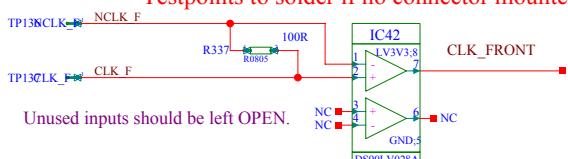
## Front Panel Text



## INTERLOCK



Testpoints to solder if no connector mounted.



## LEDS

Front Panel cables

DIFF\_CONN: CLK //in for test

LEMO: BCRES //out

4x4 RJ45-8

REC cable 3 TRANS cable 3

REC cable 2 TRANS cable 2

REC cable 1

REC cable 0

Differential Connector: JMP2 to solder 2 pins with 100mil distance

RS: Binder Subminiatur-Rundsteckverbinder d= 10mm der Serie 711 ; 719; 8mm; 712; 12mm;  
RS: Subminiatur-Rundsteckverbinder d=2mm der Serie 710 haben eine Bajonetts-Verriegelung  
TRIAD01 Serie von Thomas&Betsch bei RS d=15mm bei 3 pins  
MMCX Mikro-Miniatur-Koax-Steckverbinder 3.5 Euro bei RS, für RG178 cable;  
DOPPEL LEMO COAX: EPY.00.250.NTN 14.3 hoch passt in VME; 8 mm breit; RS: 28 Euro

4x4 RJ45-8 Connectors ==> 24 cm

4 + 2 INFINIBAND CONNECTORS ==> 6x1=6 cm

Front Panel space for 9U: >300 mm

## Frontpanel

DR1 DRILL\_2P8 DR2 DRILL\_2P8 DR3 DRILL\_2P8

## Rail

X3 DRILL\_2P8 X2 DRILL\_2P8

## PSB-9U-CARD

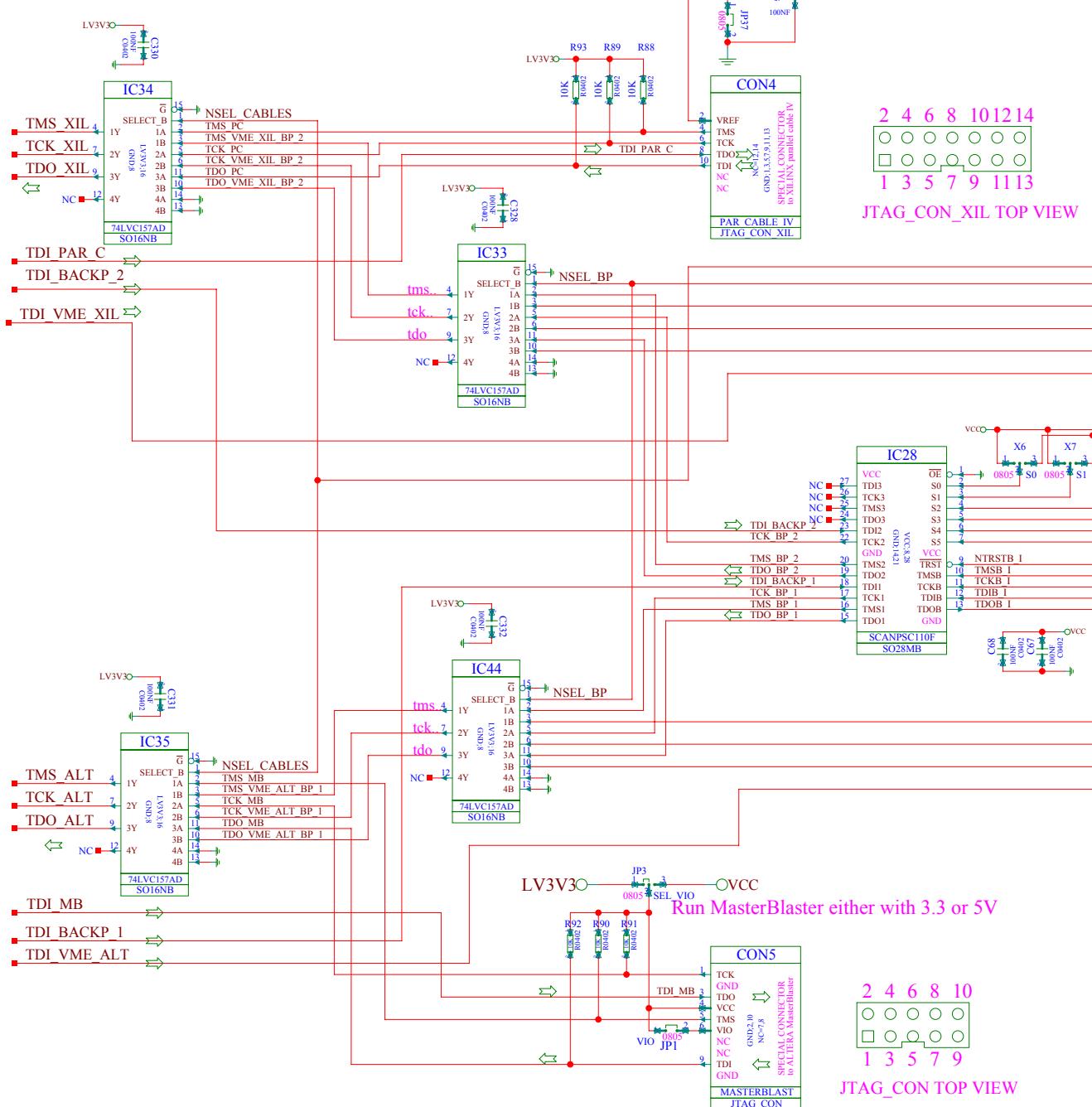
FRONT PAN PSB

HEPHY VIENNA ELEKTRONIK 1 sheet 1 of 1

modified by A.TAUROE 11-15-2004 13:21

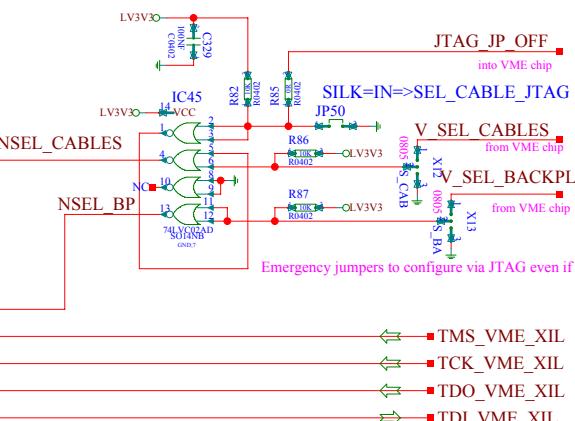
checked by AT 11-12-2004 17:24

VREF is adjustable for other future download device  
Set VREF = 3.3V for Parallel CableIV



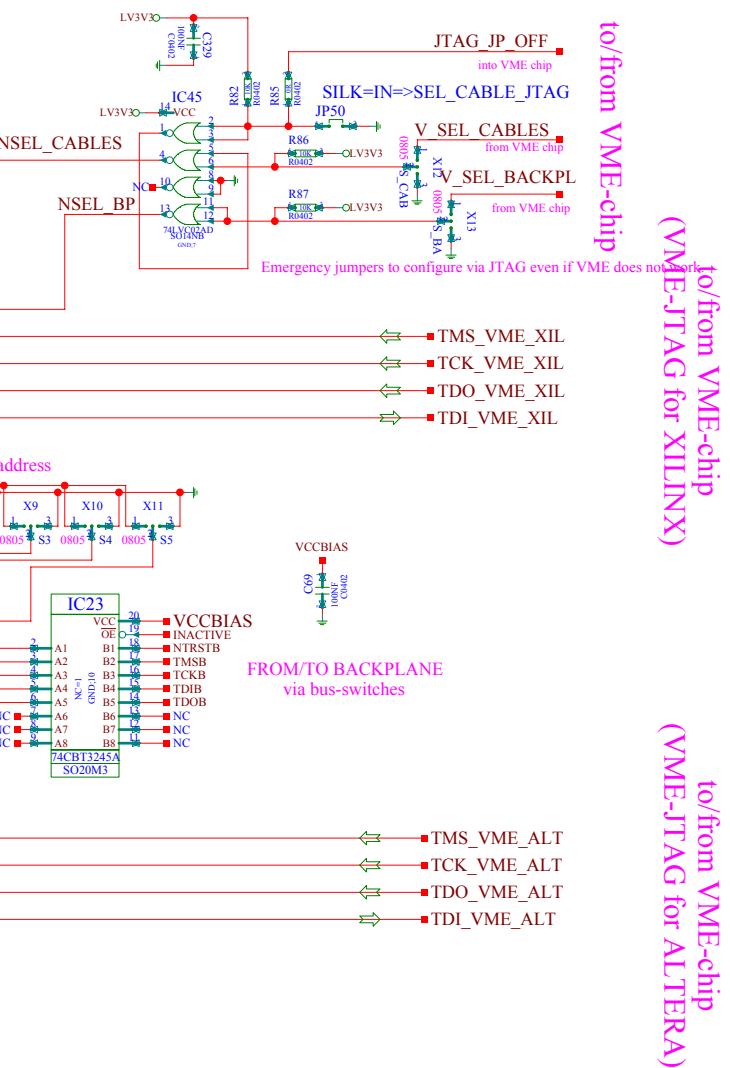
### JTAG-chain-selection:

JTAG-cables-jumper = IN => MasterBlaster and Par.-cable IV selected  
JTAG-cables-jumper = OUTand VME-chip not ready => Backplane selected  
JTAG-cables-jumper = OUTand VME-chip ready => selection by VME



(VME-JTAG for XILINX)

(VME-JTAG for ALTERA)



**PSB-CARD-9U**

**JTAG PSB**

HEPHY VIENNA  
ELEKTRONIK 1

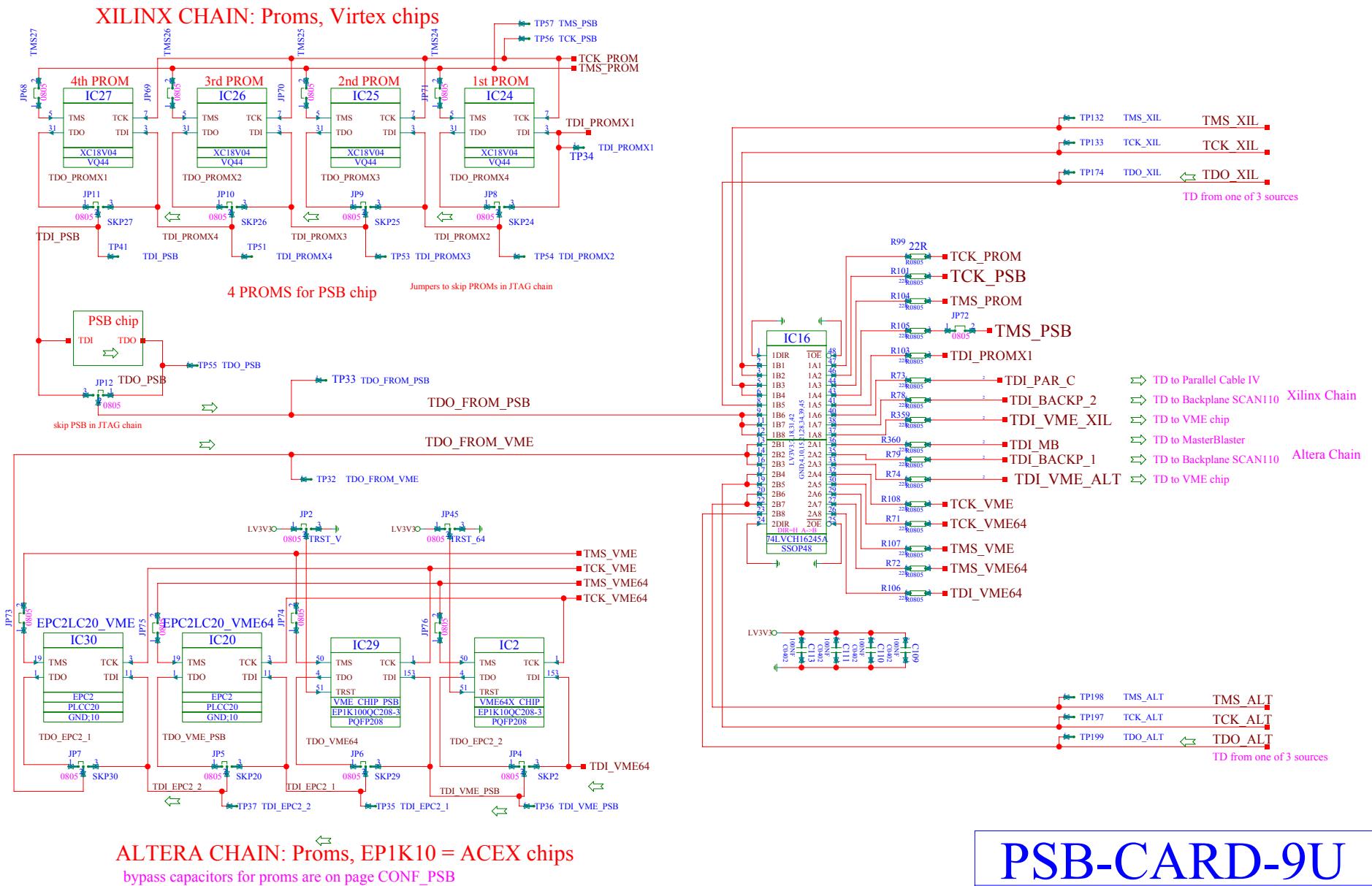
sheet 1 of 2

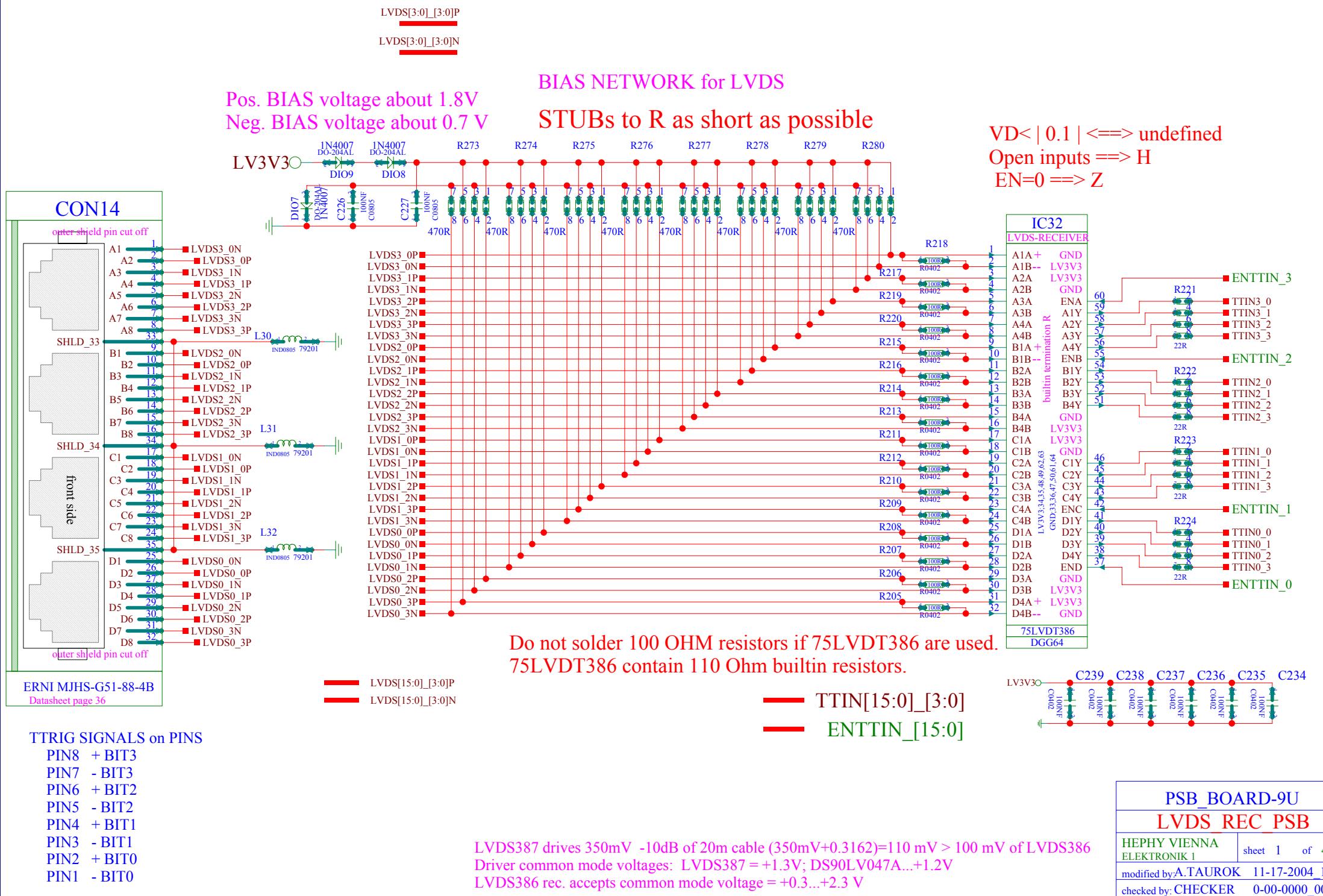
modified by: HB 11-17-2004\_16:09

checked by: AT 211004

JTAG: Xilinx Config. options: VME, Par\_CableIV, Bridge-backplane  
JTAG: Altera Config. options: VME, Master Blaster, Bridge-backplane

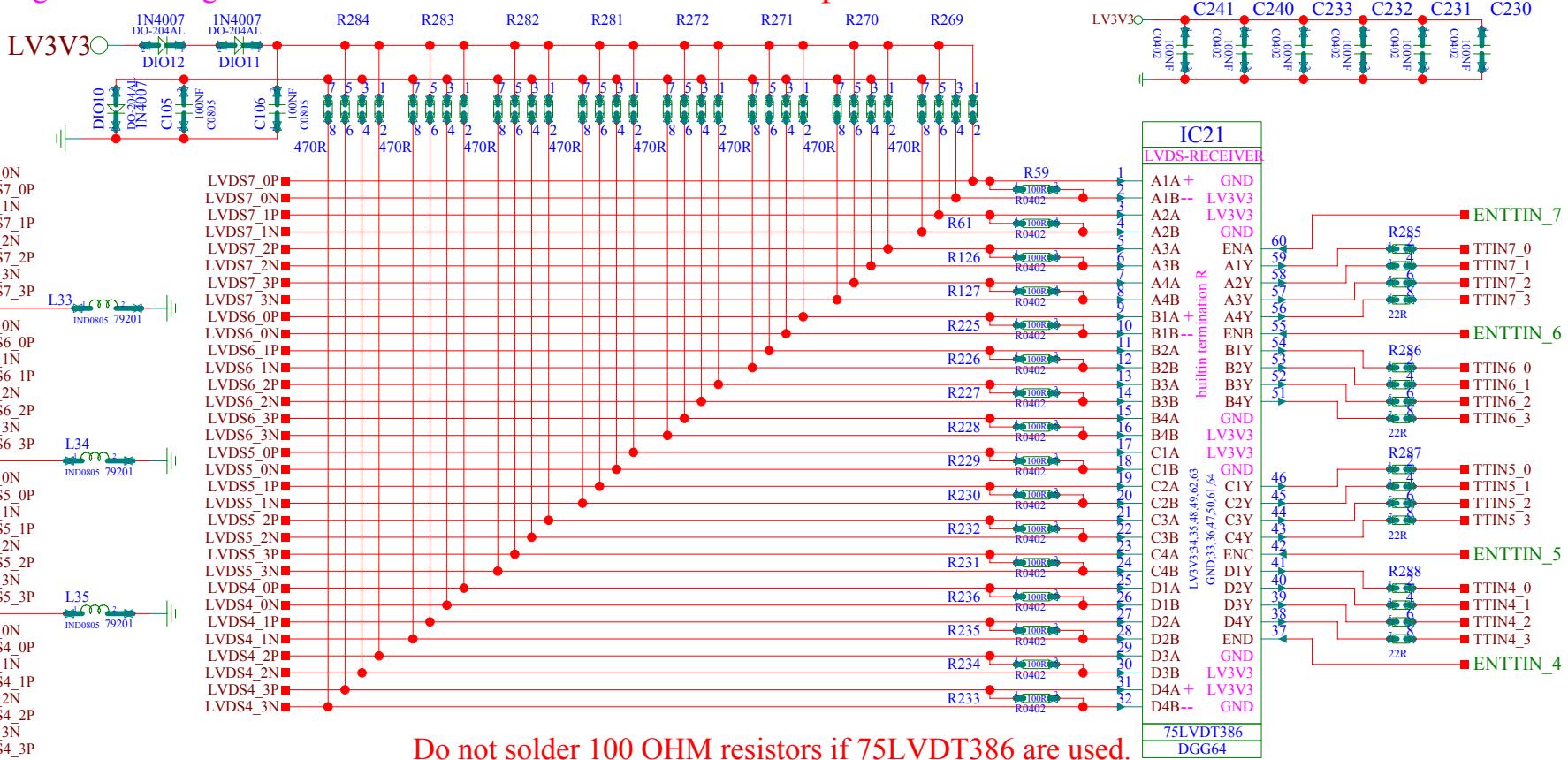
The Virtex chips are mounted on mezzanine boards.  
=>There is no JTAG hetero symbol for Virtex chips.





Pos. BIAS voltage about 1.8V  
Neg. BIAS voltage about 0.7 V

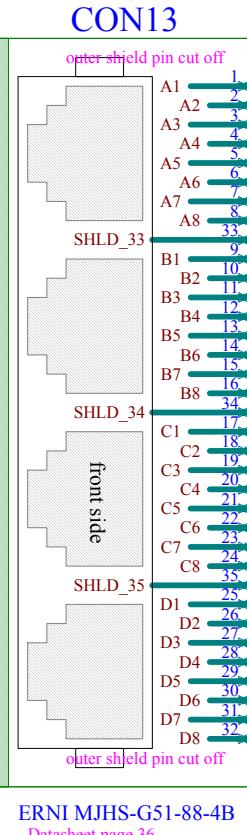
## BIAS NETWORK for LVDS STUBS to R as short as possible



Do not solder 100 OHM resistors if 75LVDT386 are used.  
75LVDT386 contain 110 Ohm builtin resistors.

— TTIN[15:0]\_3:0

— ENTTIN\_[15:0]



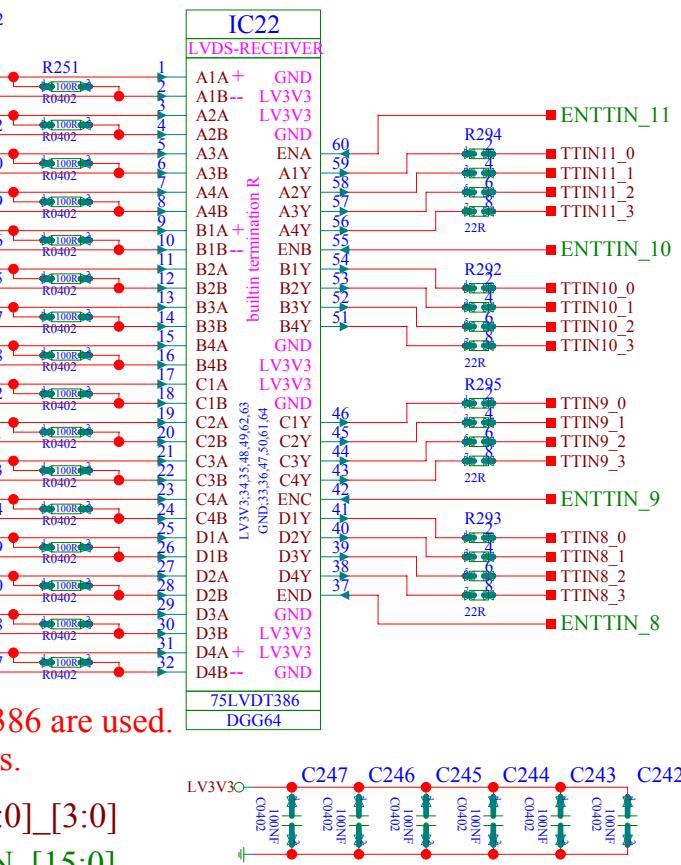
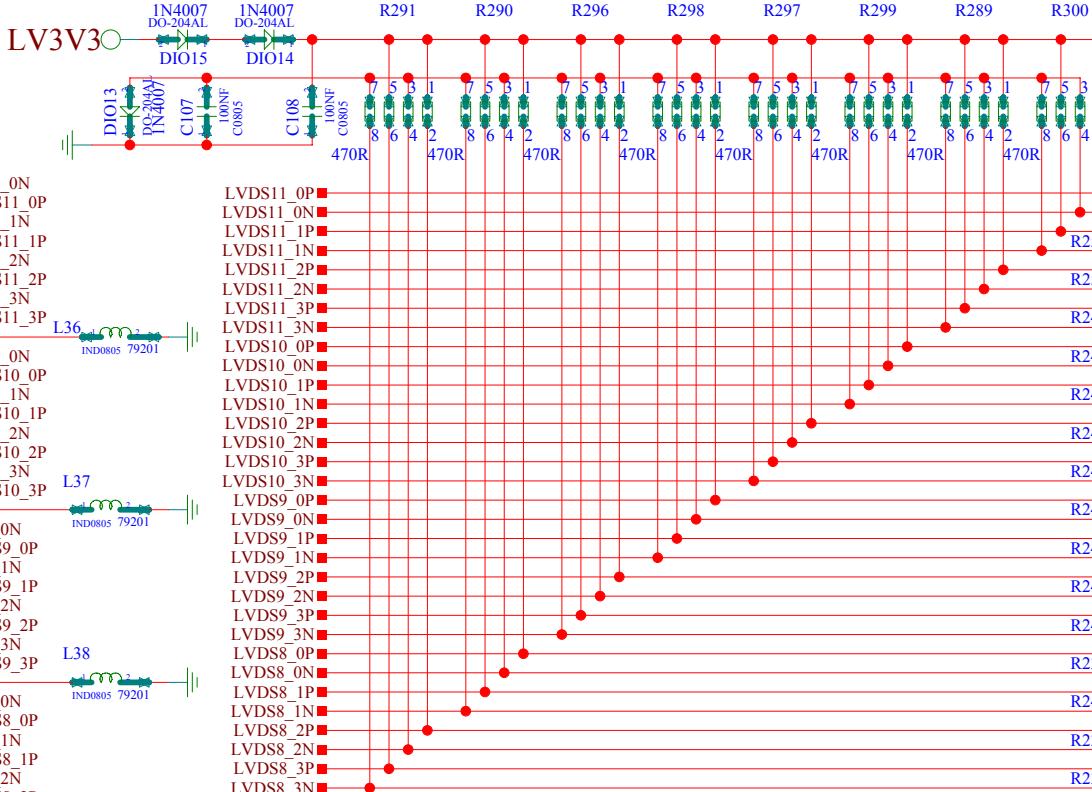
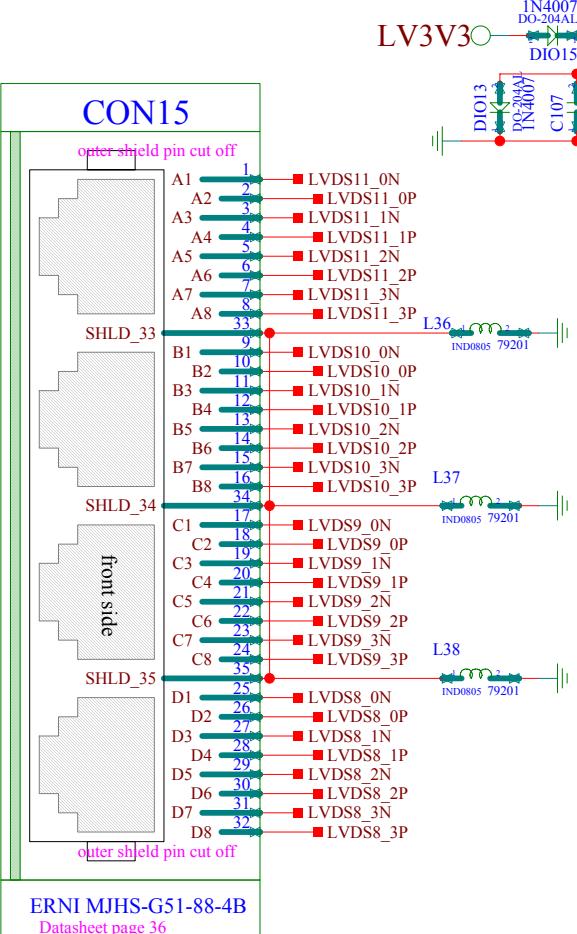
### TTRIG SIGNALS on PINS

- PIN8 + BIT3
- PIN7 - BIT3
- PIN6 + BIT2
- PIN5 - BIT2
- PIN4 + BIT1
- PIN3 - BIT1
- PIN2 + BIT0
- PIN1 - BIT0

LVDS387 drives 350mV -10dB of 20m cable ( $350\text{mV}+0.3162=110\text{ mV} > 100\text{ mV}$ ) of LVDS386  
Driver common mode voltages: LVDS387 = +1.3V; DS90LV047A...+1.2V  
LVDS386 rec. accepts common mode voltage = +0.3...+2.3 V

Pos. BIAS voltage about 1.8V  
Neg. BIAS voltage about 0.7 V

## BIAS NETWORK for LVDS STUBS to R as short as possible



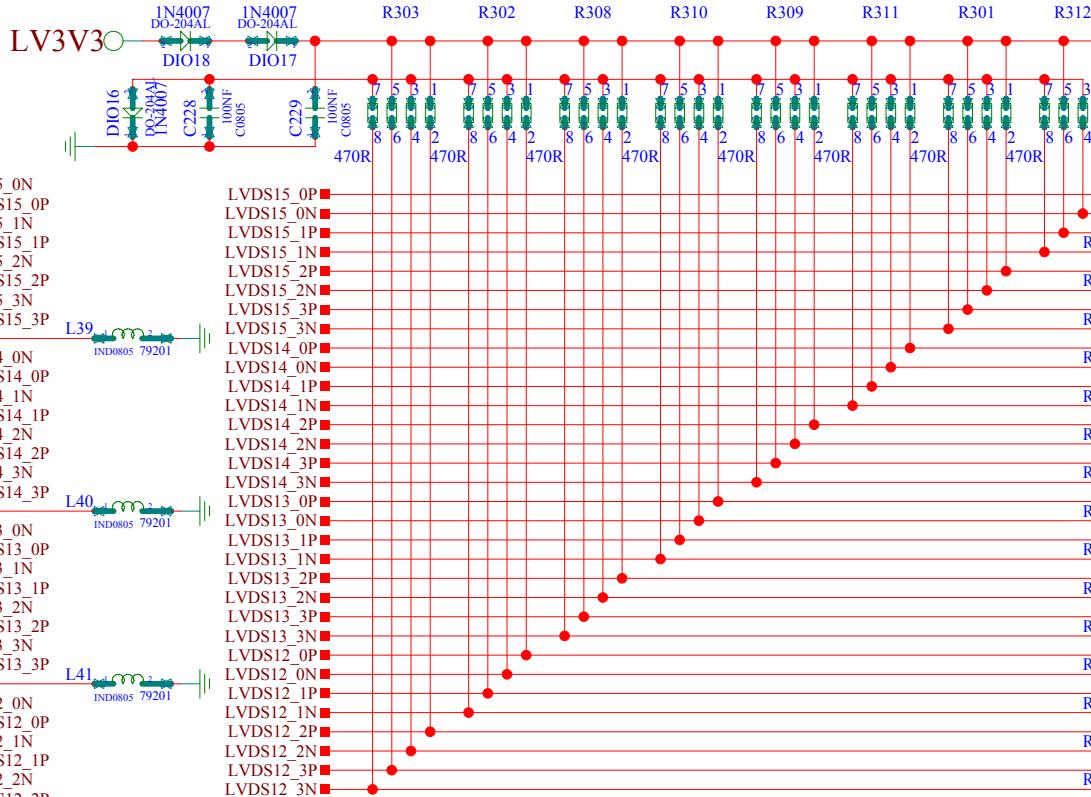
### TTRIG SIGNALS on PINS

- PIN8 + BIT3
- PIN7 - BIT3
- PIN6 + BIT2
- PIN5 - BIT2
- PIN4 + BIT1
- PIN3 - BIT1
- PIN2 + BIT0
- PIN1 - BIT0

LVDS387 drives 350mV -10dB of 20m cable ( $350\text{mV}+0.3162=110\text{ mV}$ ) > 100 mV of LVDS386  
Driver common mode voltages: LVDS387 = +1.3V; DS90LV047A...+1.2V  
LVDS386 rec. accepts common mode voltage = +0.3...+2.3 V

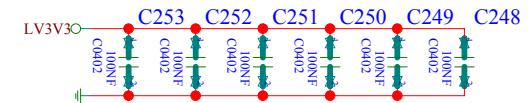
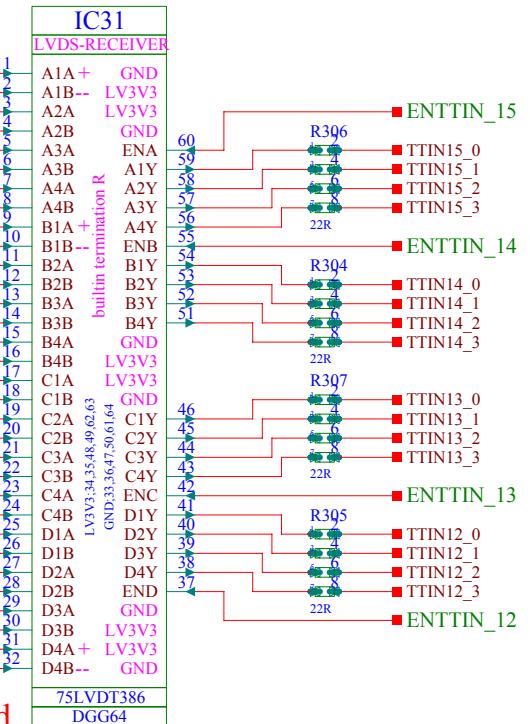
Pos. BIAS voltage about 1.8V  
Neg. BIAS voltage about 0.7 V

## BIAS NETWORK for LVDS STUBs to R as short as possible



Do not solder 100 OHM resistors if 75LVDT386 are used.  
75LVDT386 contain 110 Ohm builtin resistors.

— TTIN[15:0]\_[3:0]  
— ENTTIN\_[15:0]

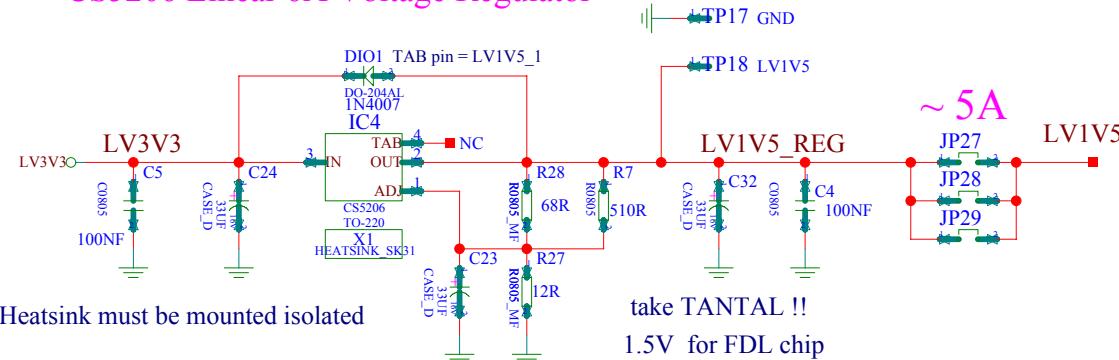


### TTRIG SIGNALS on PINS

- PIN8 + BIT3
- PIN7 - BIT3
- PIN6 + BIT2
- PIN5 - BIT2
- PIN4 + BIT1
- PIN3 - BIT1
- PIN2 + BIT0
- PIN1 - BIT0

LVDS387 drives 350mV -10dB of 20m cable ( $350\text{mV}+0.3162=110\text{ mV}$ ) > 100 mV of LVDS386  
Driver common mode voltages: LVDS387 = +1.3V; DS90LV047A...+1.2V  
LVDS386 rec. accepts common mode voltage = +0.3...+2.3 V

### CS5206 Linear 6A Voltage Regulator



$$V_{\text{ref}} = (1.240 \dots 1.254 \dots 1.266) \text{ V} / 68.1 = 18.2 \dots 18.4 \dots 18.6 \text{ mA} > 10 \text{ mA}$$

$$250 \text{ mV} / (18.2 \dots 18.6 \text{ mA}) = 13.73 \dots 13.44 \text{ Ohm}$$

Adjust voltage with R131 = 475...562 Ohm

$I_{\text{adj}} = 54 \text{ uA}$ ...can be neglected

all resistors for CS5206 in metalfilm

copied from FDL board

$\sim 5 \text{ A}$

LV1V5\_REG

LV1V5

TP17 GND

TP18 LV1V5

take TANTAL !!  
1.5V for FDL chip

# PSB-CARD-9U

## POWER\_PSB

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 1

modified by: H. BERGAUER

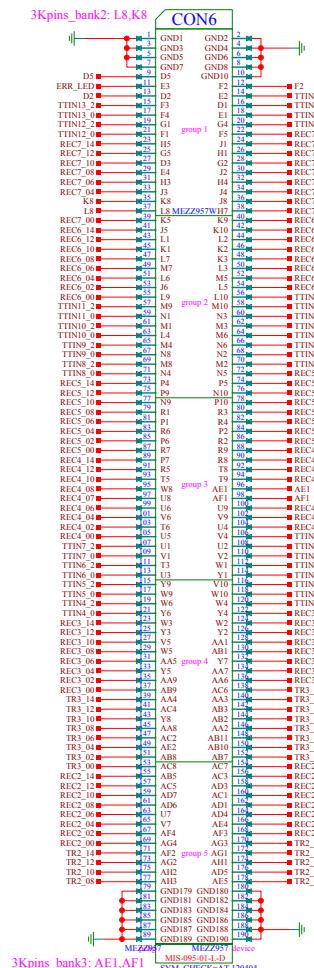
10-14-2004\_9:55

checked by: AT+MP

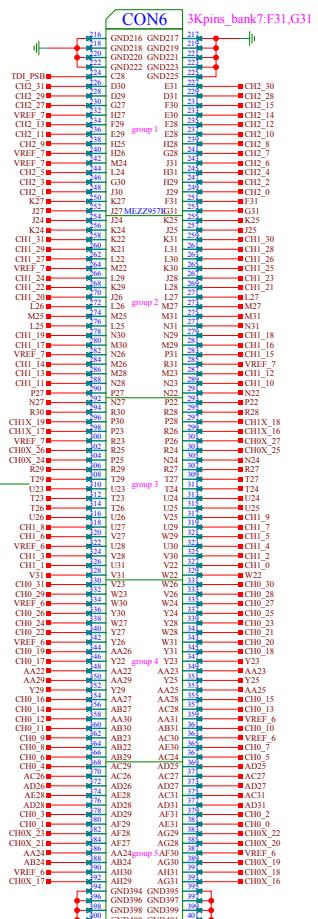
110504



# WEST MIS\_095 connector



# EAST MIS\_095 connector



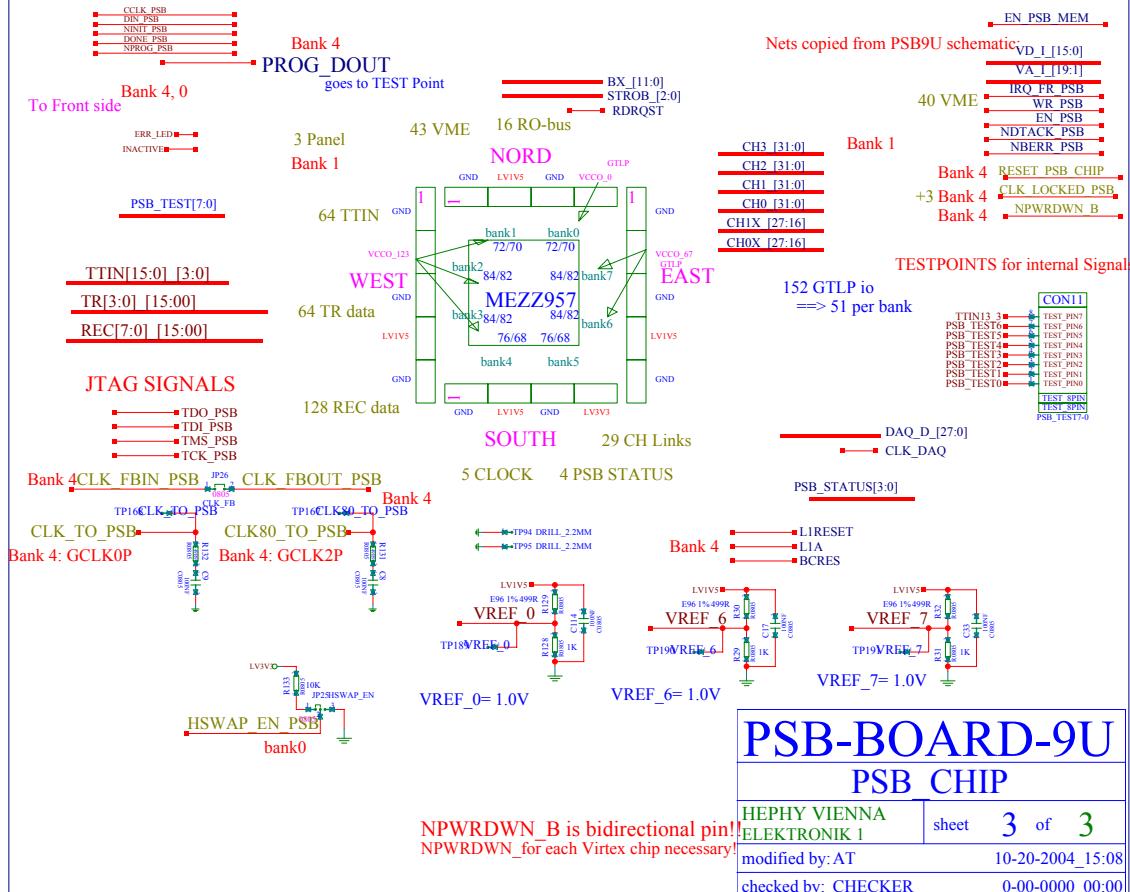
ICLB = 4 slices (as 2x2) Isllices= F+G LUT, 2 FF, hor.cascade OR,  
 Device Row x Col ./Slices/RAM kbits/Multiplier/RAMBlocks (Kbits)/DCMs/maxIO pads  
 XC2V1000 40x32 5120 160 40 40 8 432  
 XC2V1500 48x40 7680 240 48 48 8 528  
 XC2V1500 =15360 DFF XC2V2000=4BF957 xxxx io  
 XC2V1500-5FFB96 413 S XC2V3000=4BF957 xxxx io  
 Monitor RAMs: (192+16+68)\*16 = 18RAMblocks RingBuf (DPM)  
 18RAMblocks RO-Buf (FIFO)  
 18RAMblocks RX-Buf  
 18RAMblocks L/A queue 1 RAMblock =18 kbit DPRAM

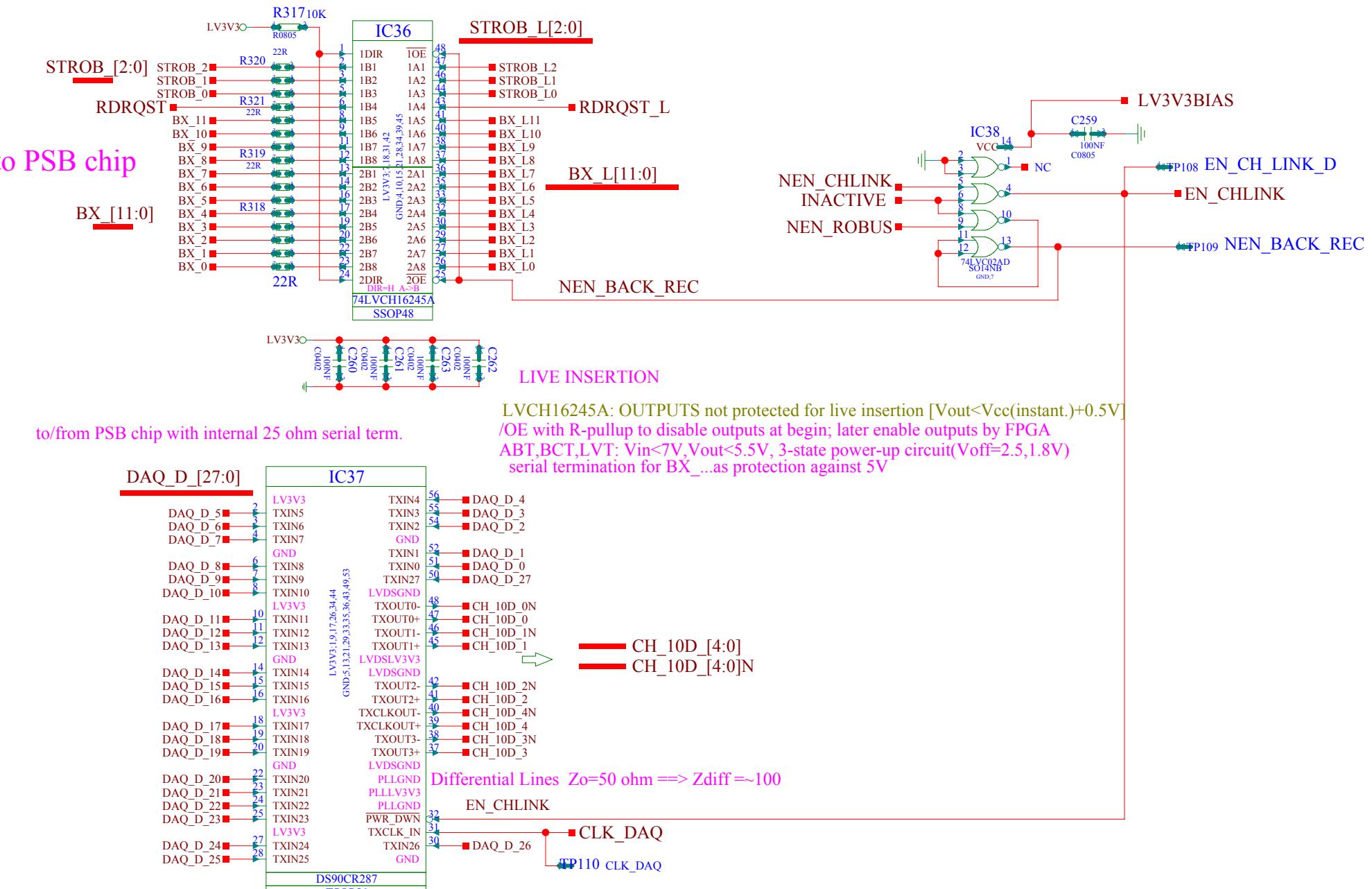
XC2V3000 benötigt 3 Proms XC18V04VQ44C A.T: Ich hoffe dass XC2V2000 genügt.  
 XC2V4000 benötigt 4 Proms XC18V04VQ44C  
 XC2V6000 benötigt 6 Proms XC18V04VQ44C

VREF, CLK, Special PINS have to be on same pins on both MEZZ boards.

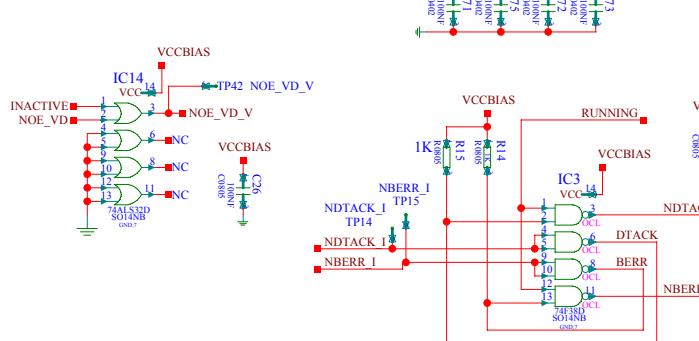
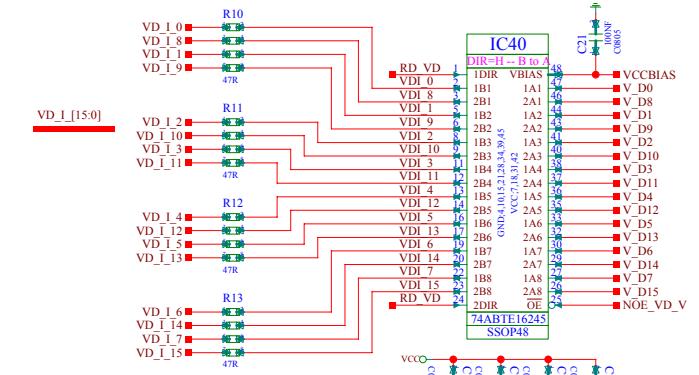
**RESET Signale to PSB chip**  
 RESET\_DCM\_PSB...resynchronizes CHIP to CLK  
 RESET\_PSB...=> GSR to STARTUP...resets all registers  
 INACTIVE ==> GTS to STARTUP...releases IO pins  
 NSYSRES ==> reconfigures PSB chip from PROM

## PSB CHIP: REFDES =CON6





47 Ohm resistors protect the Virtex drivers against overvoltage spikes.



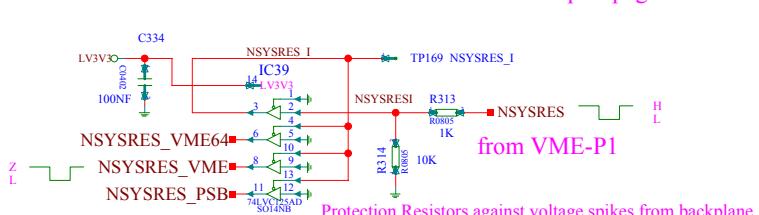
Keep NDTACK NBERR inactive while VME64X chip is unconfigured

inverted values  
Geographical Addresses

Parity bit: for odd parity

slot=1: GA=0 0001 => GAP=0  
slot=2: GA=0 0010 => GAP=0  
slot=3: GA=0 0011 => GAP=1  
etc

See VME64x pdf page 10 Table 3-3



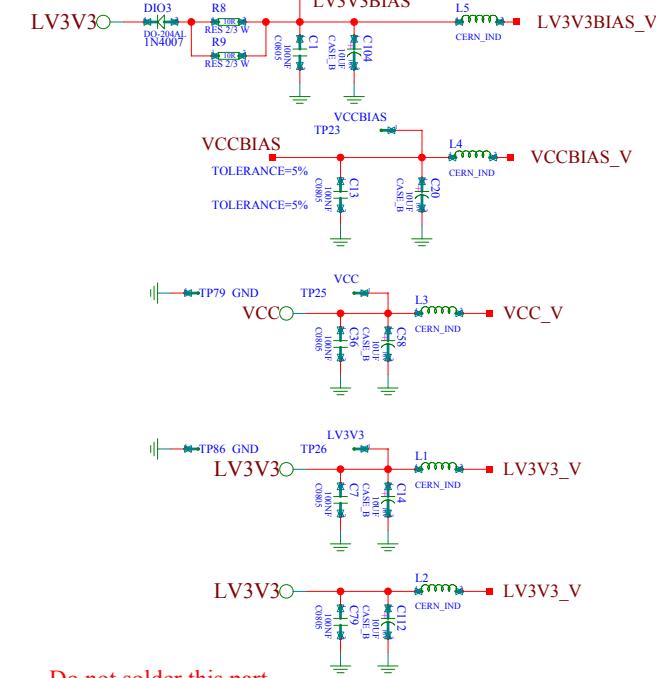
Stecker und Signale mit GTL und TIM schematic vergleichen

D1 = VCC on BACK6U  
D1 = LV3V3bias on BACK9U

CONI	
V_D0	D00 +5V
V_D1	D01 GND
V_D2	D02 RETRY*
V_D3	D03 A24
V_D4	D04 A25
V_D5	D05 A26
V_D6	D06 A27
V_D7	D07 A28
GND	D08 A29
NDS1	D09 A30
NDS2	D10 A31
NDS3	D11 A32
NDS4	D12 A33
NDS5	D13 A34
NWRITE	D14 A35
GND	D15 A36
NDTACK	D16 A37
GND	D17 A38
ASR	D18 A39
GND	D19 A40
NIACK	D20 A41
JACKIN	D21 A42
JACKOUT	D22 A43
V_AM4	D23 A44
V_A7	D24 A45
V_A6	D25 A46
V_A5	D26 A47
V_A4	D27 A48
V_A3	D28 A49
V_A2	D29 A50
V_A1	D30 A51
NC	D31 A52
V_CC	D32 A53
V_AM0	B1 A54
V_AM1	B2 A55
V_AM2	B3 A56
V_AM3	B4 A57
GND	B5 A58
NC	B6 A59
NC	B7 A60
NC	B8 A61
NC	B9 A62
NC	B10 A63
NC	B11 A64
NC	B12 A65
NC	B13 A66
NC	B14 A67
NC	B15 A68
NC	B16 A69
NC	B17 A70
NC	B18 A71
NC	B19 A72
NC	B20 A73
SERCLK	B21 A74
SERDATA*	B22 A75
GND	B23 A76
IRQ1*	B24 A77
IRQ2*	B25 A78
IRQ3*	B26 A79
IRQ4*	B27 A80
IRQ5*	B28 A81
IRQ6*	B29 A82
IRQ7*	B30 A83
IRQ8*	B31 A84
IRQ9*	B32 A85
+5STDIBY	B33 A86
+5V	Z1 129 GND
D08	Z2 130 GND
D09	Z3 131 GND
V_D9	Z4 132 GND
C2	Z5 133 LV3V3_V
V_D10	Z6 134 GND
C3	Z7 135 LV3V3_V
V_D11	Z8 136 GND
C4	Z9 137 LV3V3_V
V_D12	Z10 138 GND
C5	Z11 139 LV3V3_V
V_D13	Z12 140 LV3V3_V
C6	Z13 141 GND
V_D14	Z14 142 GND
C7	Z15 143 LV2V5_V
V_D15	Z16 144 LV2V5_V
C8	Z17 145 LV2V5_V
V_D16	Z18 146 LV2V5_V
C9	Z19 147 LV2V5_V
NC	Z20 148 LV2V5_V
C10	Z21 149 LV2V5_V
NSBERR	Z22 150 LV2V5_V
C11	Z23 151 LV2V5_V
NSYSRES	Z24 152 LV2V5_V
C12	Z25 153 GND
NLWORD	Z26 154 GND
C13	Z27 155 GND
LWORD*	Z28 156 GND
GND	Z29 157 GND
AM5	Z30 158 GND
+3.3V	Z31 159 GND
V_AM5	Z32 160 GND

LV2V5\_V not used anymore

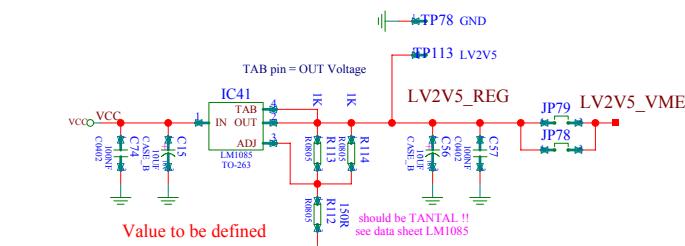
PSB9U must not be inserted into the 6U Backplane!!!



Do not solder this part.

Unused 2.5V plane can be connected to 3.3V optionally on 9U backplane if GTL-6U is not used anymore in Crate

LV3V3 LV2V5\_V (Local Net)



Value to be defined

Do not use LV2V5 and LV1V8 from BACKPLANE-6U  
LV2V5 and LV1V8 will not be connected on the Backplane-9U

## PSB-CARD-9U

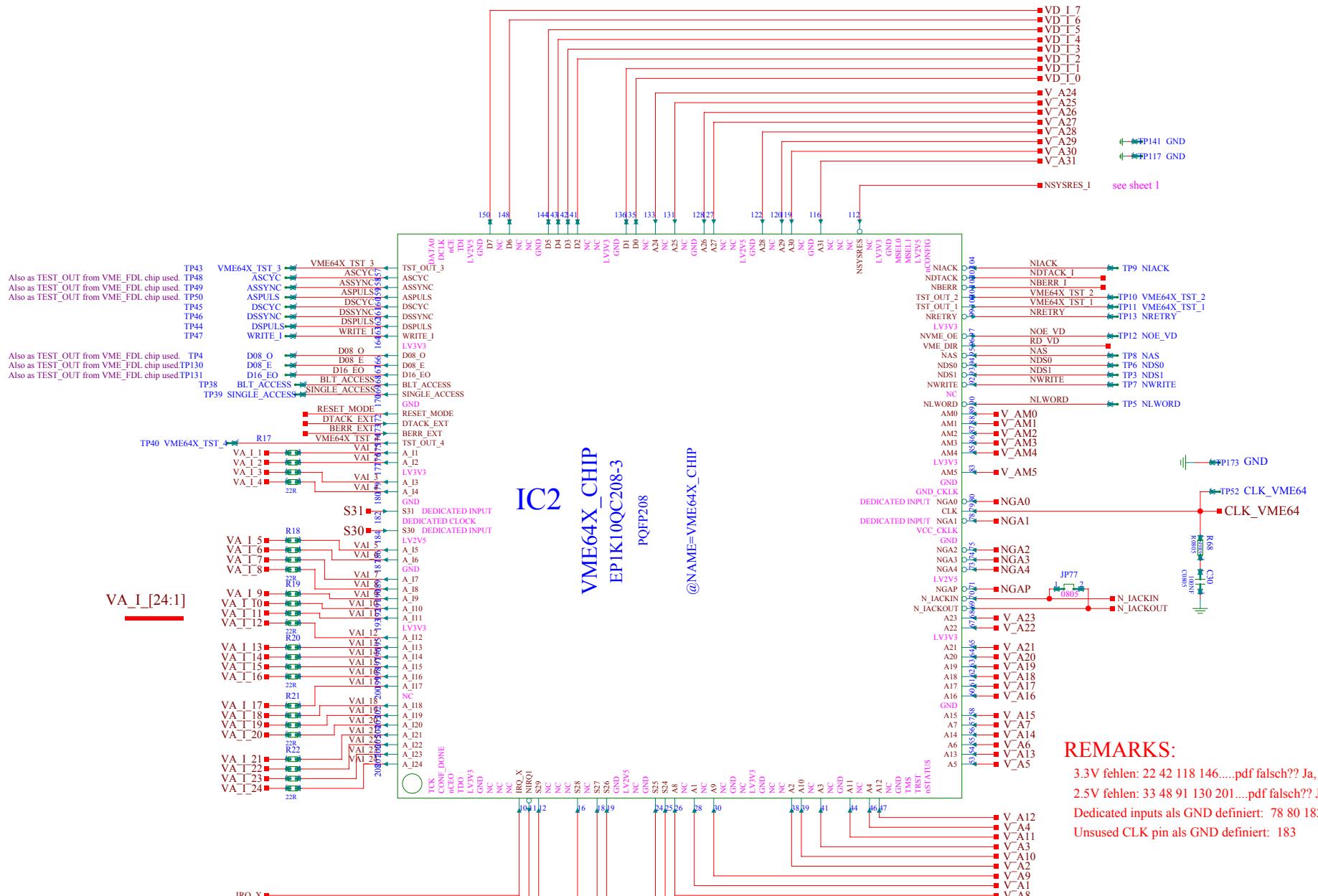
### VME INTERFACE PSB

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 3

modified by: H. BERGAUER 11-17-2004\_16:59

checked by: A TAUROK 8-18-2003\_16:53



Baseaddress

S31-S24 not used by VME644  
S31-S24 necessary for standard VME logic  
If required solder SMD Jumper to make a baseaddress.  
1-2=>H=1 // 2-3=>L=0'

# PSB-CARD-9U

## VME\_INTERFACE\_PSB

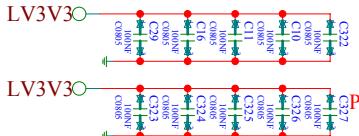
HEPHY VIENNA  
ELEKTRONIK 1

sheet 2 of 3

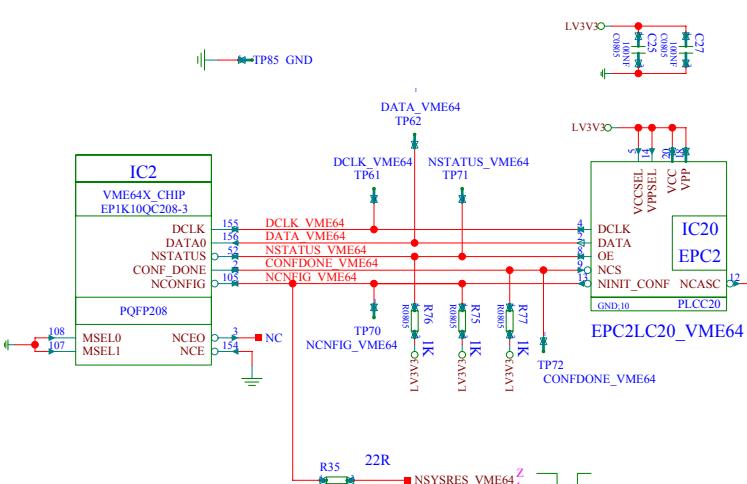
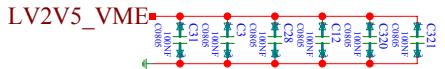
modified by: M:PADRTA 10-25-2004\_17:44

checked by: AT+MP 110504

10 pins for 3.3V

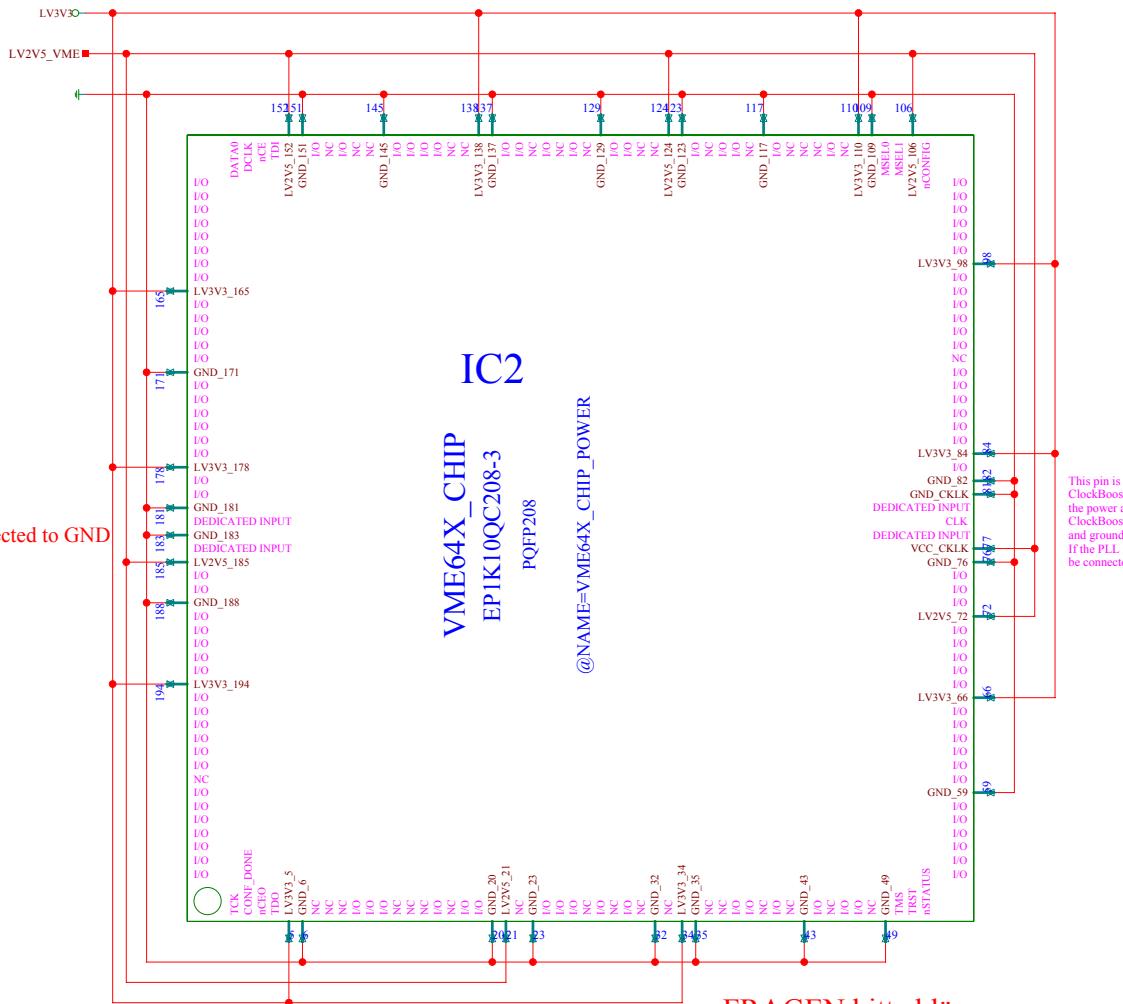


6 pins for 2.5V

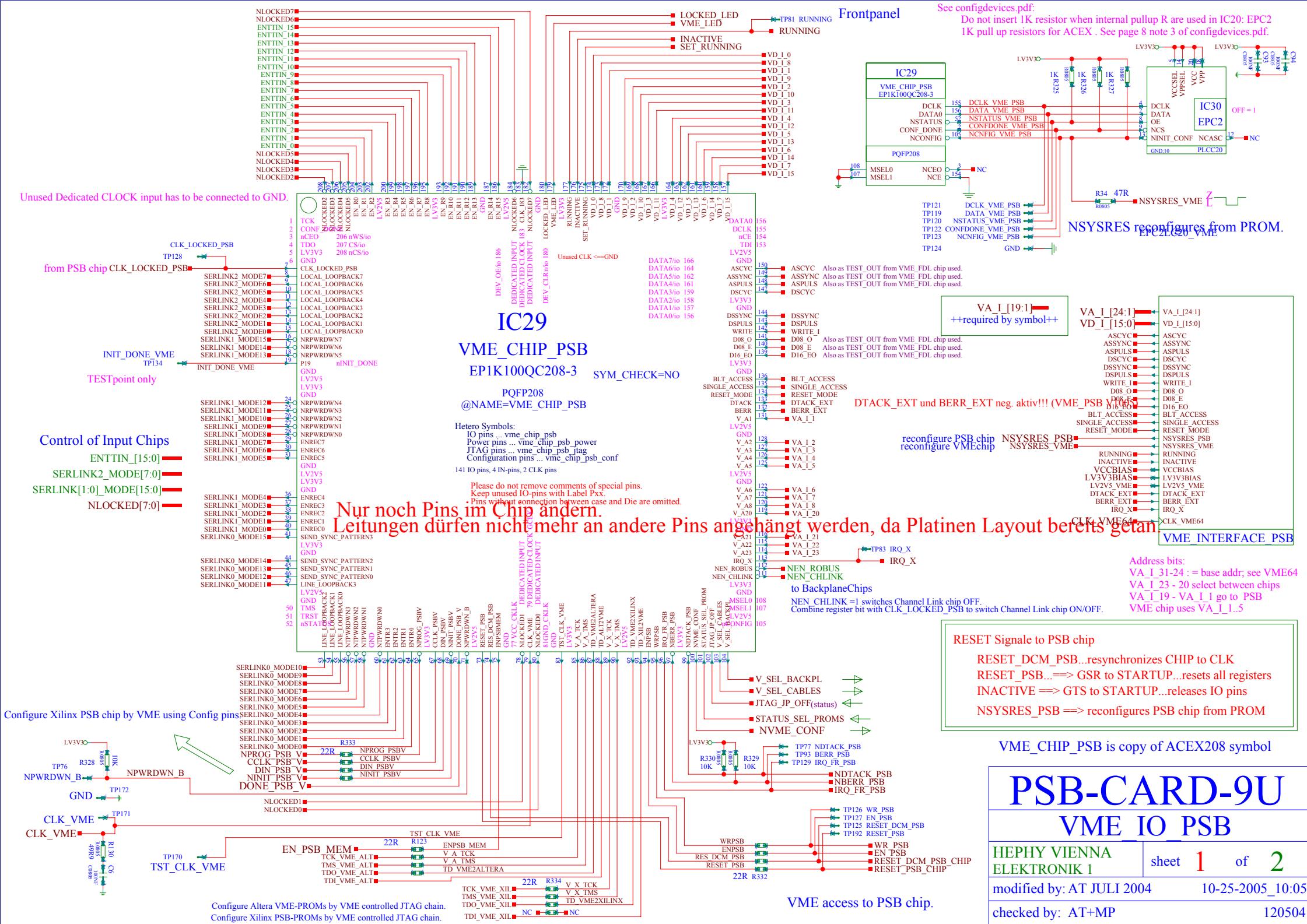


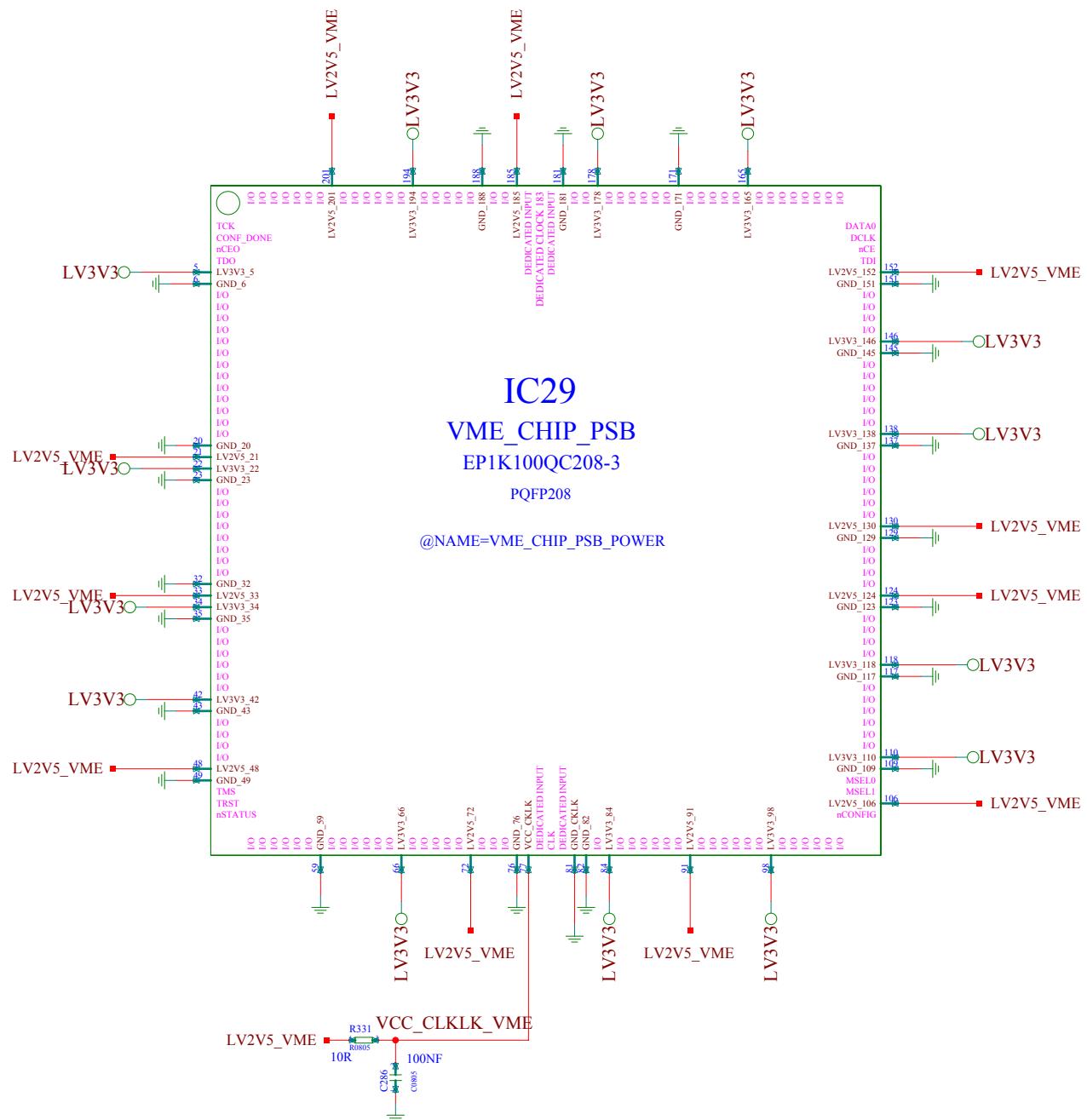
See configdevices.pdf:

Do not insert 1K resistor when internal pullup R are used in IC20: EPC2



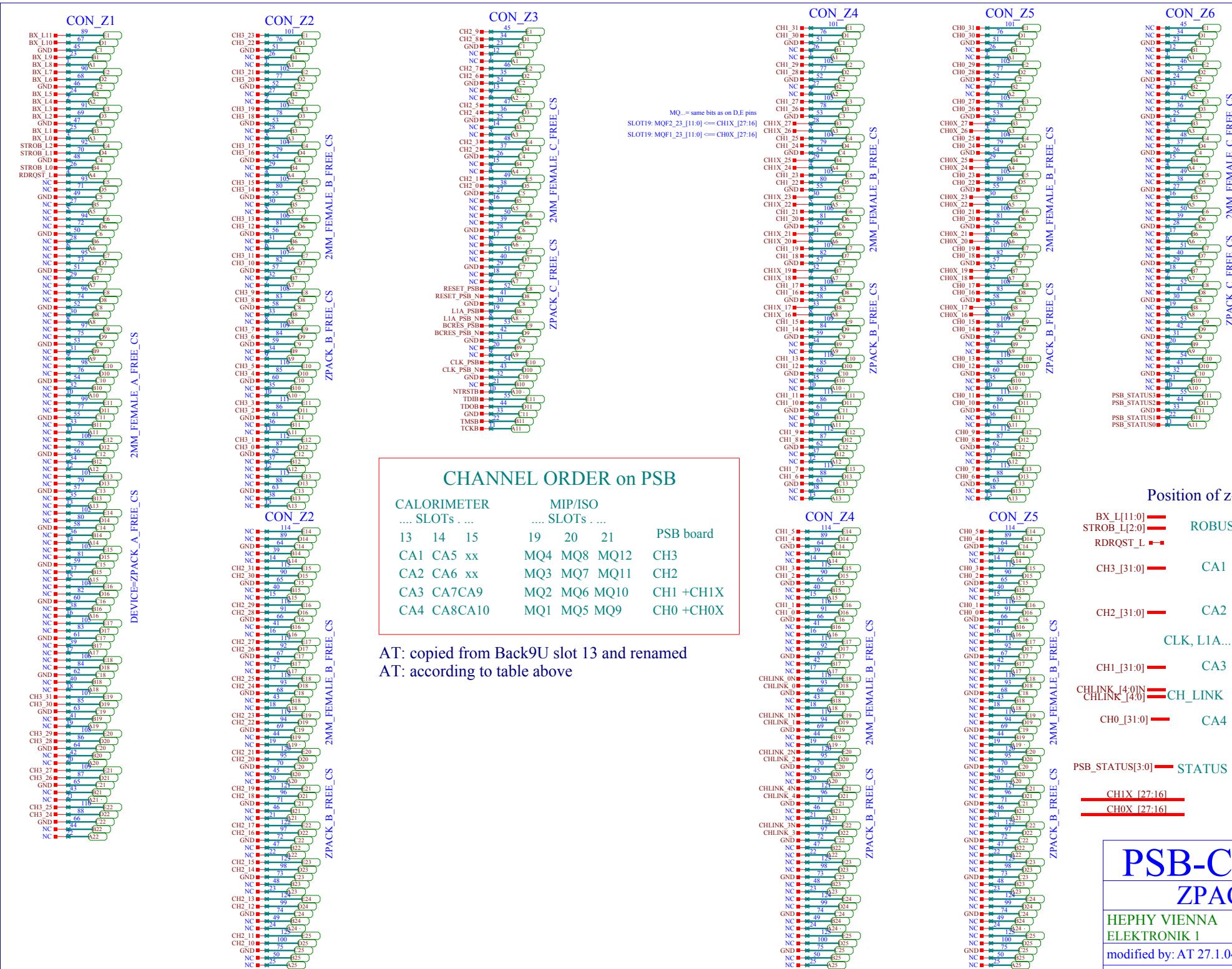
PSB-CARD-9U	
VME_INTERFACE_PSB	
HEPHY VIENNA ELEKTRONIK 1	sheet 3 of 3
modified by: H. BERGAUER	10-28-2004_17:15
checked by: CHECK_NAME	110504





**PSB-CARD-9U**  
**VME IO PSB**

HEPHY VIENNA ELEKTRONIK 1	sheet <b>2</b> of <b>2</b>
modified by: AT JULI 2004 11-17-2004_17:42	
checked by: AT+MP 120504	



# PSB-CARD-9U

## ZPACK PSB

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 1

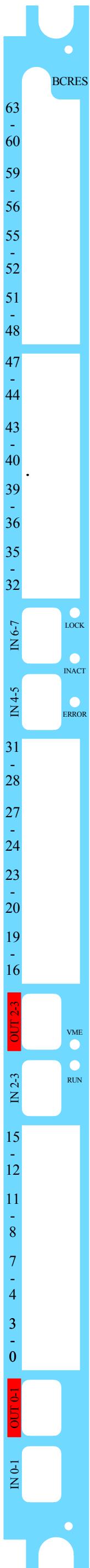
modified by: AT 27.1.04 7-15-2004\_16:30

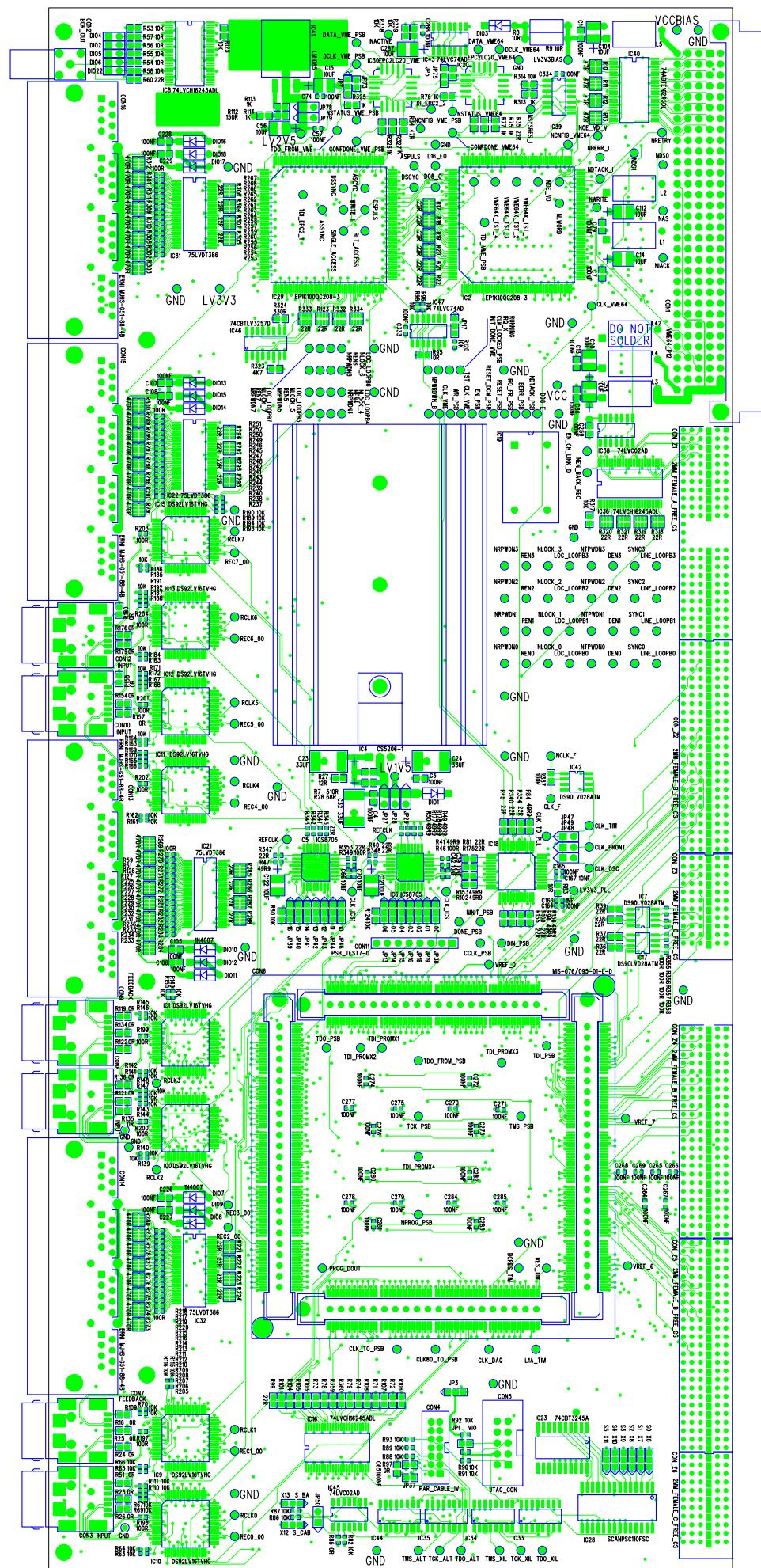
checked by: MP+AT

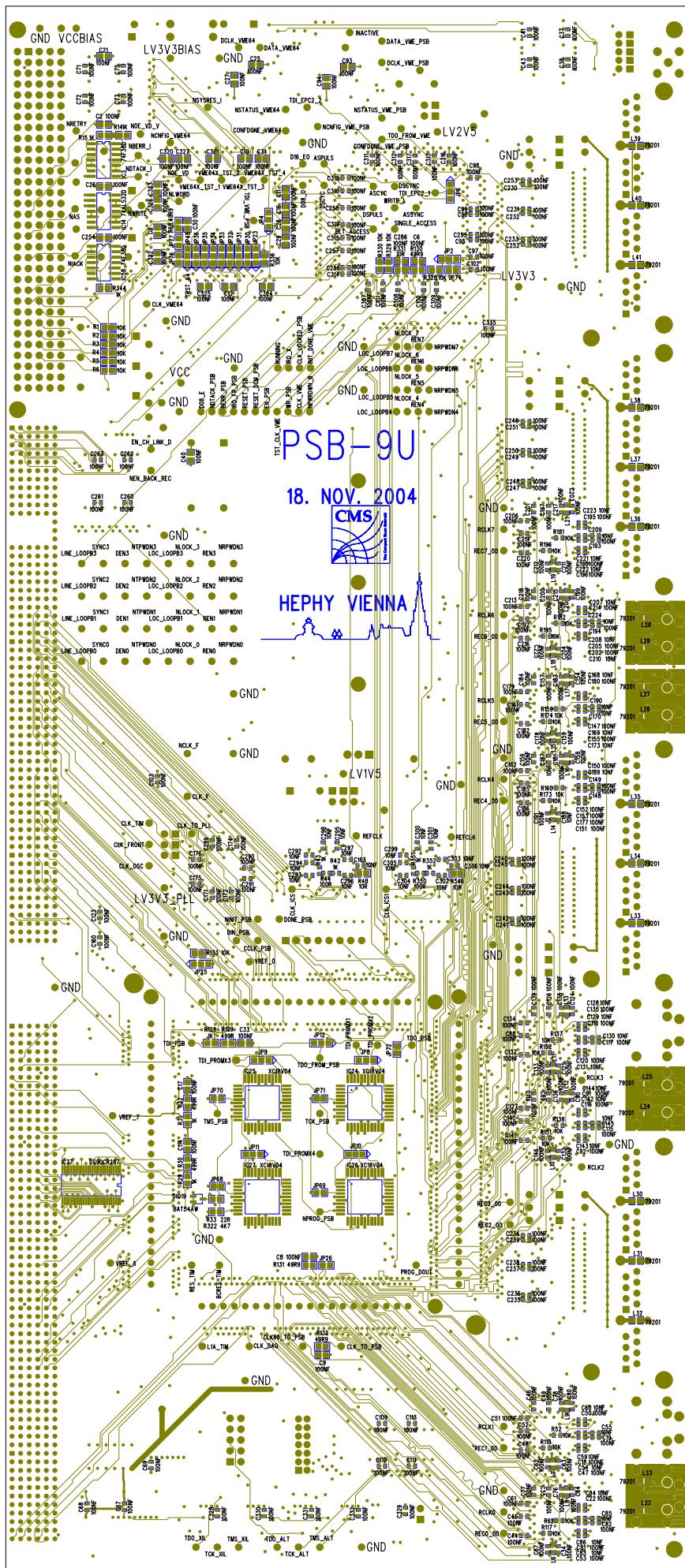
120504

Position of z-pack connectors

BX_L[11:0]	ROBUS	CON_Z1 A
STROB_L[2:0]	RDRQST_L	CON_Z2 B
CH3[31:0]	CA1	CON_Z3 C
CH2[31:0]	CA2	CON_Z4 D
CH1[31:0]	CA3	CON_Z5 E
CHLINK[4:0IN]	CH_LINK	CON_Z6 F
CH0[31:0]	CA4	
PSB_STATUS[3:0]	STATUS	
CH1X [27:16]		
CH0X [27:16]		







## Jumper and switches on PSB-9U-card

**JP1** (top side): selection of VIO of masterblaster

**OFF** → no voltage on VIO.

**ON** → LV3V3 or VCC on VIO (see JP3).

**JP2** (bottom side): TRST (JTAG) of VME-chip

**1-2 (default)** → solder R with 10K (LV3V3), TRST inactive.

**2-3** → do not solder.

**JP3** (top side): voltage selection for masterblaster

**1-2 (default)** → LV3V3.

**2-3** → VCC.

**JP4** (bottom side): VME64x-chip in JTAG-chain

**1-2** → VME64x-chip in JTAG-chain.

**2-3 (default)** → VME64x-chip **not** in JTAG-chain.

**JP5** (top side): PROM of VME64x-chip in JTAG-chain

**1-2** → PROM of VME64x-chip in JTAG-chain.

**2-3 (default)** → PROM of VME64x-chip **not** in JTAG-chain.

**JP6** (bottom side): VME-chip in JTAG-chain

**1-2** → VME-chip in JTAG-chain.

**2-3 (default)** → VME-chip **not** in JTAG-chain.

**JP7** (top side): PROM of VME-chip in JTAG-chain

**1-2** → PROM of VME-chip in JTAG-chain.

**2-3 (default)** → PROM of VME-chip **not** in JTAG-chain.

**JP8** (bottom side): 1<sup>st</sup> PROM of PSB-chip in JTAG-chain

**1-2** → in JTAG-chain.

**2-3 (default)** → **not** in JTAG-chain.

**JP9** (bottom side): 2<sup>nd</sup> PROM of PSB-chip in JTAG-chain

**1-2** → in JTAG-chain.

**2-3 (default)** → **not** in JTAG-chain.

**JP10** (bottom side): 3<sup>rd</sup> PROM of PSB-chip in JTAG-chain

**1-2** → in JTAG-chain.

**2-3 (default)** → **not** in JTAG-chain.

**JP11** (bottom side): 4<sup>th</sup> PROM of PSB-chip in JTAG-chain

**1-2** → in JTAG-chain.

**2-3 (default)** → **not** in JTAG-chain.

**JP12** (bottom side): PSB-chip in JTAG-chain

**1-2** → PSB-chip in JTAG-chain.

**2-3 (default)** → PSB-chip **not** in JTAG-chain.

**JP13, JP14, JP15, JP16, JP18, JP19 and JP38** (top side): jumper for SELxx input of PLL (IC6).

**JP17** (top side): jumper for “SEL\_PROMS”  
**(default)→** nothing inserted (NSYSRES\_PSB works).

**JP20 - JP22:** not in design!!!

**JP23, JP30, JP31, JP32, JP33, JP34, JP35 and JP36** (bottom side): S31-S24 for base address, **not used** in VME64x-systems!!!

**1-2 → ‘1’.**

**2-3 → ‘0’.**

**JP24:** not in design!!!

**JP25** (bottom side): HSWAP\_EN input of PSB-chip

**1-2 →** HSWAP\_EN=LV3V3, keeps jumper in OFF-position (I/O-pins in high-Z before configuration). In this position **configuration of PSB-chip via VME not possible**.

**2-3 (default)→** HSWAP\_EN=GND, enables pull-up-Rs of all I/O-pins in PSB-chip before configuration. In this position **configuration of PSB-chip via VME possible**.

**JP26** (bottom side): jumper for “CLK\_FBxxx”

**(default)→** not inserted.

**JP27, JP28 and JP29** (top side): jumper for “LV1V5”

**(default)→** solder-bridges after voltage-testing.

**JP37** (top side): jumper for “VREF” of Parallel-Cable IV

**(default)→** not inserted.

**JP39, JP40, JP41, JP42, JP43, JP44 and JP46** (top side): jumper for SELxx input of PLL (IC5).

**JP45** (bottom side): TRST (JTAG) of VME64x-chip

**1-2 (default)→** solder R with 10K (LV3V3), TRST inactive.

**2-3 →** do not solder.

**JP47, JP48 and JP49** (top side): selection of CLK\_TO\_PLL

**Only one jumper may be ON!**

**JP47 ON (default)→** CLK\_TIM.

**JP48 ON →** CLK\_OSC (from oscillator).

**JP49 ON →** CLK\_FRONT.

**JP50** (top side): jumper for “SEL\_CABLE\_JTAG”

**OFF (default)→** selection via VME.

**ON →** MB and PC-IV selected for JTAG.

**JP51 - JP67:** not in design!!!

**JP68, JP69, JP70, JP71 and JP72** (bottom side): jumper for “TMS-signals” for PROMs and PSB-chip. These jumpers are set in the same way as JP8-JP12.

**OFF → PROM not in JTAG-chain.**

**ON (default) → PROM in JTAG-chain.**

JP8: 1<sup>st</sup> PROM of PSB-chip

JP9: 2<sup>nd</sup> PROM of PSB-chip

JP10: 3<sup>rd</sup> PROM of PSB-chip

JP11: 4<sup>th</sup> PROM of PSB-chip

JP12: PSB-chip

**JP73, JP74, JP75 and JP76** (both sides): jumper for “TMS-signals” for PROMs and VME-chips. These jumpers are set in the same way as JP4-JP7.

**OFF → PROM not in JTAG-chain.**

**ON (default) → PROM in JTAG-chain.**

JP4: VME64x-chip

JP5: PROM of VME64x-chip

JP6: VME-chip

JP7: PROM of VME-chip

**JP77** (bottom side): N\_IACKIN/N\_IACKOUT

**ON → always on, no interrupt.**

**JP78 and JP79** (top side): jumper for “LV2V5\_VME”

**(default) → solder-bridges after voltage-testing.**

**X1 - X3:** drill-holes!!!

**X4 - X5:** not in design!!!

**X6 - X11** (top side): jumper for JTAG-code from backplane for SCANPSC110

**(default) → not used now.**

**X12** (top side): connect V\_SEL\_CABLES from VME

**1-2 (default) → connected.**

**2-3 → GND connection.**

**X13** (top side): connect V\_SEL\_BACKPL from VME

**1-2 (default) → connected.**

**2-3 → GND connection.**

# VME64X-CHIP (Version 0x100C)

of  
PSB-9U-card  
(9U-Version)

H. Bergauer, K. Kastner, M. Padrta, A. Taurok



**Jan-06**

**Version 0x100C**

## 1 Introduction

The VME64x Interface for Global Trigger boards is made for a slave module without interrupt capabilities. It works in systems with backplanes supplying VME64x standard as well as in systems with VME/VME64 backplanes. The Interface will contain a VME64x-chip, a VME-CHIP-PSB, transceivers for VME-data, logic for “live-insertion”, DTACK\*- and BERR\*-drivers and a special VME64x connector (P1/J1).

## 2 VME64x-chip

### 2.1 Versionshistory

- V1001: block-transfer via VME implemented (F1). (HB, 270504)
- V1003: 32-bit-transfer via VME implemented. (HB, 100804)
- V1004: same as V1001, but NLD\_ADDR freezes addresses. (HB, 211004)
- V1005: same as V1003 (32-bit-transfer), but NLD\_ADDR freezes addresses. (HB, 221104). **Do not use for PSB-card.**
- V1006: same as V1005 (32-bit-transfer), but with TEST\_OUT-selection in USER\_CSR. (HB, 291104). **Do not use for PSB-card.**
- V1007: same as V1004 (16-bit-transfer), but with TEST\_OUT-selection in USER\_CSR. (HB190805)
- V1008: same as V1007 (16-bit-transfer), but VIEWDRAW in local directory and working with vme\_chips\_lib. Changes in timing - TIMING\_V2\_1 used. (HB140905)
- V1009: based on V1008 (16-bit-transfer), but complete new fully synchronous design implemented. (HB041005)
- V100A: based on V1009 (16-bit-transfer), but DTACK\_EXT and BERR\_EXT from VME-CHIP-PSB are used as negative active signals now (because at power-up configuration of VME64X-CHIP is faster than configuration of VME-CHIP and therefore wrong DTACK and BERR signals are generated after configuration, which causes LEDs=“on” of CAEN-controller). Card-number is on S27-S24 (CARD\_NR[3..0]). (HB201005)
- V100B: based on V100A (16-bit-transfer), but INIT\_DONE-feedback on pin 19 (S26 and pin 18 (S27) is implemented to have no wrong DTACK and BERR signals during init-phase after configuration-phase. Card-number is on S31-S28 (CARD\_NR[3..0]) now. (HB241005)
- **V100C:** based on V100B of VME64x-chip, but AM=0x2F is combined with BASE\_ADDR\_CR\_CSR to generate correct NVME\_OE. Therefore geo\_addr\_v2\_0 and vme\_d16\_v1\_6 are used. (HB071205)

### 2.2 Hardware

The VME64x-chip is an Altera EP1K10QC208-3.

### 2.3 Firmware

```
serial-nr.: PSBxx          (xx = CARD_NR [dec] jumpers S31-S28)
chip_id:   0x00018n11      (n = CARD_NR [hex] jumpers S31-S28)
version:   0x0000100C
```

### 2.4 References

See VME64-specification and VME64x-specification for definitions.

## 2.5 Features of the VME64x-chip (V100C)

- **User Configuration ROM** (USER\_CR: address range 0x01003..0x01033, size is 13 bytes) for “chip identifier“ and “version“ of VME64x-chip (see 2.7.3) [0x01003-0x0101F] and for “serial number“ of board (see 2.7.3) [0x01023-0x01033].
- “Card number“ is part of “chip identifier“ and is fix soldered by jumpers on the lines S31-S28 (CARD\_NR[3..0]).
- “Serial number“ is PSBxx (xx is the decimal expression of “card number” with leading zero - exception: PSB16 has “card number”=0).
- **User Command Status Register** (USER\_CSR: address range 0x05003..0x0502F, size is 12 bytes) for the “TEST\_OUT-selection-registers” is implemented (see USER\_CSR space).
- **Function 0** (F0) – D16 only, base-address at **A31-A25**, AM=0x0D and 0x09 (only single transfer).
- **Function 1** (F1) – D16 only, base-address at **A31-A25**, AM=0x0F and 0x0B (only block transfer).

## 2.6 Address spaces overview

**AM:** 0x2F, access: **D08\_O**

**A23-A19:** Geographic address (=VME slot number) or ‘11110’=amnesia address

<b>A18-A00</b>	<b>=&gt;</b>	<b>Register-name</b>
0x00003 – 0x007FF	=>	512x8 bit Configuration ROM (read)
0x01003	=>	chip-id_3 (read)
0x01007	=>	chip-id_2 (read)
0x0100B	=>	chip-id_1 (read)
0x0100F	=>	chip-id_0 (read)
0x01013	=>	version_3 (read)
0x01017	=>	version_2 (read)
0x0101B	=>	version_1 (read)
0x0101F	=>	version_0 (read)
0x01023 – 0x01033	=>	5 bytes Serial Number [PSBxx] (read)
0x03003 – 0x037FF	=>	CRAM 512x8 bit RAM (not used!!) (read/write)
0x05003 – 0x05007	=>	TEST_OUT-selection in USER_CSR (read/write)
[0x7FC03 – 0x7FFFF]	=>	Command/Status registers (read/write)]
0x7FF63	=>	ADER-F0_3 register (read/write)
0x7FF67	=>	ADER-F0_2 register (read/write)
0x7FF6B	=>	ADER-F0_1 register (read/write)
0x7FF6F	=>	ADER-F0_0 register (read/write)
0x7FF73	=>	ADER-F1_3 register (read/write)
0x7FF77	=>	ADER-F1_2 register (read/write)
0x7FF7B	=>	ADER-F1_1 register (read/write)
0x7FF7F	=>	ADER-F1_0 register (read/write)
0x7FFF7	=>	Bit Clear Register [BCR] (read/write)
0x7FFF8	=>	Bit Set Register [BSR] (read/write)
0x7FFF9	=>	BAR - Geographic address (read)

## 2.7 Parts of the VME64x-chip

### 2.7.1 Defined Configuration ROM (CR)

The definition of the CR is made in the VME64x-specification (10.2.1 The defined CR area, page 39 and Table 10-12, page 53).

- Checksum (0x03): see VME64-specification (Table 2-32, page 55)  
**not calculated yet, to be done in cr.mif!!!**
- Length of ROM (0x07..0x0F): see VME64-specification (Table 2-32, page 55)  
**not calculated yet, to be done in cr.mif!!!**
- Configuration ROM data access width (0x13): see VME64-specification (Table 2-32, page 55)  
**0x81 => “Only use D08(O), every fourth byte“.**
- CSR data access width (0x17): see VME64-specification (Table 2-32, page 55)  
**0x81 => “Only use D08(O), every fourth byte“.**
- CR/CSR space specification ID (0x1B): see VME64x-specification (Rule 10.3, page 39)  
**0x02 => VME64x.**
- Manufactor's ID (0x27..0x2F): see VME64-specification (Table 2-32, page 56)  
**0x00.**
- Board ID (0x33..0x3F): see VME64-specification (Table 2-32, page 56)  
**not fixed yet, has to be defined for all boards of the GT-system!!**
- Revision ID (0x43..0x4F): see VME64-specification (Table 2-32, page 56)  
**not fixed yet, has to be defined for all boards of the GT-system!!**
- Program ID (0x7F): see VME64-specification (Table 2-32, page 56)  
**0x01 => “No program, ID ROM only“.**
- Offset to BEG\_USER\_CR (0x83..0x8B): see VME64x-specification (Table 10-12, page 53)  
**0x01003 => used for chip\_id- and version-register.**
- Offset to END\_USER\_CR (0x8F..0x97): see VME64x-specification (Table 10-12, page 53)  
**0x0101F => used for chip\_id- and version-register.**
- Offset to BEG\_CRAM (0x9B..0xA3): see VME64x-specification (Table 10-12, page 53)  
**0x03003 => used for future applications.**
- Offset to END\_CRAM (0xA7..0xAF): see VME64x-specification (Table 10-12, page 53)  
**0x037FF => used for future applications.**
- Offset to BEG\_USER\_CSR (0xB3..0xBB): see VME64x-specification (Table 10-12, page 53)  
**0x05003 => used for TEST\_OUT-selection register..**
- Offset to END\_USER\_CSR (0xBF..0xC7): see VME64x-specification (Table 10-12, page 53)  
**0x0502F.**
- Offset to BEG\_SN (0xCB..0xD3): see VME64x-specification (Table 10-12, page 53)  
**0x01023 => part of USER\_CR, contains the “serial number”.**
- Offset to END\_SN (0xD7..0xDF): see VME64x-specification (Table 10-12, page 53)  
**0x01033.**
- Slave characteristics parameter (0xE3): see VME64x-specification (Table 10-1, page 40)  
**0x00.**
- Master characteristics parameter (0xEB): see VME64x-specification (Table 10-2, page 40)  
**0x00.**
- CRAM\_ACCESS\_WIDTH (0xFF): see VME64x-specification (Table 10-10, page 49)

**0x81 => “Only use D08(O), every fourth byte“.**

- Function 0 and 1 DAWPR (0x103..0x107): see VME64x-specification (Table 10-3, page 42)

**0x83 => “Accepts D16 or D08(EO) cycles“.**

- Function 0 AMCAP (0x123..0x13F): see VME64x-specification (Table 10-5, page 44)

**0x0000 0000 0000 2200 => AM=0x0D and 0x09 “extended data access“ - single access.**

- Function 1 AMCAP (0x143..0x15F): see VME64x-specification (Table 10-5, page 44)

**0x0000 0000 0000 8800 => AM=0x0F and 0x0B “standard data access“ - single access.**

- Function 0 and 1 ADEM (0x623..0x63F): see VME64x-specification (Table 10-4, page 43)

**0xFE000000 => "mask bits 31-25=1".**

## 2.7.2 Defined Control/Status Register (CSR)

The definition of the CSR is made in the VME64x-specification (10.2.2 The defined CSR area, page 45 and Table 10-13, page 55).

- **Base Address Register (BAR)** (0x7FFFF): see VME64x-specification (Table 10-13, page 55), set with geographical address or amnesia address.
- **Bit Set Register (BSR)** (0x7FFF8): see VME64x-specification (Table 10-13, page 55), for setting see Table 10-6, page 45.
- **Bit Clear Register (BCR)** (0x7FFF7): see VME64x-specification (Table 10-13, page 55), for setting see Table 10-7, page 46.

BCR, BSR bits:

- Bit 7: EN/DIS RESET\_MODE
- Bit 4: EN/DIS MODULE
- Bit 3: EN/DIS BERR FLAG

- **Function 1 ADER** (0x7FF73..0x7FF7F): see VME64x-specification (Table 10-13, page 55), used for address relocation with Function 1 ADEM and Function 1 AMCAP (see Table 10-8, page 47).
- **Function 0 ADER** (0x7FF63..0x7FF6F): see VME64x-specification (Table 10-13, page 55), used for address relocation with Function 0 ADEM and Function 0 AMCAP (see Table 10-8, page 47).

## 2.7.3 Chip\_ID and version ROM space

A user configuration ROM is implemented for the “chip\_ID“ and “version“ of the VME64x-chip of the board. It is located at the addresses 0x01003-0x0101F, size is 8 bytes, part of the USER\_CR.

## 2.7.4 Serial Number ROM space

A user configuration ROM is implemented for the “serial number“ of the board. It is located at the addresses 0x01023-0x01033, size is 5 bytes (PSBxx), part of the USER\_CR.

## 2.7.5 USER\_CSR space

A “user command status register (USER\_CSR)” is implemented for the „TEST\_OUT-selection-registers“.

### 2.7.5.1 TEST\_OUT registers

TEST\_OUT-registers are used to select internal signals to a certain TEST\_OUT-pin. There are four TEST\_OUT-pins implemented, each pin can be driven by 1 of 16 internal signals. So 4 bits are used for the code of the selection of internal signals. We have two registers, one for the selection of TST\_OUT\_1 and TST\_OUT\_2, the other for TST\_OUT\_3 and TST\_OUT\_4.

### 2.7.5.2 Test-signal-definition

Code for the selection of internal signals for TEST\_OUT-pins:

<b>sel_test_out_x[3:0]</b>	<b>→ testsignal-name</b>
0000	TST_CLK_VME
0001	D08_O_I
0010	D16_EO_I
0011	LD_CNT
0100	BLT_CNT
0101	CNT_EN
0110	DTACK_CR_CSR
0111	RD_CR
1000	ASCYC_I
1001	ASSYNC_I
1010	ASPULS_I
1011	DTACK_EXT_I
1100	BERR_EXT_I
1101	D32_EO_I
1110	D08_E_I
1111	MODULE_ENABLED

### 2.7.5.3 Registerdefinition

**0x05003 => sel\_test\_out\_12 (write/read)**

D7	D6	D5	D4	D3	D2	D1	D0
<b>sel_test_out_2[3:0]</b>				<b>sel_test_out_1[3:0]</b>			

**0x05007 => sel\_test\_out\_34 (write/read)**

D7	D6	D5	D4	D3	D2	D1	D0
<b>sel_test_out_4[3:0]</b>				<b>sel_test_out_3[3:0]</b>			

## 2.7.6 CRAM space

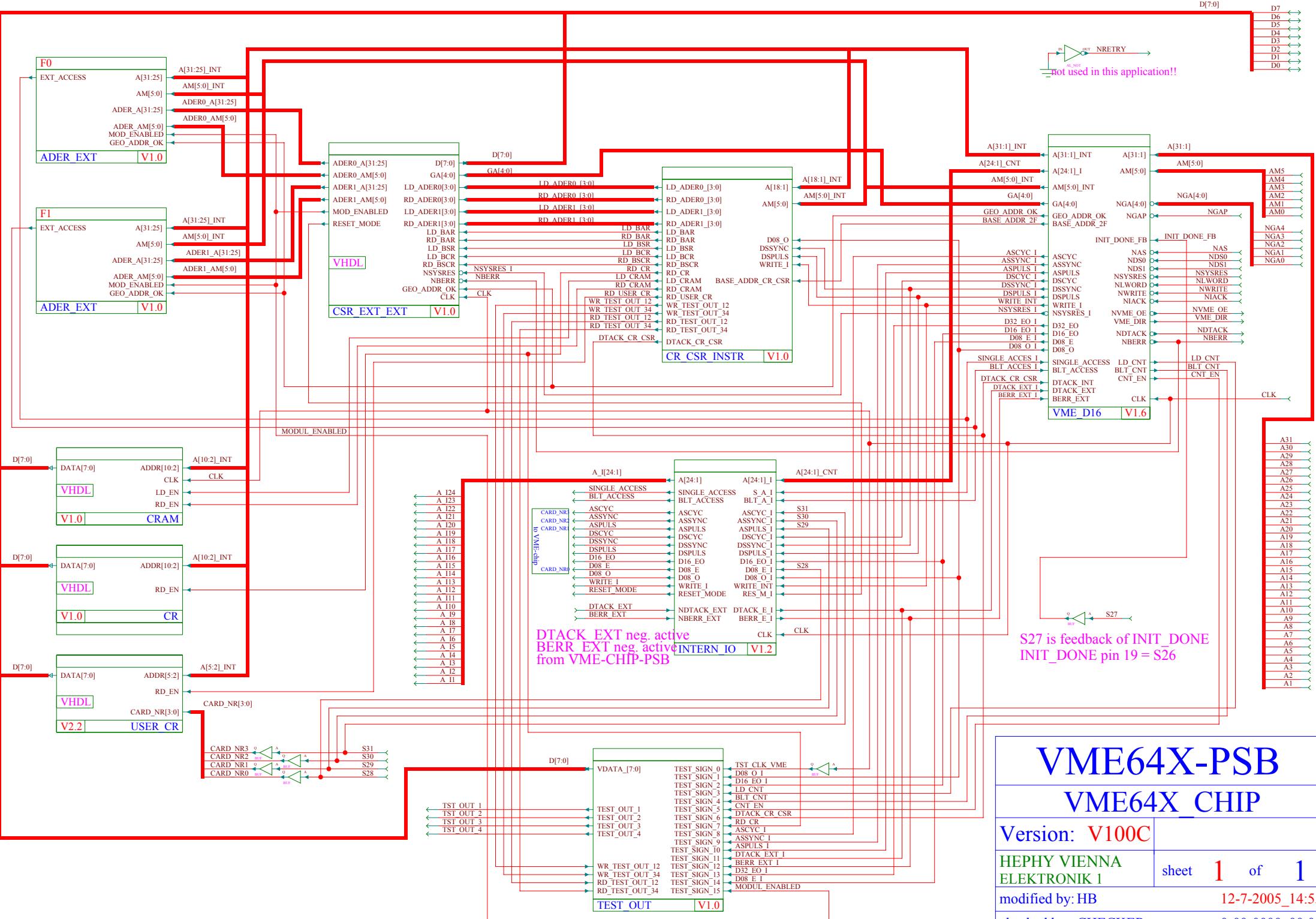
The configuration RAM (CRAM) is defined as a RAM for special purpose. The size is 512 bytes. The CRAM is located at addresses 0x03003..0x037FF.

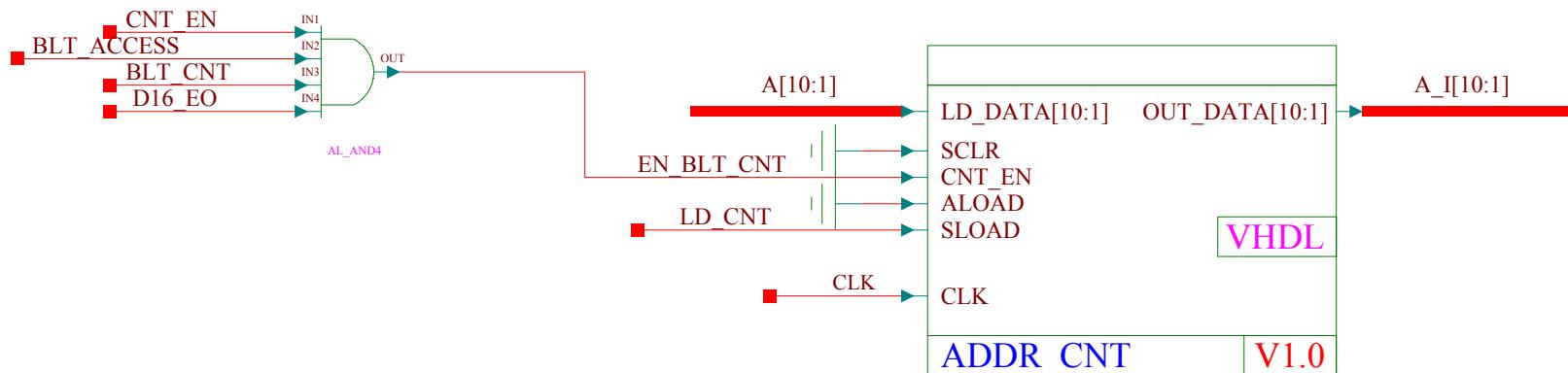
The contains of the CRAM has to be defined!!!

## 3 Softwareguide for the VME64x Interface

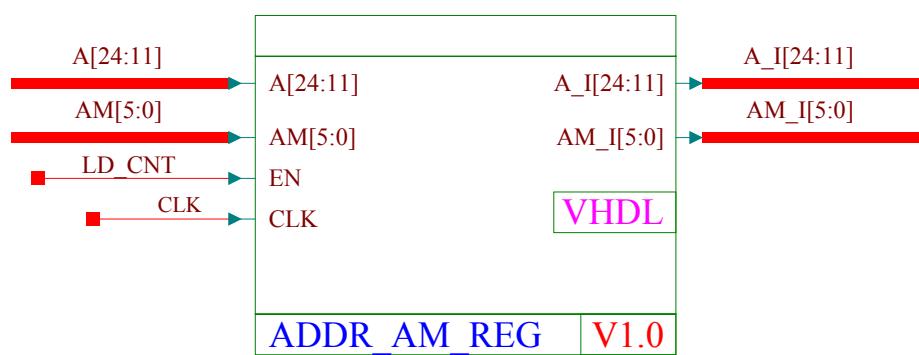
### 3.1 Module enable

After power-up the module is disabled through the default value of the “ENABLE MODULE”-bit of the BitSet-register in the CommandStatusRegister (CSR) of VME64x. To enable the module, one has to set bit 4 in the CSR, that means to write 0x10 to address 0x7FFF with AM=0x2F.





NLD\_ADDR freezes addresses during VME cycle

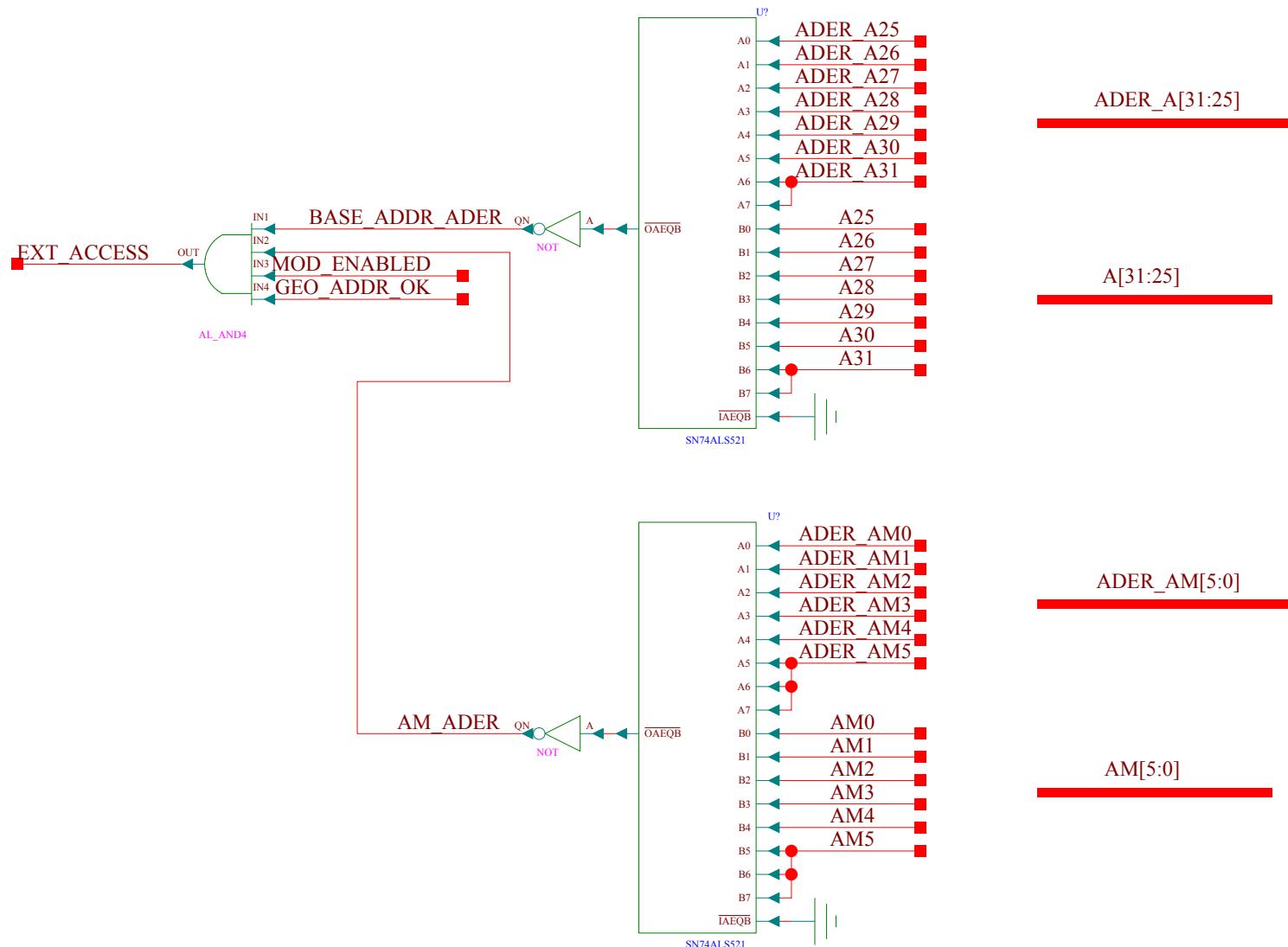


A[24:1]  
A\_I[24:1]  
AM[5:0]  
AM\_I[5:0]

## VME64X-CHIP ADDRESSES\_AM

Version:	V1.1	
HEPHY VIENNA ELEKTRONIK 1		sheet 1 of 1
modified by HB	9-23-2005 10:45	

checked by: CHECKER 0-00-0000 00:00



VME64X-CHIP

ADER\_EXT

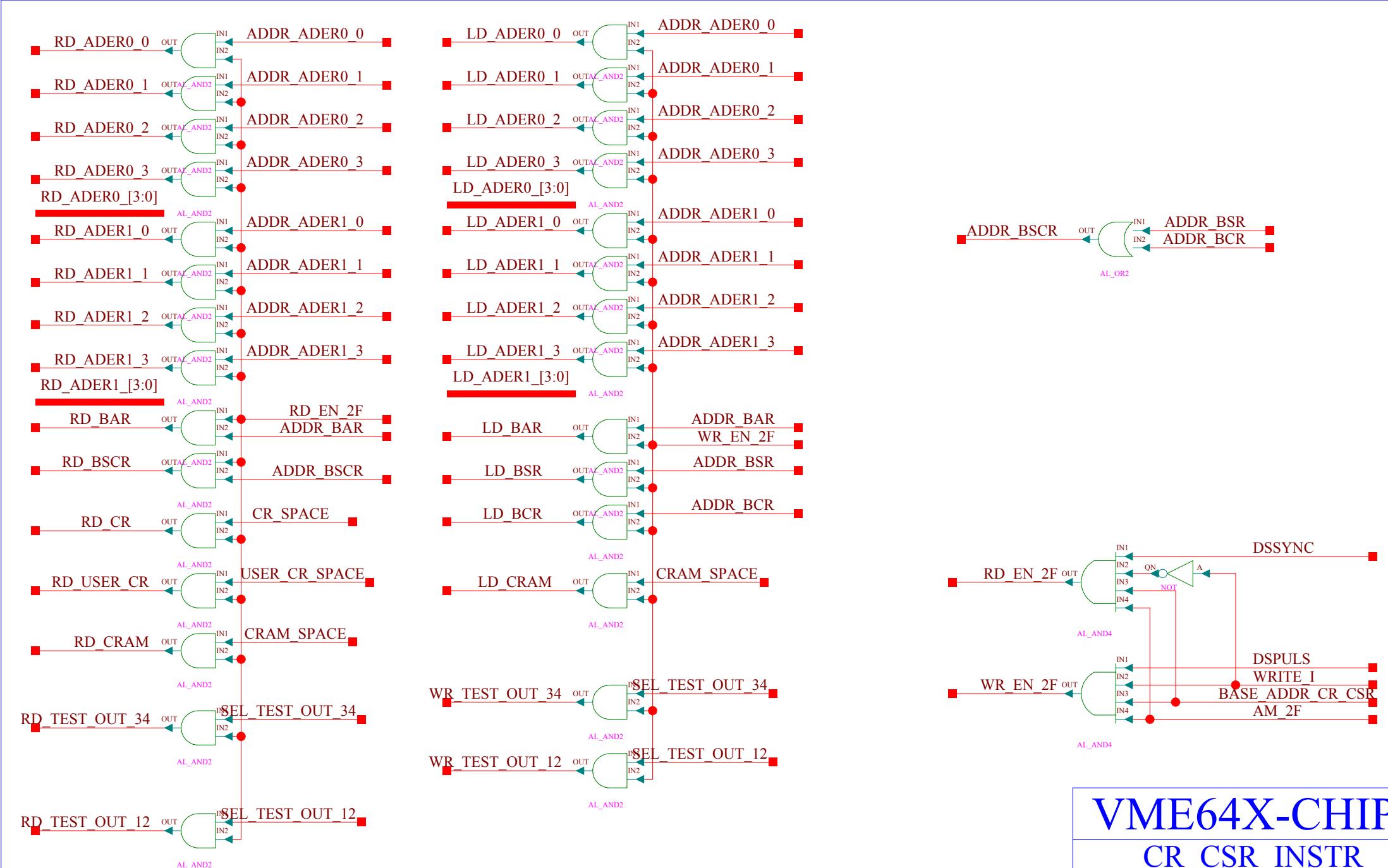
Version: V1.0

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 1

modified by HB 8-29-2005 9:32

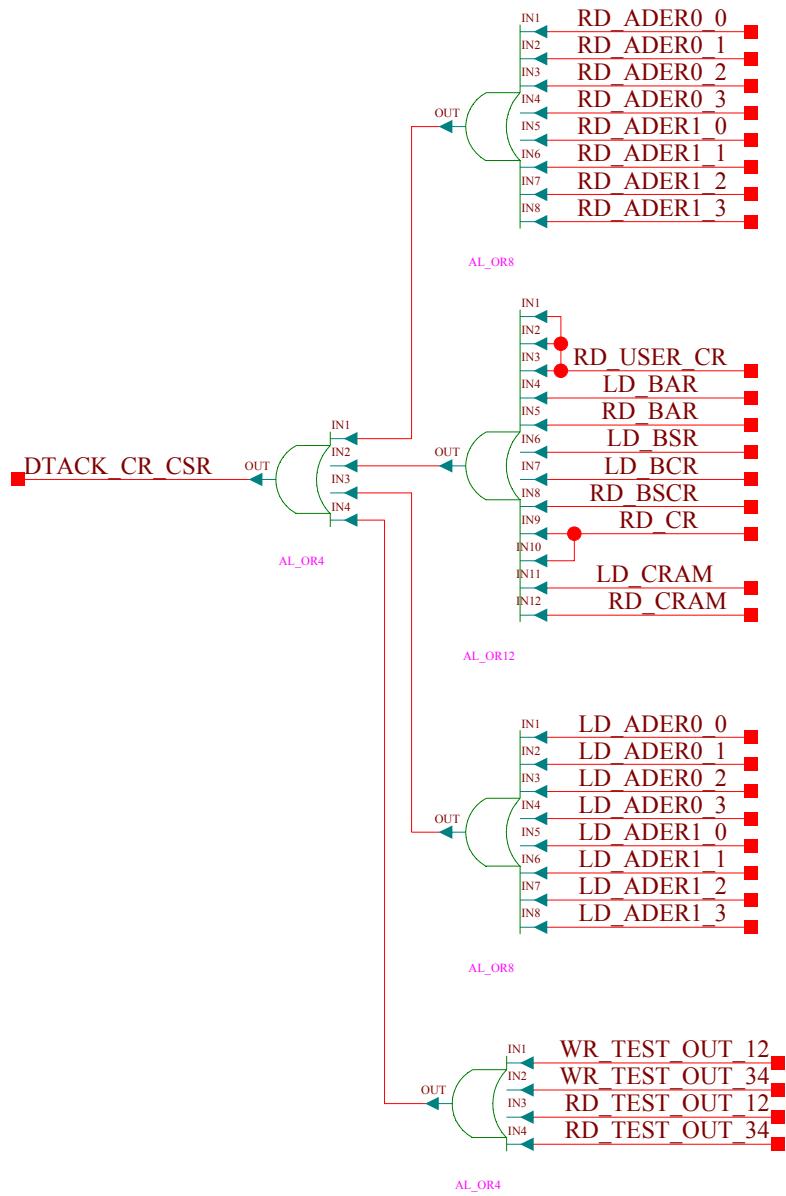
checked by: CHECKER 0-00-0000 00:00



## VME64X-CHIP

### CR\_CSR\_INSTR

Version:	V1.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 5
modified by HB	8-26-2005 13:54
checked by: CHECKER	0-00-0000 00:00



no BERR for CR/CSR access!!

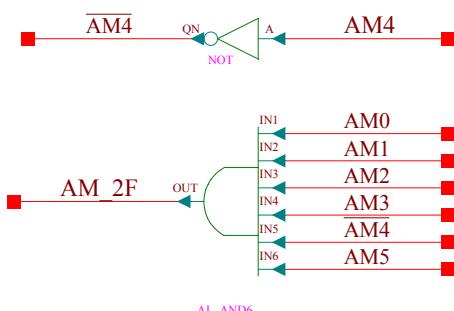
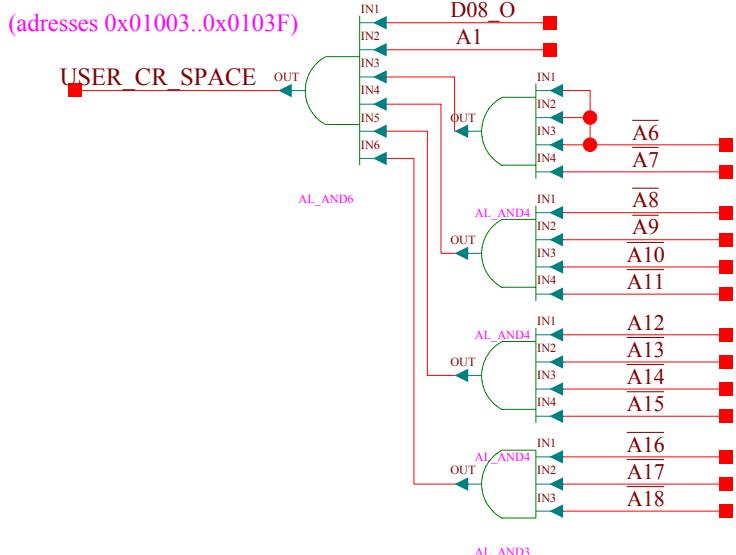
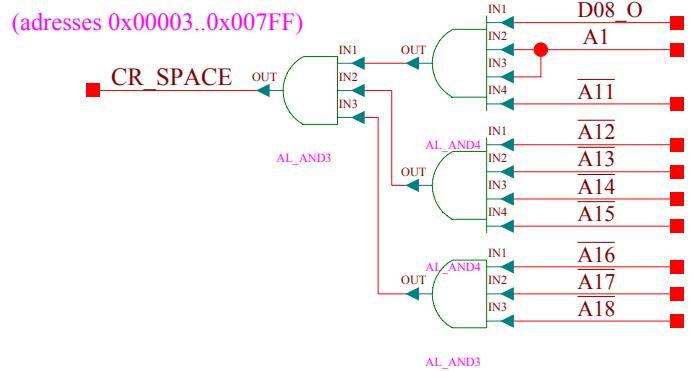
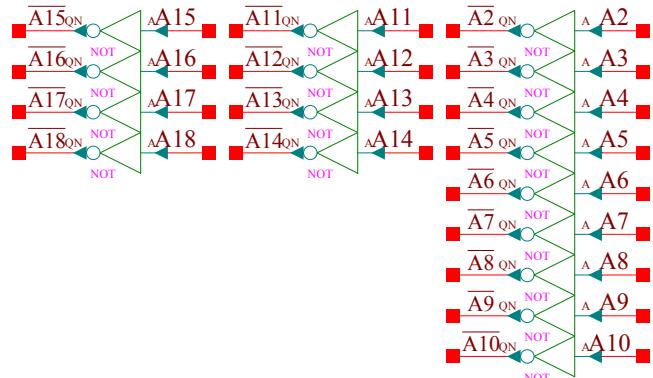
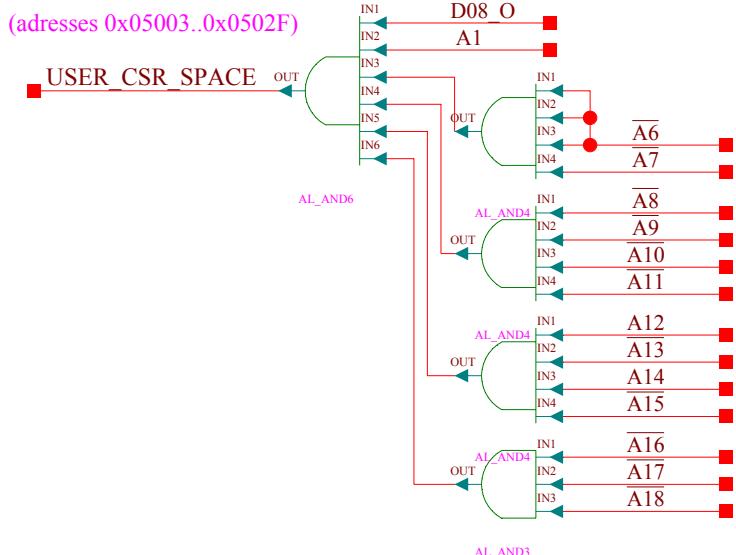
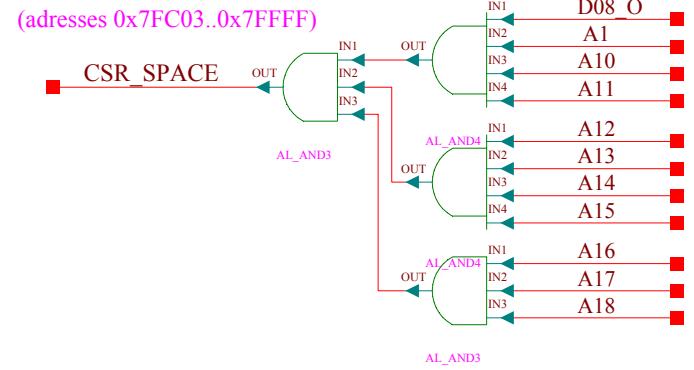
## VME64X-CHIP CR\_CSR\_INSTR

Version: V1.0	
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HEPHY VIENNA ELEKTRONIK 1	sheet 2 of 5
------------------------------	--------------

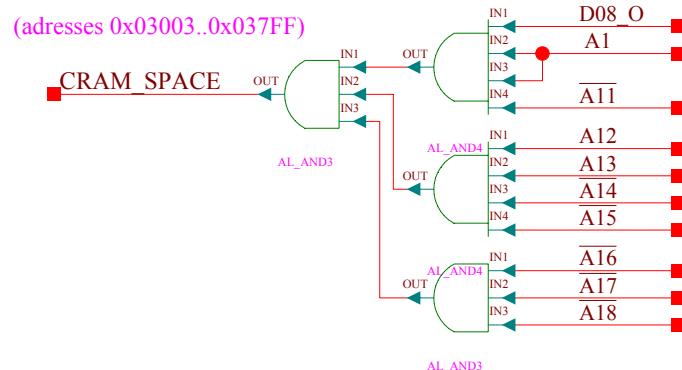
modified by HB	8-26-2005 13:54
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checked by: CHECKER	0-00-0000 00:00
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A[18:1]

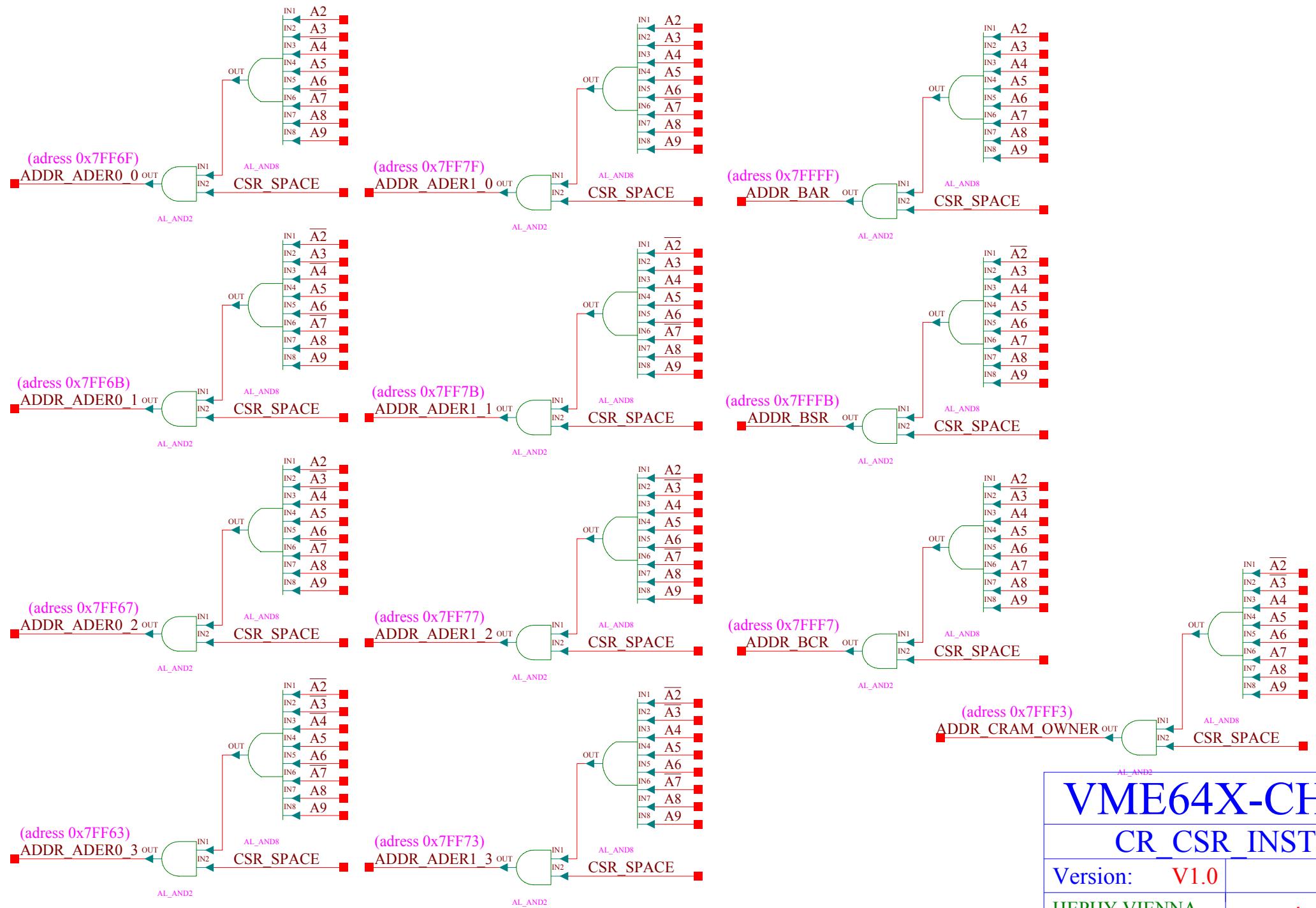
AM[5:0]



## VME64X-CHIP

### CR\_CSR\_INSTR

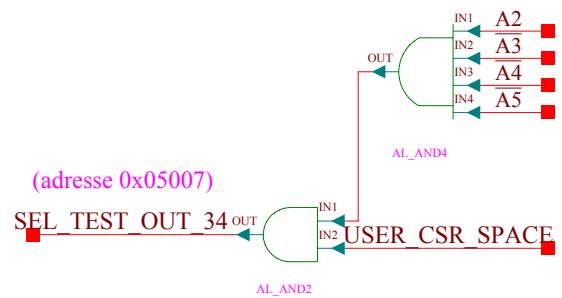
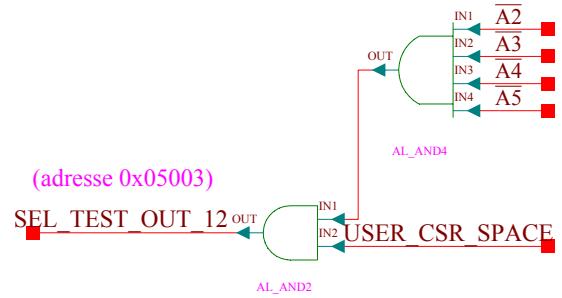
Version:	V1.0
HEPHY VIENNA ELEKTRONIK 1	sheet 3 of 5
modified by HB	8-26-2005 13:54
checked by: CHECKER	0-00-0000 00:00



## VME64X-CHIP

### CR\_CSR\_INSTR

Version:	V1.0
HEPHY VIENNA ELEKTRONIK 1	sheet 4 of 5
modified by HB	8-26-2005 13:54
checked by: CHECKER	0-00-0000 00:00



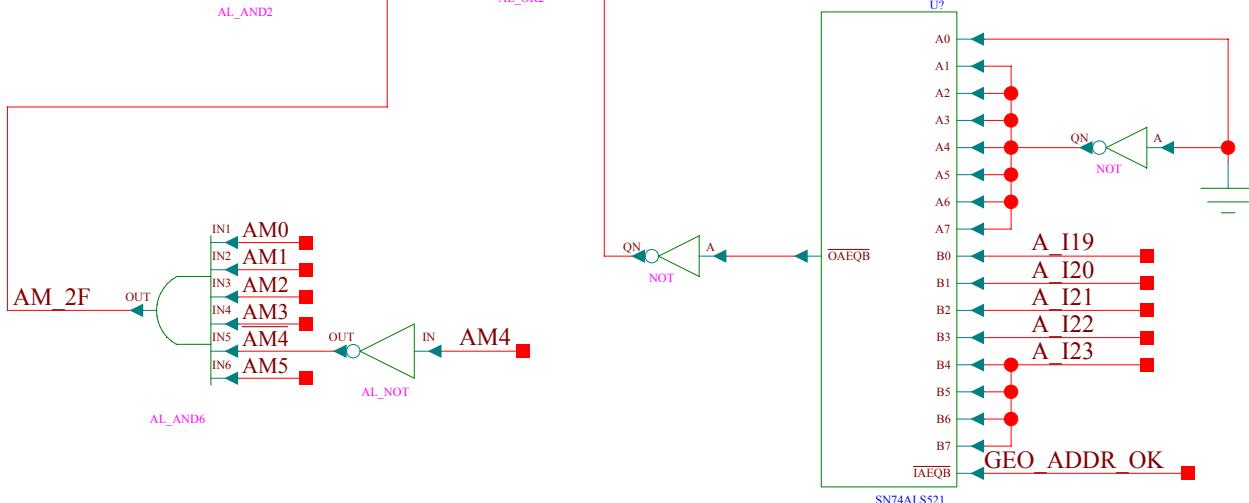
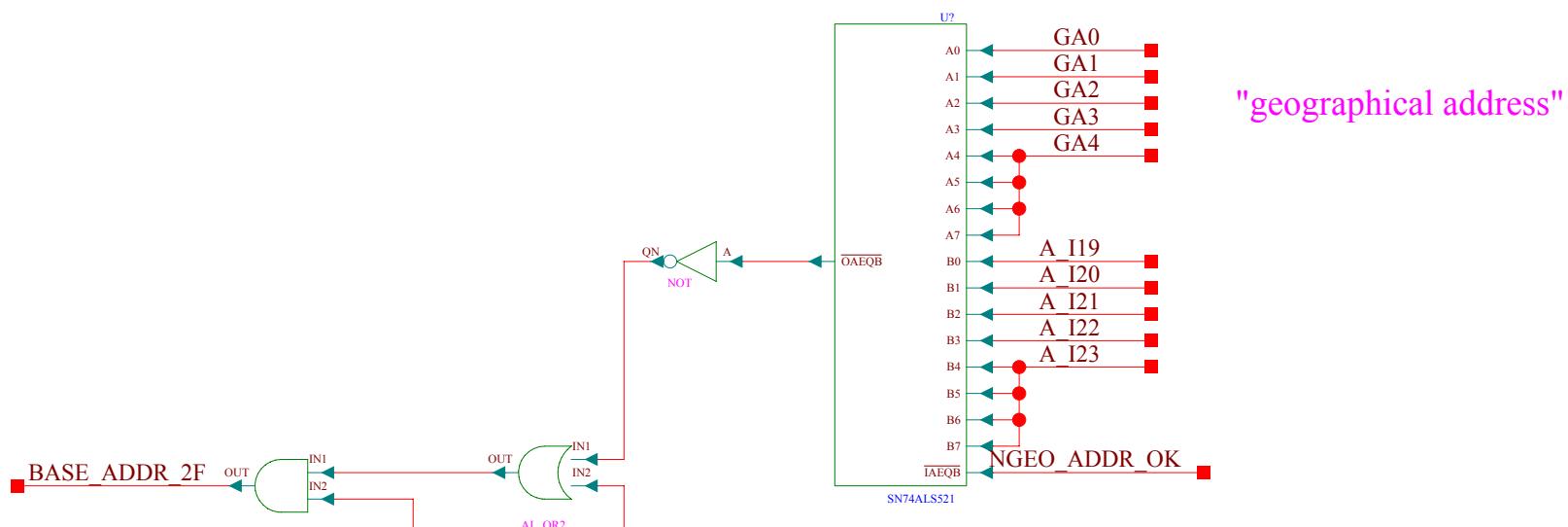
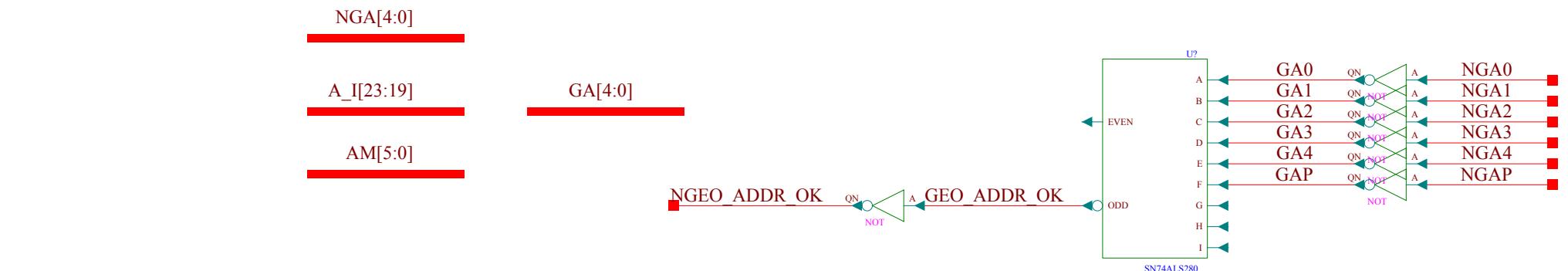
VME64X-CHIP  
CR\_CSR\_INSTR

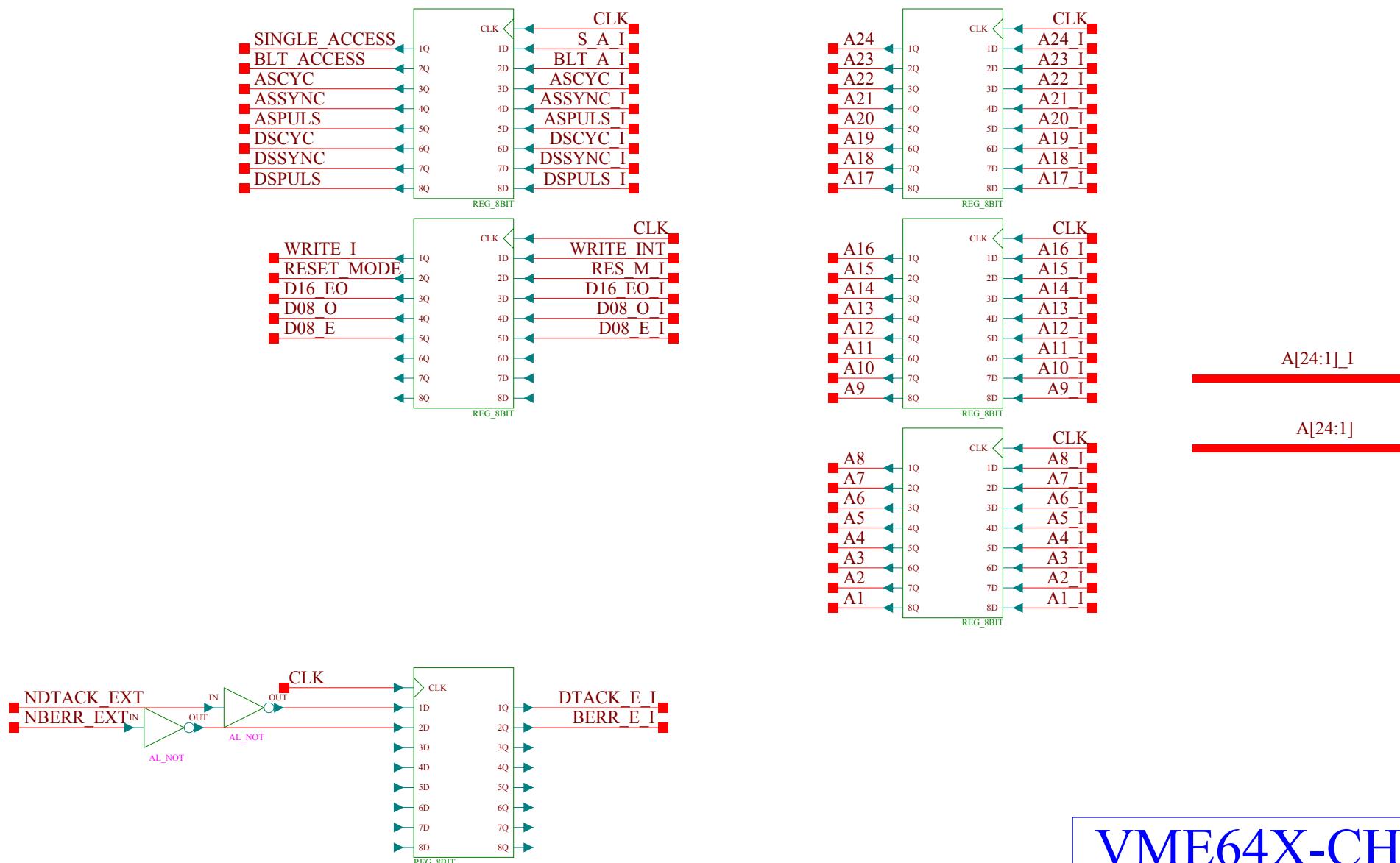
Version: V1.0	
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HEPHY VIENNA ELEKTRONIK 1	sheet 5 of 5
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modified by HB	8-26-2005 13:54
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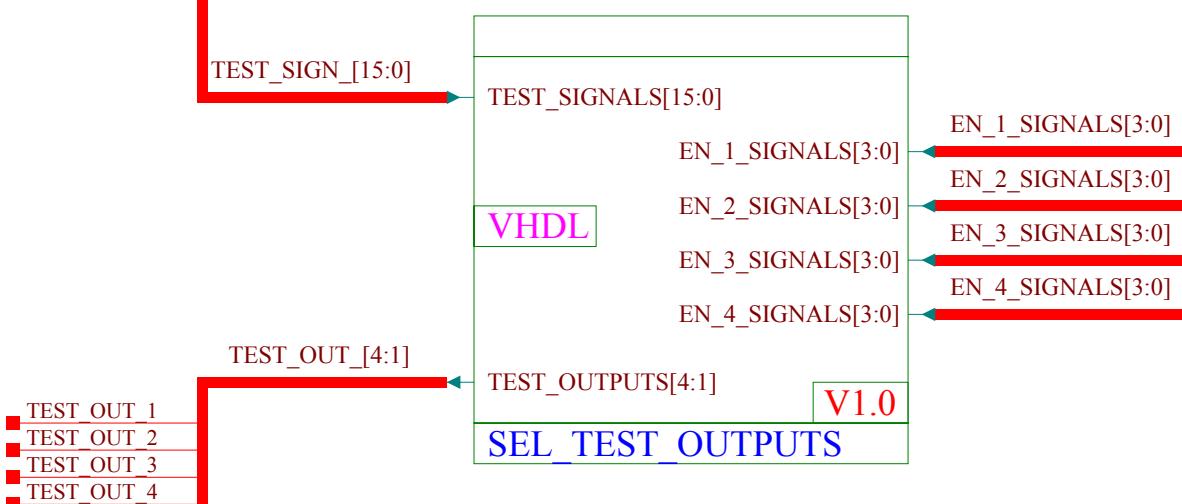
checked by: CHECKER	0-00-0000 00:00
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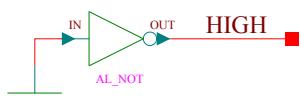
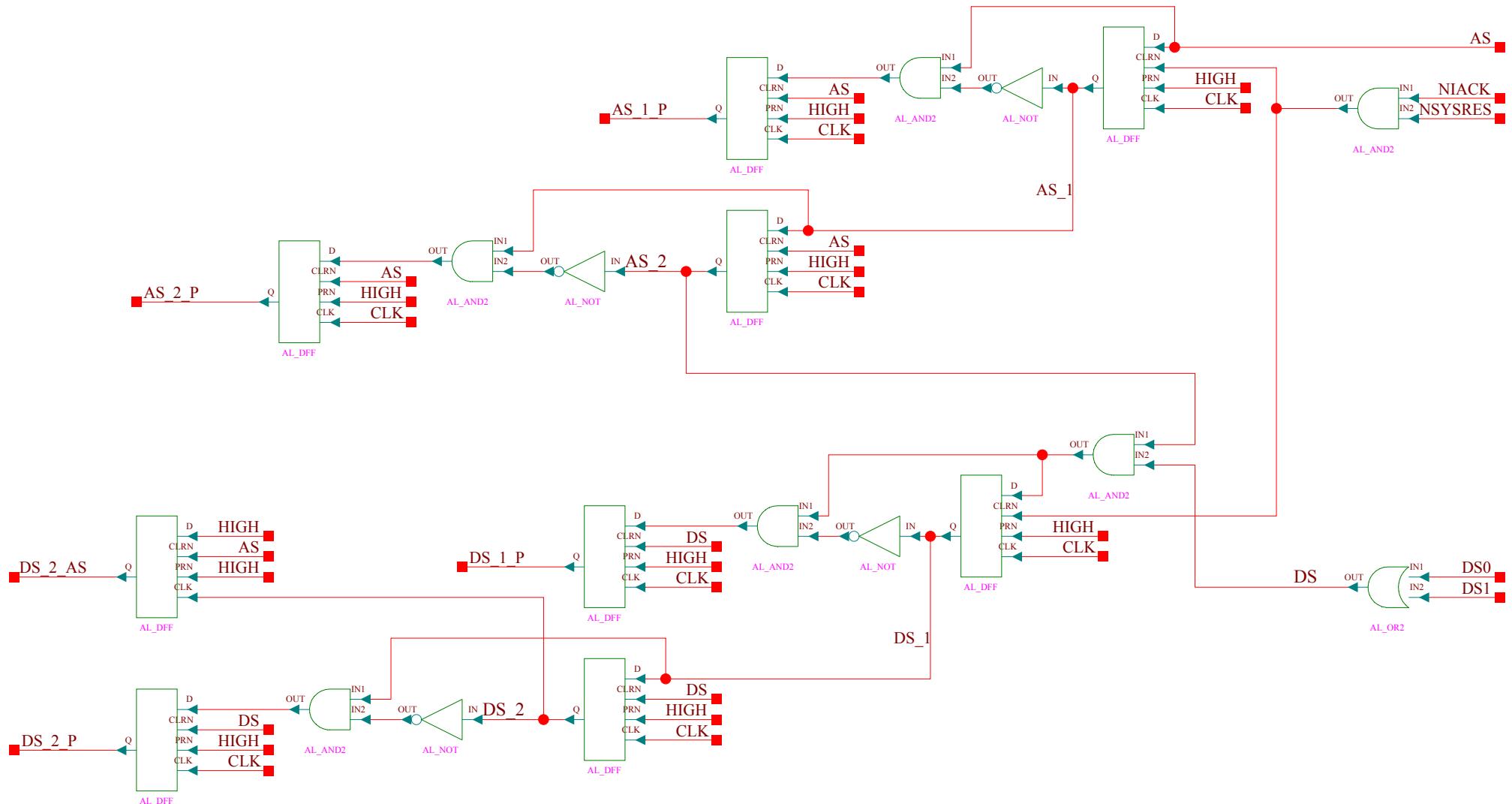


## VME64X-CHIP INTERN\_IO

Version: V1.2	
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by HB checked by: CHECKER	10-20-2005 9:17 0-00-0000 00:00



<b>VME64X-CHIP</b>	
TEST OUT	
Version:	V1.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by HB 8-29-2005 11:07	
checked by: CHECKER 0-00-0000 00:00	



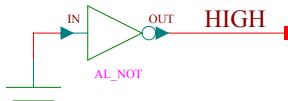
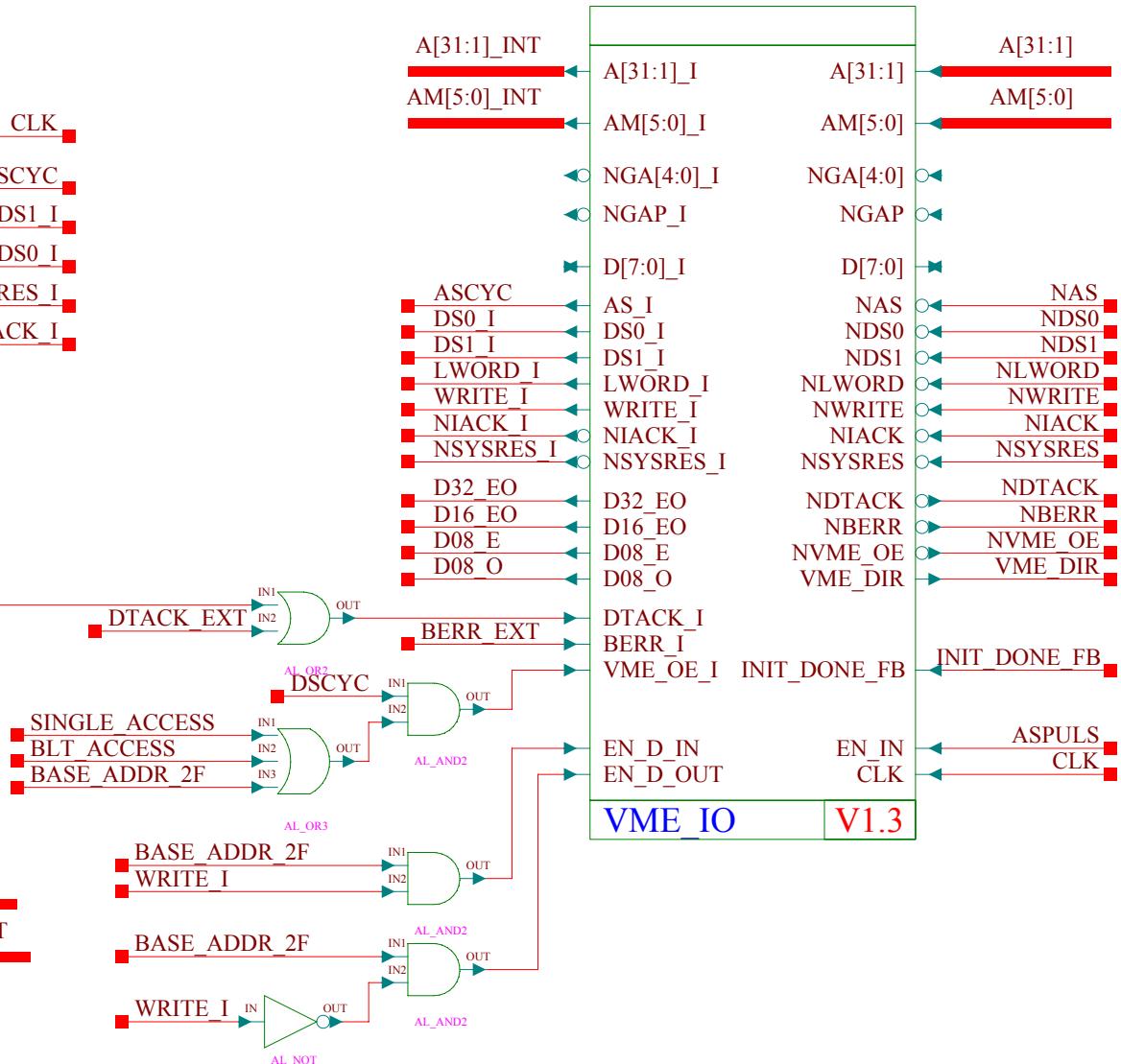
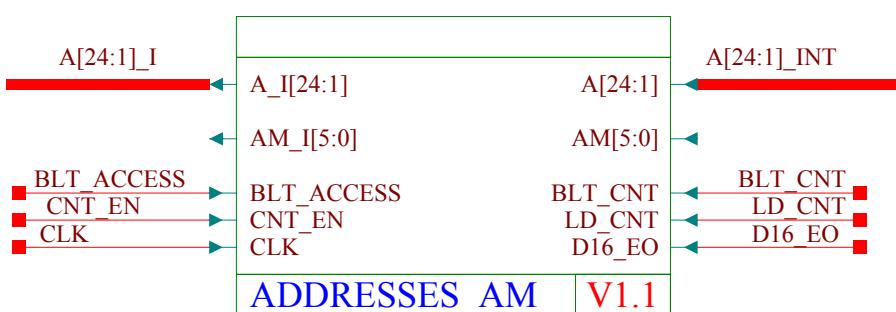
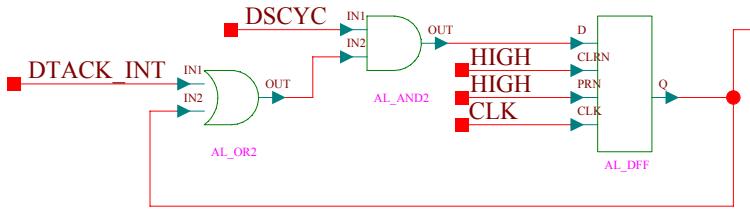
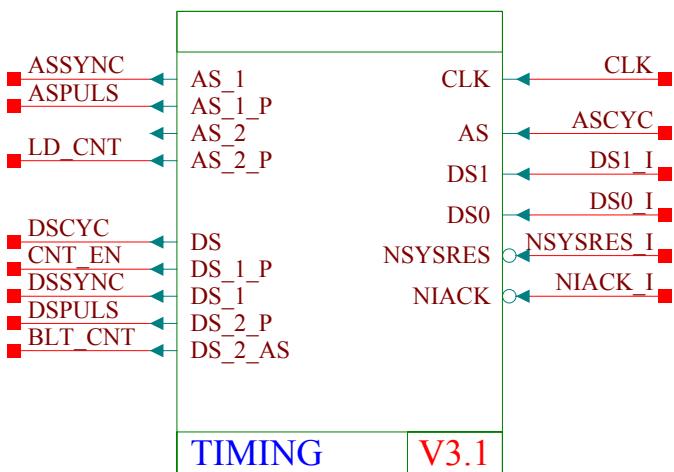
## VME64X-CHIP TIMING

Version: V3.1

HEPHY VIENNA  
ELEKTRONIK 1 sheet 1 of 1

modified by HB 10-7-2005 14:18

checked by: CHECKER 0-00-0000 00:00

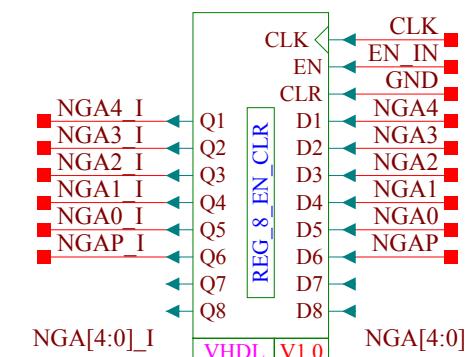
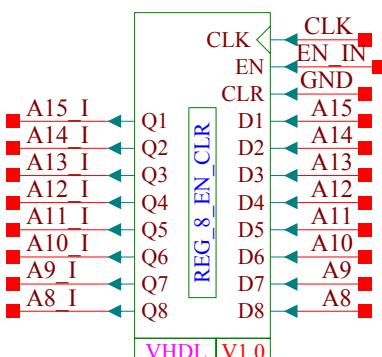
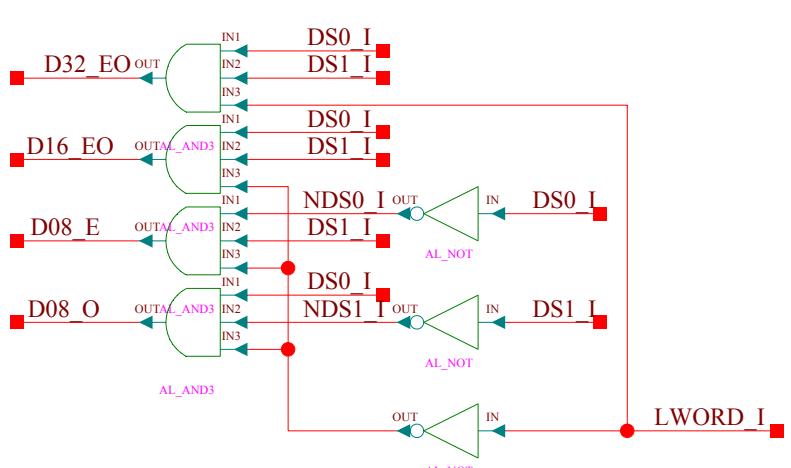
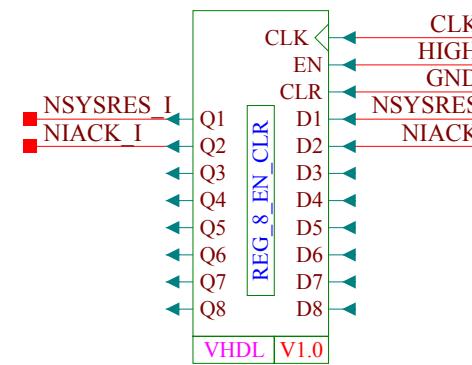
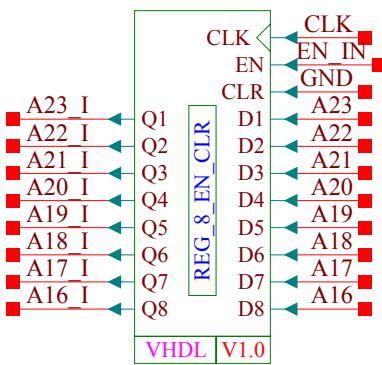
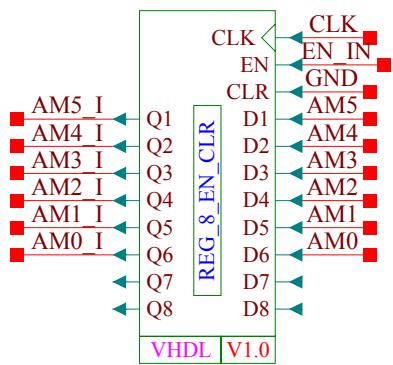
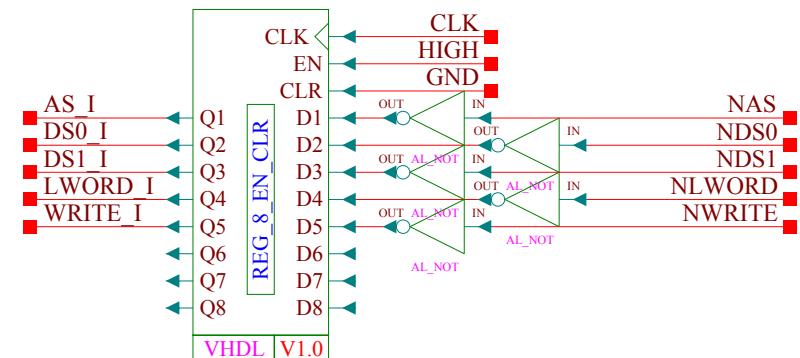
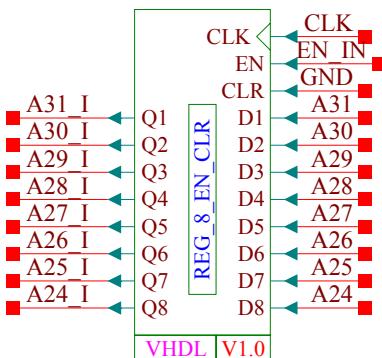
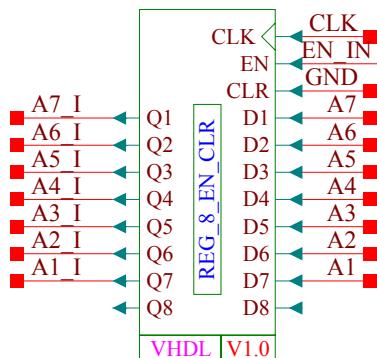


**A[31:25]\_INT**

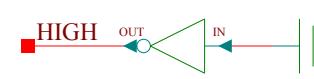
## VME D16

Version: <b>V1.6</b>	
HEPHY VIENNA ELEKTRONIK 1	sheet <b>1</b> of <b>1</b>
modified by HB	12-7-2005 14:57

checked by: CHECKER 0-00-0000 00:00



A[31:1]\_I      A[31:1]  
AM[5:0]\_I      AM[5:0]



# VME64X-CHIP

## VME\_IO

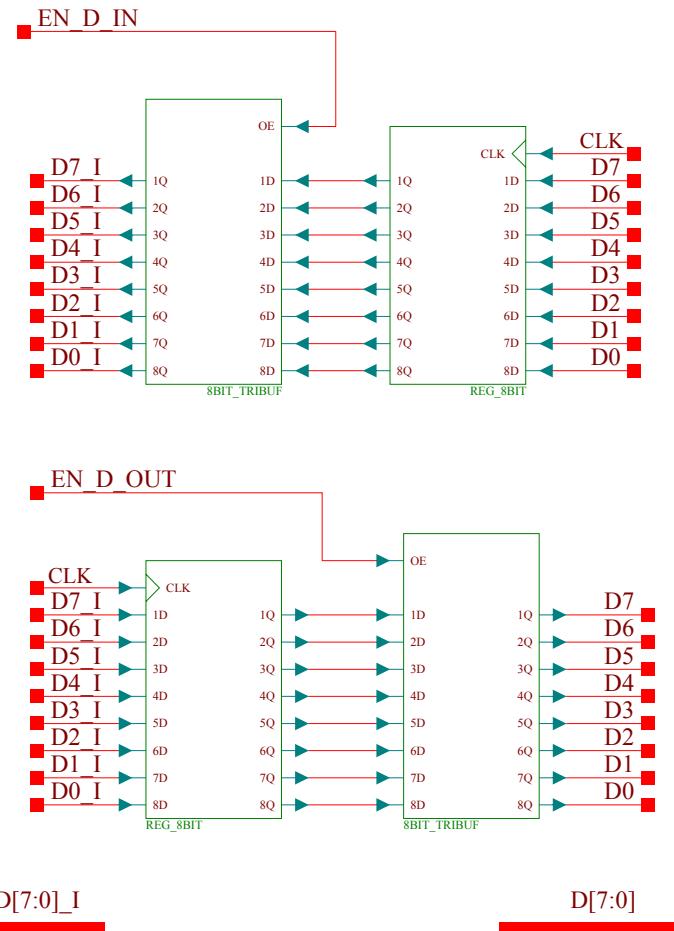
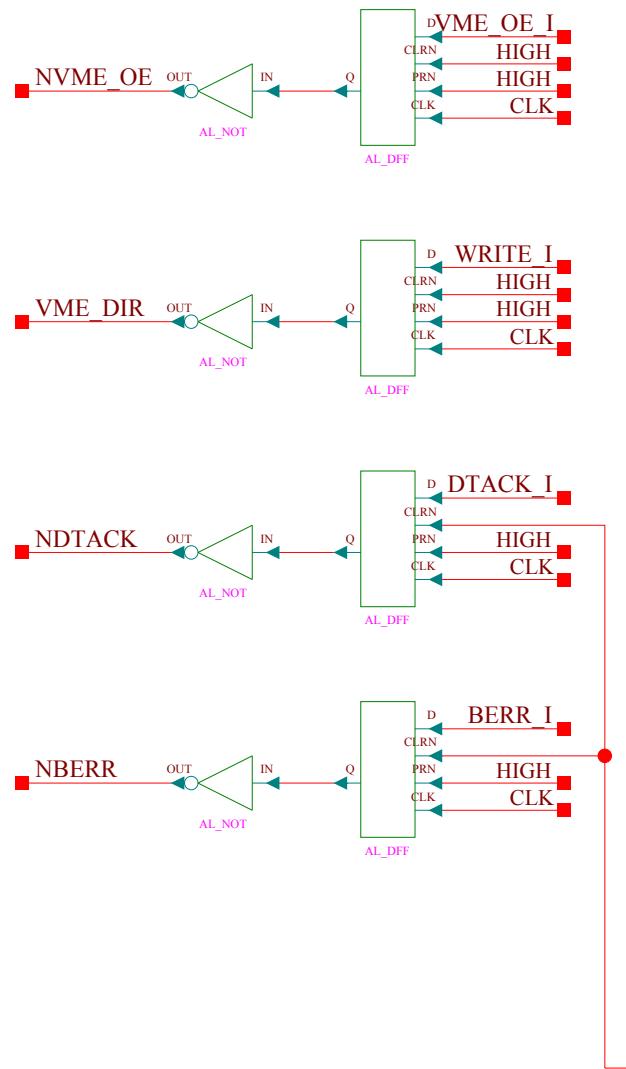
Version: V1.3

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 2

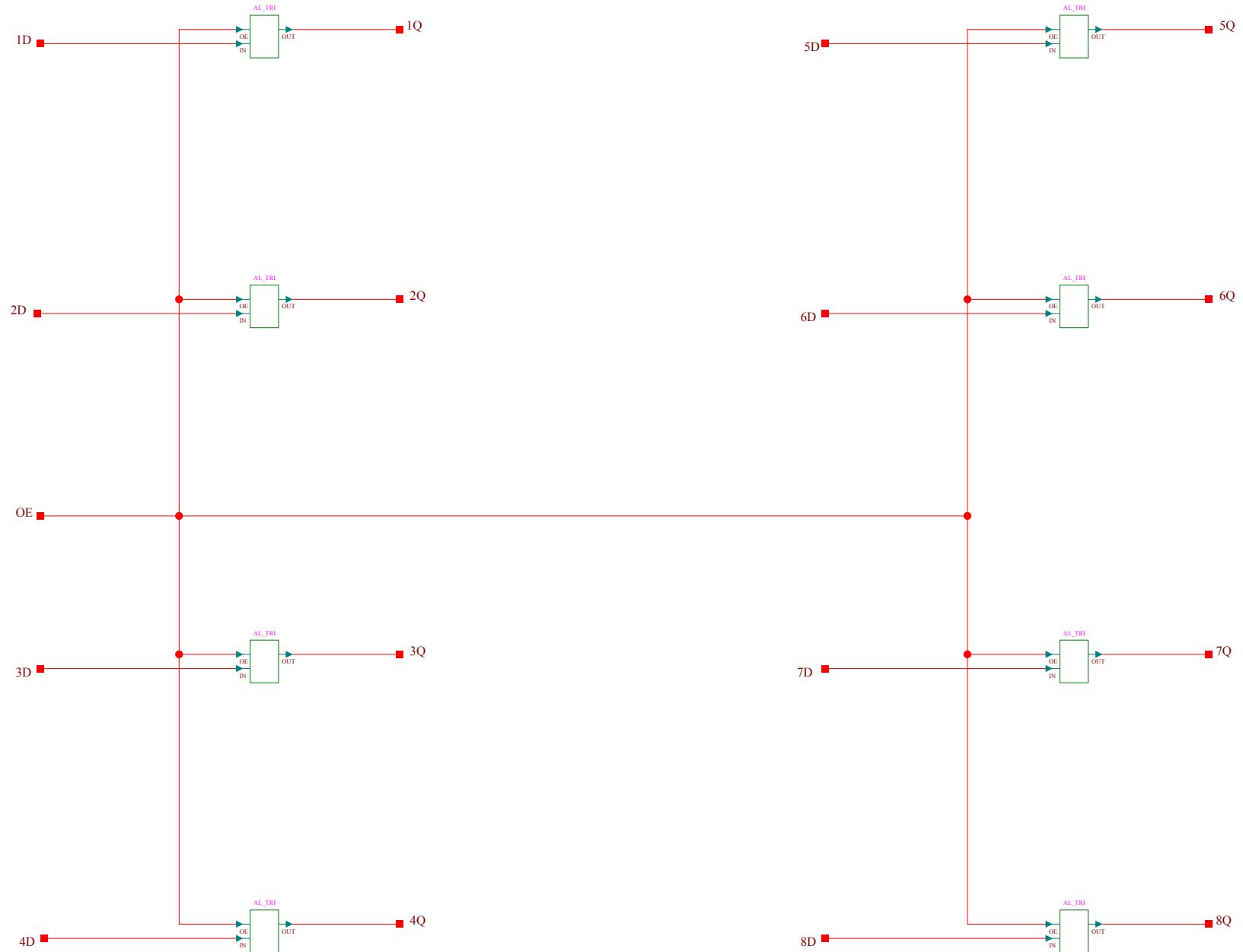
modified by HB 10-21-2005 14:41

checked by: CHECKER 0-00-0000 00:00



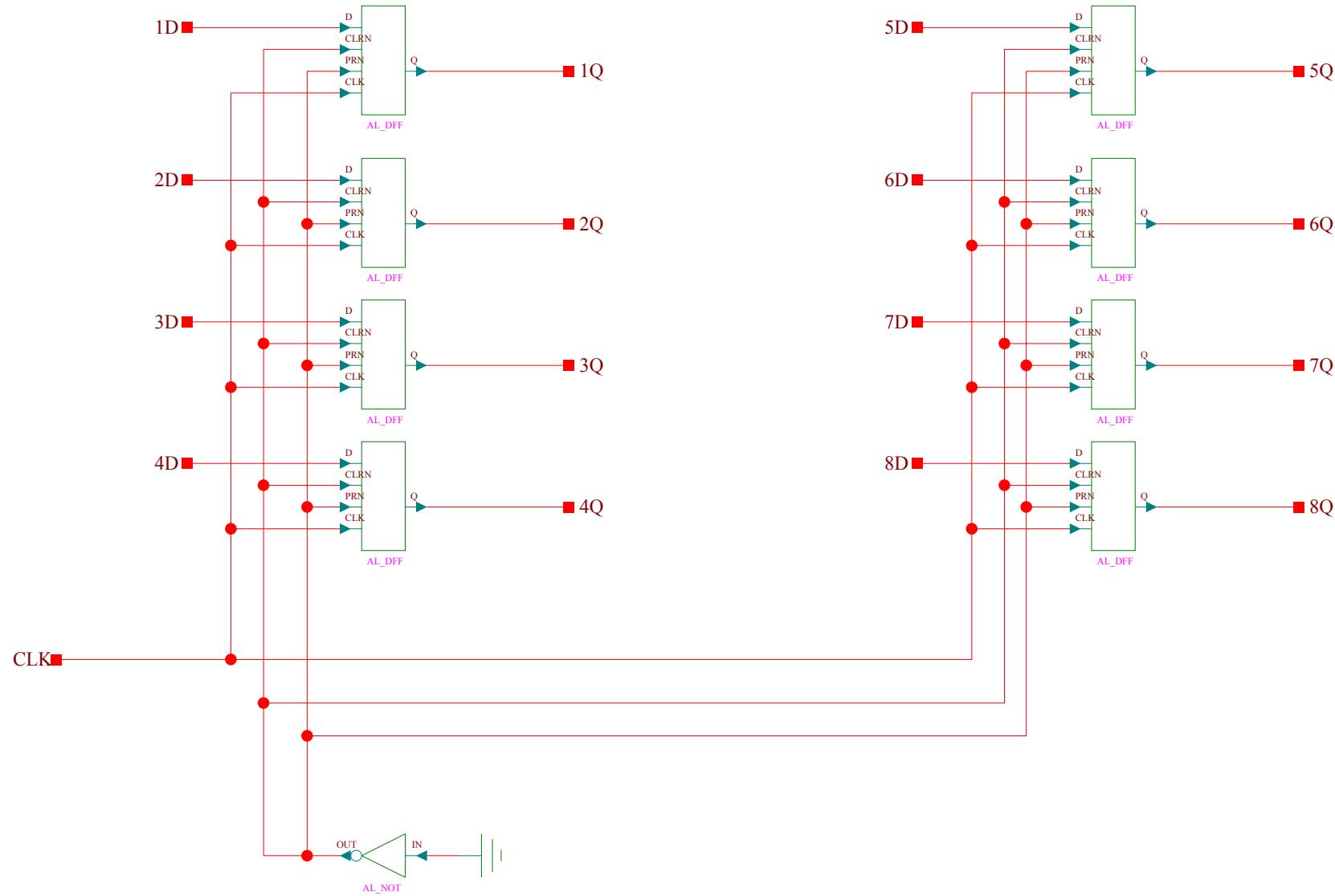
VME64X-CHIP	
VME_IO	
Version:	V1.3
HEPHY VIENNA ELEKTRONIK 1	sheet 2 of 2
modified by HB	10-21-2005 14:41
checked by: CHECKER	0-00-0000 00:00

# 8bit\_tribuf



# reg\_8bit

8-bit register generated by LAB3



```
-----□
--□
-- LOGIC CORE: GTL-module vme64x interface chip logic      --□
-- MODULE NAME: addr_am_reg                                --□
-- INSTITUTION: Hephys Vienna                            --□
-- DESIGNER: H. Bergauer                                --□
--□
-- VERSION: V1.0                                         --□
-- DATE: 08 2005                                         --□
--□
-- FUNCTIONAL DESCRIPTION:                               --□
-- input register for addresses and address modifier    --□
--□
-----□
LIBRARY ieee;□
USE ieee.std_logic_1164.ALL;□
LIBRARY lpm;□
USE lpm.lpm_components.ALL;□
□
ENTITY addr_am_reg IS□
  PORT(□
    clk : IN      STD_LOGIC;□
    en : IN      STD_LOGIC;□
    a : IN      STD_LOGIC_VECTOR(24 DOWNTO 11);□
    am : IN      STD_LOGIC_VECTOR(5 DOWNTO 0);□
    a_i : OUT     STD_LOGIC_VECTOR(24 DOWNTO 11);□
    am_i : OUT     STD_LOGIC_VECTOR(5 DOWNTO 0));□
END addr_am_reg;□
□
ARCHITECTURE rtl OF addr_am_reg IS□
BEGIN□
  □
  -- input register for addresses □
  addr_reg: lpm_ff□
  GENERIC MAP  (LPM_WIDTH => 14)□
  PORT MAP  (data => a, □
    clock => clk,□
    enable => en,□
    q => a_i);□
  □
  -- input register for address modifier □
  am_reg: lpm_ff□
  GENERIC MAP  (LPM_WIDTH => 6)□
  PORT MAP  (data => am, □
    clock => clk,□
    enable => en,□
    q => am_i);□
  □
END ARCHITECTURE rtl;□
```

```

-----
--                                         □
-- LOGIC CORE: GTL-module vme64x interface chip logic    --□
-- MODULE NAME: addr_cnt                                --□
-- INSTITUTION: Hephzibah Vienna                         --□
-- DESIGNER: H. Bergauer                                --□
--                                         --□
-- VERSION: V1.0                                         --□
-- DATE: 08 2005                                         --□
--                                         --□
-- FUNCTIONAL DESCRIPTION:                            --□
-- addresses counter for BLT                         --□
--                                         --□
-----□
LIBRARY ieee;□
USE ieee.std_logic_1164.ALL;□
LIBRARY lpm;□
USE lpm.lpm_components.ALL;□
□
ENTITY addr_cnt IS□
  PORT(□
    clk : IN      STD_LOGIC;□
    cnt_en : IN    STD_LOGIC;□
    sclr : IN     STD_LOGIC;□
    aload : IN     STD_LOGIC;□
    sload : IN     STD_LOGIC;□
    ld_data : IN    STD_LOGIC_VECTOR(10 DOWNTO 1);□
    out_data   : OUT   STD_LOGIC_VECTOR(10 DOWNTO 1));□
END addr_cnt;□
□
ARCHITECTURE rtl OF addr_cnt IS□
BEGIN□
  -- default of updown is UP□
  -- this is an up-counter□
  □
  inst_cnt: lpm_counter□
    GENERIC MAP(LPM_WIDTH => 10,□
                LPM_TYPE => "LPM_COUNTER")□
    PORT MAP(data => ld_data,□
              clock => clk,□
              cnt_en => cnt_en,□
              sclr => sclr,□
              aload => aload,□
              sload => sload,□
              q => out_data);□
  □
END ARCHITECTURE rtl;□

```

```
-----□
--□
-- LOGIC CORE: GTL-module vme64x interface chip logic      --□
-- MODULE NAME: cr                                         --□
-- INSTITUTION: Hephys Vienna                                --□
-- DESIGNER: H. Bergauer                                     --□
--                                         --□
-- VERSION: V1.0                                           --□
-- DATE: 08 2005                                         --□
--                                         --□
-- FUNCTIONAL DESCRIPTION:                                 --□
-- configuration ROM for VME64x                           --□
-- range: 0x03 - 0x7FF                                     --□
--                                         --□
-----□
LIBRARY ieee;□
USE ieee.std_logic_1164.ALL;□
LIBRARY lpm;□
USE lpm.lpm_components.ALL;□
□
ENTITY cr IS□
  PORT(□
    addr      : IN      STD_LOGIC_VECTOR(10 DOWNTO 2);□
    rd_en     : IN      STD_LOGIC;□
    data      : INOUT   STD_LOGIC_VECTOR(7 DOWNTO 0));□
END cr;□
□
ARCHITECTURE rtl OF cr IS□
BEGIN□
□
-- Configuration ROM für VME64x mit 512x8 bits □
  cr_rom:lpm_rom□
  GENERIC MAP    (LPM_WIDTH => 8,□
    LPM_WIDTHAD => 9,□
      LPM_OUTDATA => "UNREGISTERED",□
      LPM_ADDRESS_CONTROL => "UNREGISTERED",□
      LPM_FILE => "cr.mif")□
  PORT MAP    (address => addr, □
    memenab => rd_en,□
    q => data);□
□
END ARCHITECTURE rtl;□
```

```

-----
--                                         --
-- LOGIC CORE: GTL-module vme64x interface chip logic   --
-- MODULE NAME: cram                                     --
-- INSTITUTION: Heph Vienna                            --
-- DESIGNER: H. Bergauer                                --
--                                         --
-- VERSION: V1.0                                         --
-- DATE: 08 2005                                         --
--                                         --
-- FUNCTIONAL DESCRIPTION:                               --
-- configuration RAM 512x8 for VME64x                   --
-- range: 0x03003 - 0x037FF                           --
--                                         --
-----                                         --

LIBRARY ieee;□
USE ieee.std_logic_1164.ALL;□
LIBRARY lpm;□
USE lpm.lpm_components.ALL;□
□
ENTITY cram IS□
  PORT(□
    addr      : IN      STD_LOGIC_VECTOR(10 DOWNTO 2);□
    clk       : IN      STD_LOGIC;□
    ld_en     : IN      STD_LOGIC;□
    rd_en     : IN      STD_LOGIC;□
    data      : INOUT   STD_LOGIC_VECTOR(7 DOWNTO 0));□
END cram;□
□
ARCHITECTURE rtl OF cram IS□
BEGIN□
  □
  -- Configuration RAM für VME64x mit 512x8 bits  □
  config_ram: lpm_ram_io□
  GENERIC MAP  (LPM_WIDTH => 8,□
    LPM_WIDTHAD => 9,□
      LPM_INDATA => "REGISTERED",□
      LPM_OUTDATA => "UNREGISTERED",□
      LPM_ADDRESS_CONTROL => "REGISTERED")□
  PORT MAP  (address => addr, □
    inclock => clk,□
    we => ld_en,□
    outenab => rd_en,□
    dio => data);□
  □
END ARCHITECTURE rtl;□

```

```

-----
--                                     --
-- LOGIC CORE: GTL-module vme64x interface chip logic      --
-- MODULE NAME: csr_ext_ext                                --
-- INSTITUTION: Hephys Vienna                            --
-- DESIGNER: H. Bergauer                                 --
--                                     --
-- VERSION: V1.0                                         --
-- DATE: 08 2005                                         --
--                                     --
-- FUNCTIONAL DESCRIPTION:                               --
-- control/status register                           --
-- range: 0x7FC00 - 0xFFFFF                         --
-- F0 => extended access A31-A25                   --
-- F1 => extended access A31-A25                   --
--                                     --
-----
```

LIBRARY ieee;□  
 USE ieee.std\_logic\_1164.ALL;□  
 LIBRARY altera;□  
 USE altera.maxplus2.ALL;□  
 LIBRARY lpm;□  
 USE lpm.lpm\_components.ALL;□  
 □

ENTITY csr\_ext\_ext IS□  
 PORT(□  
 clk : IN STD\_LOGIC; □  
 d : INOUT STD\_LOGIC\_VECTOR(7 DOWNTO 0); □  
 ga : IN STD\_LOGIC\_VECTOR(4 DOWNTO 0); □  
 nsysres : IN STD\_LOGIC; □  
 nberr : IN STD\_LOGIC; □  
 geo\_addr ok : IN STD\_LOGIC; □  
 ld\_adero0 : IN STD\_LOGIC\_VECTOR(3 DOWNTO 0); □  
 ld\_adero1 : IN STD\_LOGIC\_VECTOR(3 DOWNTO 0); □  
 rd\_adero0 : IN STD\_LOGIC\_VECTOR(3 DOWNTO 0); □  
 rd\_adero1 : IN STD\_LOGIC\_VECTOR(3 DOWNTO 0); □  
 ld\_bar : IN STD\_LOGIC; □  
 rd\_bar : IN STD\_LOGIC; □  
 ld\_bsr : IN STD\_LOGIC; □  
 ld\_bcr : IN STD\_LOGIC; □  
 rd\_bscr : IN STD\_LOGIC; □  
 reset\_mode : INOUT STD\_LOGIC; □  
 mod\_enabled : INOUT STD\_LOGIC; □  
 adero0\_a : OUT STD\_LOGIC\_VECTOR(31 DOWNTO 25);□  
 adero1\_a : OUT STD\_LOGIC\_VECTOR(31 DOWNTO 25);□  
 adero0\_am : OUT STD\_LOGIC\_VECTOR(5 DOWNTO 0);□  
 adero1\_am : OUT STD\_LOGIC\_VECTOR(5 DOWNTO 0));□  
 END csr\_ext\_ext;□  
 □

ARCHITECTURE rtl OF csr\_ext\_ext IS□  
 CONSTANT amnesia\_addr: STD\_LOGIC\_VECTOR(4 DOWNTO 0) := "11110";□  
 SIGNAL aclr: STD\_LOGIC;□  
 SIGNAL adero3\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero2\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero1\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero0\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero1\_3\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero1\_2\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero1\_1\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL adero1\_0\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL bsr\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL bcr\_out: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL bscr\_in: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL bar\_in: STD\_LOGIC\_VECTOR(7 DOWNTO 0);□  
 SIGNAL set\_res\_mode: STD\_LOGIC;□  
 SIGNAL dis\_res\_mode: STD\_LOGIC;□  
 SIGNAL en\_module: STD\_LOGIC;□  
 SIGNAL dis\_module: STD\_LOGIC;□  
 SIGNAL set\_berr\_flag: STD\_LOGIC;□

```

SIGNAL clr_berr_flag: STD_LOGIC;□
SIGNAL berr_flag: STD_LOGIC;□
BEGIN□
    aclr <= NOT nsysres;□
    □
    -- base-address A31-A25□
    ader0_a <= ader0_3_out(7 DOWNTO 1);□
    ader0_am <= ader0_0_out(7 DOWNTO 2);□
    □
    ader1_a <= ader1_3_out(7 DOWNTO 1);□
    ader1_am <= ader1_0_out(7 DOWNTO 2);□
    □
    -- ****
    -- load ader0_3 register□
        ader0_3_load: lpm_ff□
        GENERIC MAP      (LPM_WIDTH => 8)□
        PORT MAP        (data => d, □
                          clock => clk, □
                          enable => ld_ader0(3), □
                          aclr => aclr, □
                          q => ader0_3_out);□
    □
    -- load ader0_2 register□
        ader0_2_load: lpm_ff□
        GENERIC MAP      (LPM_WIDTH => 8)□
        PORT MAP        (data => d, □
                          clock => clk, □
                          enable => ld_ader0(2), □
                          aclr => aclr, □
                          q => ader0_2_out);□
    □
    -- load ader0_1 register□
        ader0_1_load: lpm_ff□
        GENERIC MAP      (LPM_WIDTH => 8)□
        PORT MAP        (data => d, □
                          clock => clk, □
                          enable => ld_ader0(1), □
                          aclr => aclr, □
                          q => ader0_1_out);□
    □
    -- load ader0_0 register□
        ader0_0_load: lpm_ff□
        GENERIC MAP      (LPM_WIDTH => 8)□
        PORT MAP        (data => d, □
                          clock => clk, □
                          enable => ld_ader0(0), □
                          aclr => aclr, □
                          q => ader0_0_out);□
    □
    -- read ader0_3 register□
        ader0_3_read:□
        FOR i IN 0 TO 7 GENERATE□
            tri_ader0_3: tri□
            PORT MAP(ader0_3_out(i), □
                      rd_ader0(3), □
                      d(i));□
        END GENERATE ader0_3_read;□
    □
    -- read ader0_2 register□
        ader0_2_read:□
        FOR i IN 0 TO 7 GENERATE□
            tri_ader0_2: tri□
            PORT MAP(ader0_2_out(i), □
                      rd_ader0(2), □
                      d(i));□
        END GENERATE ader0_2_read;□
    □
    -- read ader0_1 register□
        ader0_1_read:□

```

```

FOR i IN 0 TO 7 GENERATE□
    tri_ader0_1: tri□
    PORT MAP(ader0_1_out(i),□
              rd_ader0(1),□
              d(i));□
END GENERATE ader0_1_read;□
□
-- read ader0_0 register□
ader0_0_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_ader0_0: tri□
    PORT MAP(ader0_0_out(i),□
              rd_ader0(0),□
              d(i));□
END GENERATE ader0_0_read;□
□
-- ****
-- load ader1_3 register□
ader1_3_load: lpm_ff□
GENERIC MAP      (LPM WIDTH => 8)□
PORT MAP (data => d, □
           clock => clk,□
           enable => ld_ader1(3),□
           aclr => aclr,□
           q => ader1_3_out);□
□
-- load ader1_2 register□
ader1_2_load: lpm_ff□
GENERIC MAP      (LPM WIDTH => 8)□
PORT MAP (data => d, □
           clock => clk,□
           enable => ld_ader1(2),□
           aclr => aclr,□
           q => ader1_2_out);□
□
-- load ader1_1 register□
ader1_1_load: lpm_ff□
GENERIC MAP      (LPM WIDTH => 8)□
PORT MAP (data => d, □
           clock => clk,□
           enable => ld_ader1(1),□
           aclr => aclr,□
           q => ader1_1_out);□
□
-- load ader1_0 register□
ader1_0_load: lpm_ff□
GENERIC MAP      (LPM WIDTH => 8)□
PORT MAP (data => d, □
           clock => clk,□
           enable => ld_ader1(0),□
           aclr => aclr,□
           q => ader1_0_out);□
□
-- read ader1_3 register□
ader1_3_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_ader1_3: tri□
    PORT MAP(ader1_3_out(i),□
              rd_ader1(3),□
              d(i));□
END GENERATE ader1_3_read;□
□
-- read ader1_2 register□
ader1_2_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_ader1_2: tri□
    PORT MAP(ader1_2_out(i),□
              rd_ader1(2),□
              d(i));□

```

```

END GENERATE ader1_2_read;□
-- read ader1_1 register□
ader1_1_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_ader1_1: tri□
    PORT MAP(ader1_1_out(i),□
        rd ader1(1),□
        d(i));□
END GENERATE ader1_1_read;□
-- read ader1_0 register□
ader1_0_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_ader1_0: tri□
    PORT MAP(ader1_0_out(i),□
        rd ader1(0),□
        d(i));□
END GENERATE ader1_0_read;□
-- ****
-- load bit set register□
bsr_load: lpm_ff□
GENERIC MAP (LPM_WIDTH => 8)□
PORT MAP (data => d, □
    clock => clk,□
    enable => ld_bsr,□
    aclr => aclr,□
    q => bsr_out);□
set_res_mode <= bsr_out(7);□
en_module <= bsr_out(4);□
set_berr_flag <= bsr_out(3);□
-- load bit clear register□
bcr_load: lpm_ff□
GENERIC MAP (LPM_WIDTH => 8)□
PORT MAP (data => d, □
    clock => clk,□
    enable => ld_bcr,□
    aclr => aclr,□
    q => bcr_out);□
dis_res_mode <= bcr_out(7);□
dis_module <= bcr_out(4);□
clr_berr_flag <= bcr_out(3);□
-- ****
-- setting and clearing bits of BSR and BCR□
PROCESS (set_res_mode, dis_res_mode, en_module, dis_module, set_berr_flag, clr_berr_flag,
BEGIN
    IF set_res_mode='1' THEN□
        reset_mode <= '1';□
    ELSIF (set_res_mode='0' AND dis_res_mode='1') OR nsysres='0' THEN□
        reset_mode <= '0';□
    END IF;□
    IF en_module='1' OR nsysres='0' THEN□
        mod_enabled <= '1';□
    ELSIF (en_module='0' AND dis_module='1' AND nsysres='1') THEN□
        mod_enabled <= '0';□
    END IF;□
    IF en_module='1' THEN□
        mod_enabled <= '1';□
    ELSIF (en_module='0' AND dis_module='1') OR nsysres='0' THEN□
        mod_enabled <= '0';□
    END IF;□
    -- set berr_flag if a BERR is generated on board or set_berr_flag='1'??

```

```

-- clear berr_flag if a SYSRES is generated or clr_berr_flag='1' (and set_berr_flag='0')□
-- see VME64x-specification Rule 10.16□
□
    IF set_berr_flag='1' OR nberr='0' THEN□
        berr_flag <= '1';□
    ELSIF (set_berr_flag='0' AND clr_berr_flag='1') OR nsysres='0' THEN□
        berr_flag <= '0';□
    END IF;□
END PROCESS;□
□
-- ****
bscr_in <= reset_mode & '0' & '0' & mod_enabled & berr_flag & '0' & '0' & '0'; □
□
-- read bit set/clear register□
bscr_read:□
FOR i IN 0 TO 7 GENERATE□
    tri bscr: tri□
    PORT MAP(bscr_in(i),□
              rd_bscr,□
              d(i));□
END GENERATE bscr_read;□
□
-- ****
-- setting BAR with GA or amnesia address□
□
PROCESS (geo_addr_ok, ga)□
BEGIN□
    IF geo_addr_ok = '1' THEN□
        bar_in(7 DOWNTO 3) <= ga(4 DOWNTO 0); □
        bar_in(2 DOWNTO 0) <= "000"; □
    ELSE□
        bar_in <= amnesia_addr & '0' & '0' & '0'; □
    END IF;□
END PROCESS;□
□
-- read base address register□
bar_read:□
FOR i IN 0 TO 7 GENERATE□
    tri_bar: tri□
    PORT MAP(bar_in(i),□
              rd_bar,□
              d(i));□
END GENERATE bar_read;□
□
END ARCHITECTURE rtl;□

```

```

-----
-- LOGIC CORE: GT-logic
-- MODULE NAME: reg_8_en_clr
-- INSTITUTION: Hephys Vienna
-- DESIGNER: H. Bergauer
--
-- VERSION: V1.0
-- DATE: 09 2005
--
-- FUNCTIONAL DESCRIPTION:
-- register (8 bit) with enable and clr
--

LIBRARY ieee;
USE ieee.std_logic_1164.ALL;
LIBRARY lpm;
USE lpm.lpm_components.ALL;

ENTITY reg_8_en_clr IS
  PORT(
    d1 : IN STD_LOGIC;
    d2 : IN STD_LOGIC;
    d3 : IN STD_LOGIC;
    d4 : IN STD_LOGIC;
    d5 : IN STD_LOGIC;
    d6 : IN STD_LOGIC;
    d7 : IN STD_LOGIC;
    d8 : IN STD_LOGIC;
    clk : IN STD_LOGIC;
    en : IN STD_LOGIC;
    clr : IN STD_LOGIC;
    q1 : OUT STD_LOGIC;
    q2 : OUT STD_LOGIC;
    q3 : OUT STD_LOGIC;
    q4 : OUT STD_LOGIC;
    q5 : OUT STD_LOGIC;
    q6 : OUT STD_LOGIC;
    q7 : OUT STD_LOGIC;
    q8 : OUT STD_LOGIC);
END reg_8_en_clr;

ARCHITECTURE rtl OF reg_8_en_clr IS
  SIGNAL d : STD_LOGIC_VECTOR(8 DOWNTO 1);
  SIGNAL q : STD_LOGIC_VECTOR(8 DOWNTO 1);
BEGIN
  d <= d8 & d7 & d6 & d5 & d4 & d3 & d2 & d1;
  q1 <= q(1);
  q2 <= q(2);
  q3 <= q(3);
  q4 <= q(4);
  q5 <= q(5);
  q6 <= q(6);
  q7 <= q(7);
  q8 <= q(8);

  reg: lpm_ff
    GENERIC MAP(LPM_WIDTH => 8)
    PORT MAP(data => d, clock => clk, enable => en,
              aclr => clr, q => q);
END ARCHITECTURE rtl;

```

```
--  
-- LOGIC CORE: GT-logic  
-- MODULE NAME: rw_reg_8  
-- INSTITUTION: Hephys Vienna  
-- DESIGNER: H. Bergauer  
--  
-- VERSION: V1.0  
-- DATE: 08 2005  
--  
-- FUNCTIONAL DESCRIPTION:  
-- read/write register (8 bit)  
--  
-----  
LIBRARY ieee;  
USE ieee.std_logic_1164.ALL;  
LIBRARY lpm;  
USE lpm.lpm_components.ALL;  
LIBRARY altera;  
USE altera.maxplus2.ALL;  
  
ENTITY rw_reg_8 IS  
    PORT(  
        data      : INOUT STD_LOGIC_VECTOR(7 DOWNTO 0);  
        wr_clk   : IN     STD_LOGIC;  
        rd_en    : IN     STD_LOGIC;  
        reg_out  : OUT    STD_LOGIC_VECTOR(7 DOWNTO 0));  
END rw_reg_8;  
  
ARCHITECTURE rtl OF rw_reg_8 IS  
    SIGNAL data_int : STD_LOGIC_VECTOR(7 DOWNTO 0);  
BEGIN  
  
    -- write register  
  
    write_reg: lpm_ff  
        GENERIC MAP(LPM_WIDTH => 8)  
        PORT MAP(data, wr_clk, q => data_int);  
  
    reg_out <= data_int;  
  
    -- read register (tri-state outputs to VME)  
    tri_stat_out:  
    FOR i IN 0 TO 7 GENERATE  
        call_tri: tri  
            PORT MAP(data_int(i), rd_en, data(i));  
    END GENERATE tri_stat_out;  
  
END ARCHITECTURE rtl;
```

```

-----
--  

-- LOGIC CORE: GT logic  

-- MODULE NAME: sel_test_outputs  

-- INSTITUTION: Heph Vienna  

-- DESIGNER: H. Bergauer  

--  

-- VERSION: V1.0  

-- DATE: 08 2005  

--  

-- FUNCTIONAL DESCRIPTION:  

-- selection of 1 of 16 signals for  

-- 4 test_out-pins (scope)  

--  

-----  

LIBRARY ieee;  

USE ieee.std_logic_1164.ALL;  

USE ieee.std_logic_unsigned.ALL;  

ENTITY sel_test_outputs IS
  PORT(
    -- test_signals_0      : IN STD_LOGIC;
    -- test_signals_1      : IN STD_LOGIC;
    -- test_signals_2      : IN STD_LOGIC;
    -- test_signals_3      : IN STD_LOGIC;
    -- test_signals_4      : IN STD_LOGIC;
    -- test_signals_5      : IN STD_LOGIC;
    -- test_signals_6      : IN STD_LOGIC;
    -- test_signals_7      : IN STD_LOGIC;
    -- test_signals_8      : IN STD_LOGIC;
    -- test_signals_9      : IN STD_LOGIC;
    -- test_signals_10     : IN STD_LOGIC;
    -- test_signals_11     : IN STD_LOGIC;
    -- test_signals_12     : IN STD_LOGIC;
    -- test_signals_13     : IN STD_LOGIC;
    -- test_signals_14     : IN STD_LOGIC;
    -- test_signals_15     : IN STD_LOGIC;
    test_signals        : IN STD_LOGIC_VECTOR(15 DOWNTO 0);
    en_1_signals        : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
    en_2_signals        : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
    en_3_signals        : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
    en_4_signals        : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
    test_outputs        : OUT STD_LOGIC_VECTOR(4 DOWNTO 1)
  );
END sel_test_outputs;  

ARCHITECTURE rtl OF sel_test_outputs IS
--COMPONENT test_out_coded IS
--  PORT(
--    en_signals          : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
--    test_signals        : IN STD_LOGIC_VECTOR(15 DOWNTO 0);
--    test_out            : OUT STD_LOGIC
--  );
--END COMPONENT test_out_coded;  

--  

-- SIGNAL test_signals_vec : STD_LOGIC_VECTOR(15 DOWNTO 0);  

--  

-- TYPE en_signals_type IS ARRAY (4 DOWNTO 1)
--   OF STD_LOGIC_VECTOR(3 DOWNTO 0);  

--  

-- SIGNAL en_signals_arr : en_signals_type;  

BEGIN
-- *****
-- ERKLÄRUNG:  

-- en_signals sind codiert, 4 bits aus VME-registers (2x8 bits für  

-- 4 test_outputs mit je 16 test-signals), die angeben,  

-- welches interne signal auf test-output gelegt wird.  

-- test_signals ist der vector, der die internen signals enthält.  

-- Korrespondierend mit dem value der en_signals wird das jeweilige

```

```
-- interne signal auf den test-output gelegt. Definition des internen
-- signals in vector notwendig!!!
-- ****
en_signals_arr(4) <= en_4_signals;
en_signals_arr(3) <= en_3_signals;
en_signals_arr(2) <= en_2_signals;
en_signals_arr(1) <= en_1_signals;

--test_signals_vec <=
-- test signals 15 & test signals 14 & test signals 13 & test signals 12 &
-- test_signals_11 & test_signals_10 & test_signals_9 & test_signals_8 &
-- test_signals_7 & test_signals_6 & test_signals_5 & test_signals_4 &
-- test signals 3 & test signals 2 & test signals 1 & test signals 0;

loop_test_outputs:
  for i in 1 to 4 generate
    test_outputs(i) <= test_signals(CONV_INTEGER(en_signals_arr(i)));
  end generate loop_test_outputs;

--loop_test_outputs:
--for i in 1 to 4 generate
--  call test_out: test out coded
--    PORT MAP(en_signals_arr(i), test_signals_vec, test_outputs(i));
--end generate loop_test_outputs;

END rtl;
```

```

-----
-- LOGIC CORE: GTL-module vme64x interface chip logic
-- MODULE NAME: user_cr
-- INSTITUTION: Heph Vienna
-- DESIGNER: H. Bergauer
--
-- VERSION: V2.2
-- DATE: 08 2005
--
-- FUNCTIONAL DESCRIPTION:
-- ROM for chip_id and version (each 4 bytes)
-- and serial number (VME64x)
-- range: 0x01003 - 0x0103F
--
-- REVISION:
-- V2.1: CARD NR from S24-S27 jumpers
-- V2.2: CARD_NR from S24-S27 jumpers used for
--         serial number of PSB-cards too
--
LIBRARY ieee;
USE ieee.std_logic_1164.ALL;
LIBRARY lpm;
USE lpm.lpm_components.ALL;
LIBRARY altera;
USE altera.maxplus2.ALL;

ENTITY user_cr IS
  PORT(
    addr      : IN STD_LOGIC_VECTOR(5 DOWNTO 2);
    card_nr   : IN STD_LOGIC_VECTOR(3 DOWNTO 0);
    rd_en     : IN STD_LOGIC;
    data      : INOUT STD_LOGIC_VECTOR(7 DOWNTO 0));
END user_cr;

ARCHITECTURE rtl OF user_cr IS
  SIGNAL addr_sel : STD_LOGIC_VECTOR(3 DOWNTO 0);
  SIGNAL addr_mem : std_logic;
  SIGNAL addr_card_nr : std_logic;
  SIGNAL addr_ser_nr_1 : std_logic;
  SIGNAL addr_ser_nr_2 : std_logic;
  SIGNAL data_mem : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_cnr : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_snr_1 : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_snr_2 : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_tri : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_cnr_tri : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_snr_1_tri : STD_LOGIC_VECTOR(7 DOWNTO 0);
  SIGNAL data_snr_2_tri : STD_LOGIC_VECTOR(7 DOWNTO 0);
BEGIN
  -- card_nr
  data_cnr(7) <= data_mem(7);
  data_cnr(6) <= data_mem(6);
  data_cnr(5) <= data_mem(5);
  data_cnr(4) <= data_mem(4);
  data_cnr(3) <= card_nr(3);
  data_cnr(2) <= card_nr(2);
  data_cnr(1) <= card_nr(1);
  data_cnr(0) <= card_nr(0);

  -- serial_nr in ASCII, first character !!! 0x30 + Card_nr !!!
  WITH card_nr SELECT
    data_snr_1 <=
      X"31" WHEN X"0",
      X"30" WHEN X"1",
      X"30" WHEN X"2",
      X"30" WHEN X"3",

```

```

X"30" WHEN X"4",
X"30" WHEN X"5",
X"30" WHEN X"6",
X"30" WHEN X"7",
X"30" WHEN X"8",
X"30" WHEN X"9",
X"31" WHEN X"A",
X"31" WHEN X"B",
X"31" WHEN X"C",
X"31" WHEN X"D",
X"31" WHEN X"E",
X"31" WHEN X"F",
X"00" WHEN OTHERS;

WITH card_nr SELECT
data_snr_2 <=
    X"36" WHEN X"0",
    X"31" WHEN X"1",
    X"32" WHEN X"2",
    X"33" WHEN X"3",
    X"34" WHEN X"4",
    X"35" WHEN X"5",
    X"36" WHEN X"6",
    X"37" WHEN X"7",
    X"38" WHEN X"8",
    X"39" WHEN X"9",
    X"30" WHEN X"A",
    X"31" WHEN X"B",
    X"32" WHEN X"C",
    X"33" WHEN X"D",
    X"34" WHEN X"E",
    X"35" WHEN X"F",
    X"00" WHEN OTHERS;

WITH addr SELECT
addr_sel <=
    X"1" WHEN X"0",
    X"1" WHEN X"1",
    X"2" WHEN X"2",
    X"1" WHEN X"3",
    X"1" WHEN X"4",
    X"1" WHEN X"5",
    X"1" WHEN X"6",
    X"1" WHEN X"7",
    X"1" WHEN X"8",
    X"1" WHEN X"9",
    X"1" WHEN X"A",
    X"4" WHEN X"B",
    X"8" WHEN X"C",
    X"1" WHEN X"D",
    X"1" WHEN X"E",
    X"1" WHEN X"F",
    X"0" WHEN OTHERS;

-- addresses for card_nr and serial_nr
addr_mem <= addr_sel(0) AND rd_en;
addr_card_nr <= addr_sel(1) AND rd_en;
addr_ser_nr_1 <= addr_sel(2) AND rd_en;
addr_ser_nr_2 <= addr_sel(3) AND rd_en;

-- USER_CR for chip_id, version and SN with 16x8 bits
call_user_cr: lpm_rom
  GENERIC MAP  (LPM_WIDTH => 8,
    LPM_WIDTHAD => 4,
    LPM_OUTDATA => "UNREGISTERED",
    LPM_ADDRESS_CONTROL => "UNREGISTERED",
    LPM_FILE => "user_cr.mif")
  PORT MAP  (address => addr,
    memenab => rd_en,

```

```

q => data_mem);

-- mux for card_nr
call_mux_cnr: busmux
  GENERIC MAP  (WIDTH => 8)
  PORT MAP  (dataaa => data_mem,
             datab => data_cnr,
             sel => addr_card_nr,
             result => data_cnr_tri);

tri data cnr:
FOR i IN 0 TO 7 GENERATE
  call_data_cnr: tri
    PORT MAP(data cnr tri(i),
              addr_card_nr,
              data(i));
END GENERATE tri data cnr;

-- mux for serial_nr first ASCII character
call mux_snr_1: busmux
  GENERIC MAP  (WIDTH => 8)
  PORT MAP  (dataaa => data_mem,
             datab => data_snr_1,
             sel => addr_ser_nr_1,
             result => data_snr_1_tri);

tri_data_snr_1:
FOR i IN 0 TO 7 GENERATE
  call data_snr_1: tri
    PORT MAP(data_snr_1_tri(i),
              addr_ser_nr_1,
              data(i));
END GENERATE tri_data_snr_1;

-- mux for serial_nr second ASCII character
call mux_snr_2: busmux
  GENERIC MAP  (WIDTH => 8)
  PORT MAP  (dataaa => data_mem,
             datab => data_snr_2,
             sel => addr_ser_nr_2,
             result => data_snr_2_tri);

tri_data_snr_2:
FOR i IN 0 TO 7 GENERATE
  call_data_snr_2: tri
    PORT MAP(data_snr_2_tri(i),
              addr_ser_nr_2,
              data(i));
END GENERATE tri_data_snr_2;

tri_data_mem:
FOR i IN 0 TO 7 GENERATE
  call_data_mem: tri
    PORT MAP(data_mem(i),
              addr_mem,
              data(i));
END GENERATE tri_data_mem;

END ARCHITECTURE rtl;

```

```

-- ****
-- Specify values for addresses of Configuration ROM for VME64x of PSB9U-cards
-- Only every forth address of CR table is used. D08_O = 1 and A01 = 1.
-- 
-- V100C:
-- 
-- CR/CSR space definition:
-- 
-- VME64x_CR range: 0x03-0xFFFF (0x03-0x7FF in this mif-file defined)
-- USER_CR range for chip_id, version and SN: 0x001003-0x001033 (see user_cr.mif)
-- CRAM range for future applications (not defined yet): 0x003003-0x0037FF
-- USER_CSR range for TEST_OUT-selection register: 0x005003-0x00502F
-- VME64x_CSR range: 0x7FC00-0x7FFFF
-- 
-- FUNCTION definition:
-- 
-- Function 0: D16 only, A31-A25, AM=0x0D and 0x09 (single transfer)
-- Function 1: D16 only, A31-A25, AM=0x0F and 0x0B (block transfer)
-- ****

DEPTH = 512;      % Memory depth and width are required    %
WIDTH = 8;        % Enter a decimal number    %
-- 
ADDRESS_RADIX = HEX;      % Address and value radices are required    %
DATA_RADIX = HEX;        % Enter BIN, DEC, HEX, OCT, or UNS; unless    %
                         % otherwise specified, radices = HEX    %

-- used address-bits
-- A10 | A09 A08 A07 A06 | A05 A04 A03 A02

CONTENT
BEGIN
000      : 00; -- checksum [CR address = 0x03] -- to be defined!!
001      : 00; -- length of ROM (MSB, byte 2), not defined [CR address = 0x07] -- to be defined!!
002      : 00; -- length of ROM (byte 1), not defined [CR address = 0x0B]
003      : 00; -- length of ROM (LSB, byte 0), not defined [CR address = 0x0F]
-- 
004      : 81; -- CR data access width (0x81=D08(0)) [CR address = 0x13]
005      : 81; -- CSR data access width (0x81=D08(0)) [CR address = 0x17]
006      : 02; -- CR/CSR space specification ID (0x02=VME64x) [CR address = 0x13]
007      : 43; -- 0x43 (ASCII "C") [CR address = 0x1F]
-- 
008      : 52; -- 0x52 (ASCII "R") [CR address = 0x23]
009      : 00; -- Manufactor's ID (MSB, byte 2) (0x00=no IEEE code) [CR address = 0x27]
00A      : 00; -- Manufactor's ID (byte 1) (0x00=no IEEE code) [CR address = 0x2B]
00B      : 00; -- Manufactor's ID (LSB, byte 0) (0x00=no IEEE code) [CR address = 0x2F]

```

```

00C      : A0; -- Board ID (MSB, byte 3) (0xA0=example) [CR address = 0x33]
00D      : 12; -- Board ID (byte 2) (0x12=example) [CR address = 0x37]
00E      : 34; -- Board ID (byte 1) (0x34=example) [CR address = 0x3B]
00F      : 56; -- Board ID (LSB, byte 0) (0x56=example) [CR address = 0x3F]

010      : B9; -- Revision ID (MSB, byte 3) (0xB9=example) [CR address = 0x43]
011      : 87; -- Revision ID (byte 2) (0x87=example) [CR address = 0x47]
012      : 65; -- Revision ID (byte 1) (0x65=example) [CR address = 0x4B]
013      : 43; -- Revision ID (LSB, byte 0) (0x43=example) [CR address = 0x4F]

[014..01E] : 00; -- not used! ("Pointer to null ..." and "RESERVED") [CR address = 0x53..0x7B]

01F      : 01; -- Programm ID (0x01=no program, ID code only) [CR address = 0x7F]

020      : 00; -- Offset to BEG_USER_CR (MSB, byte 2), (0x00) [CR address = 0x83] -- BEG_USER_CR = 0x001003
021      : 10; -- Offset to BEG_USER CR (byte 1), (0x10) [CR address = 0x87]
022      : 03; -- Offset to BEG_USER_CR (LSB, byte 0), (0x03) [CR address = 0x8B]
023      : 00; -- Offset to END_USER_CR (MSB, byte 2), (0x00) [CR address = 0x8F] -- END_USER_CR = 0x00101F

024      : 10; -- Offset to END_USER_CR (byte 1), (0x10) [CR address = 0x93]
025      : 1F; -- Offset to END_USER_CR (LSB, byte 0), (0x1F) [CR address = 0x97]
026      : 00; -- Offset to BEG_CRAM (MSB, byte 2), (0x00) [CR address = 0x9B] -- BEG_CRAM = 0x003003
027      : 30; -- Offset to BEG_CRAM (byte 1), (0x30) [CR address = 0x9F]

028      : 03; -- Offset to BEG_CRAM (LSB, byte 0), (0x03) [CR address = 0xA3]
029      : 00; -- Offset to END_CRAM (MSB, byte 2), (0x00) [CR address = 0xA7] -- END_CRAM = 0x0037FF
02A      : 37; -- Offset to END_CRAM (byte 1), (0x37) [CR address = 0xAB]
02B      : FF; -- Offset to END_CRAM (LSB, byte 0), (0xFF) [CR address = 0xAF]

02C      : 00; -- Offset to BEG_USER_CSR (MSB, byte 2), (0x00) [CR address = 0xB3] -- BEG_USER_CSR = 0x005003
02D      : 50; -- Offset to BEG_USER_CSR (byte 1), (0x50) [CR address = 0xB7]
02E      : 03; -- Offset to BEG_USER_CSR (LSB, byte 0), (0x03) [CR address = 0xBB]
02F      : 00; -- Offset to END_USER_CSR (MSB, byte 2), (0x00) [CR address = 0xBF] -- END_USER_CSR = 0x00502F

030      : 50; -- Offset to END_USER_CSR (byte 1), (0x50) [CR address = 0xC3]
031      : 2F; -- Offset to END_USER_CSR (LSB, byte 0), (0x2F) [CR address = 0xC7]
032      : 00; -- Offset to BEG_SN (MSB, byte 2), (0x00) [CR address = 0xCB] -- BEG_SN = 0x001023
033      : 10; -- Offset to BEG_SN (byte 1), (0x10) [CR address = 0xCF]

034      : 23; -- Offset to BEG_SN (LSB, byte 0), (0x23) [CR address = 0xD3]
035      : 00; -- Offset to END_SN (MSB, byte 2), (0x00) [CR address = 0xD7] -- END_SN = 0x001033
036      : 10; -- Offset to END_SN (byte 1), (0x10) [CR address = 0xDB]
037      : 33; -- Offset to END_SN (LSB, byte 0), (0x2F) [CR address = 0xDF]

038      : 00; -- Slave characteristics parameter (0x00, see Table 10-1 VME64x spec.) [CR address = 0xE3]

```

```

039      : 00; -- User defined slave characteristics, not used! [CR address = 0xE7]□
03A      : 00; -- Master characteristics, not used! [CR address = 0xEB]□
03B      : 00; -- User defined master characteristics, not used! [CR address = 0xEF]□
□
03C      : 00; -- Interrupt handler capabilities, not used! [CR address = 0xF3]□
03D      : 00; -- Interrupter capabilities, not used! [CR address = 0xF7]□
03E      : 00; -- Reserved, not used! [CR address = 0xFB]□
03F      : 00; -- CRAM ACCESS WIDTH (0x81=D08(0)) [CR address = 0xFF]□
□
040      : 83; -- Function 0 DAWPR (0x83, "D16 only (C. Schwick!)", see Table 10-3 VME64x spec.) [CR address = 0x103]□
041      : 83; -- Function 1 DAWPR (0x83, "D16 only (C. Schwick!)", see Table 10-3 VME64x spec.) [CR address = 0x107]□
042      : 00; -- Function 2 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x10B]□
043      : 00; -- Function 3 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x10F]□
□
044      : 00; -- Function 4 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x113]□
045      : 00; -- Function 5 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x117]□
046      : 00; -- Function 6 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x11B]□
047      : 00; -- Function 7 DAWPR (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x11F]□
□
048      : 00; -- Function 0 AMCAP (MSB, byte 7) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x123]□
049      : 00; -- Function 0 AMCAP (byte 6) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x127]□
04A      : 00; -- Function 0 AMCAP (byte 5) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x12B]□
04B      : 00; -- Function 0 AMCAP (byte 4) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x12F]□
□
04C      : 00; -- Function 0 AMCAP (byte 3) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x133]□
04D      : 00; -- Function 0 AMCAP (byte 2) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x137]□
04E      : 22; -- Function 0 AMCAP (byte 1) (0x22, AM=0xD and 0x9, see 10.2.1.4.2 VME64x spec.) [CR address = 0x13B]□
04F      : 00; -- Function 0 AMCAP (LSB, byte 0) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x13F]□
□
050      : 00; -- Function 1 AMCAP (MSB, byte 7) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x143]□
051      : 00; -- Function 1 AMCAP (byte 6) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x147]□
052      : 00; -- Function 1 AMCAP (byte 5) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x14B]□
053      : 00; -- Function 1 AMCAP (byte 4) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x14F]□
□
054      : 00; -- Function 1 AMCAP (byte 3) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x153]□
055      : 00; -- Function 1 AMCAP (byte 2) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x157]□
056      : 88; -- Function 1 AMCAP (byte 1) (0x88, AM=0xF and 0xB, see 10.2.1.4.2 VME64x spec.) [CR address = 0x15B]□
057      : 00; -- Function 1 AMCAP (LSB, byte 0) (0x00, see 10.2.1.4.2 VME64x spec.) [CR address = 0x15F]□
□
[058..187] : 00; -- not used! ("Function 2 - 7 AMCAP" and "Function 0 - 7 XAMCAP") [CR address = 0x163..0x61F]□
□
188      : FE; -- Function 0 ADEM (MSB, byte 3) (0xFE, "mask bits 31-25=1, 24=0", see Table 10-4 VME64x spec.) [CR address = 0
189      : 00; -- Function 0 ADEM (byte 2) (0x00, "mask bits 23-16=0", see Table 10-4 VME64x spec.) [CR address = 0x627]□
18A      : 00; -- Function 0 ADEM (byte 1) (0x00, "mask bits 15-8=0", see Table 10-4 VME64x spec.) [CR address = 0x62B]□
18B      : 00; -- Function 0 ADEM (LSB, byte 0) (0x00, "special bits=0", see Table 10-4 VME64x spec.) [CR address = 0x62F]□

```

```
18C      : FE; -- Function 1 ADEM (MSB, byte 3) (0xFE, "mask bits 31-25=1, 24=0", see Table 10-4 VME64x spec.) [CR address = 0
18D      : 00; -- Function 1 ADEM (byte 2) (0x00, "mask bits 23-16=0", see Table 10-4 VME64x spec.) [CR address = 0x637]□
18E      : 00; -- Function 1 ADEM (byte 1) (0x00, "mask bits 15-8=0", see Table 10-4 VME64x spec.) [CR address = 0x63B]□
18F      : 00; -- Function 1 ADEM (LSB, byte 0) (0x00, "special bits=0", see Table 10-4 VME64x spec.) [CR address = 0x63F]□
□
[190..1AA] : 00; -- not used! ("Function 2 - 7 ADEM" and "reserved, read as zero") [CR address = 0x643..0x6AB]□
□
1AB      : 00; -- Master data access width (0x00, "feature not implemented", see Table 10-3 VME64x spec.) [CR address = 0x6AF]□
□
[1AC..1D3] : 00; -- not used! ("Master AMCAP" and "Master XAMCAP") [CR address = 0x6B3..0x74F]□
[1D4..1FF] : 00; -- not used! ("RESERVED") [CR address = 0x753..0x7FF]□
□
END;□
□
```

```
-- ****
-- Specify values for addresses of User Configuration ROM for VME64x of PSB9U-cards
-- Only every forth address is used. D08_O = 1 and A01 = 1.
-- USER_CR range for chip_id, version and SN (VME64x): 0x001003-0x001037
-- chip id: 0x00018011 => 0 for card nr, card nr comes in hardware from jumper S31-S28!!!!
-- see user_cr.vhd V2.2 !!!
-- version: 0x0000100C
-- ****

DEPTH = 16; % Memory depth and width are required %
WIDTH = 8; % Enter a decimal number %

ADDRESS_RADIX = HEX; % Address and value radices are required %
DATA_RADIX = HEX; % Enter BIN, DEC, HEX, OCT, or UNS; unless %
% otherwise specified, radices = HEX %

-- used address-bits
-- A05 A04 A03 A02

CONTENT
BEGIN
0      : 00; -- chip_id-register 3 (MSB) [USER_CR address = 0x001003]
1      : 01; -- chip_id-register 2 [USER_CR address = 0x001007]
2      : 80; -- chip_id-register 1 [USER_CR address = 0x00100B]
3      : 11; -- chip_id-register 0 [USER_CR address = 0x00100F]

4      : 00; -- version-register 3 (MSB) [USER_CR address = 0x001013]
5      : 00; -- version-register 2 [USER_CR address = 0x001017]
6      : 10; -- version-register 1 [USER_CR address = 0x00101B]
7      : 0C; -- version-register 0 [USER_CR address = 0x00101F]

8      : 50; -- serial number byte 7 (MSB), ASCII "P" [SN address = 0x001023]
9      : 53; -- serial number byte 6, ASCII "S" [SN address = 0x001027]
A      : 42; -- serial number byte 5, ASCII "B" [SN address = 0x00102B]
B      : 00; -- serial number byte 4 ASCII "from CARD_NR jumper S31-S28" [SN address = 0x00102F]

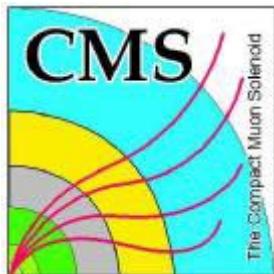
C      : 00; -- serial number byte 3 (LSB), ASCII "from CARD_NR jumper S31-S28" [SN address = 0x001033]

[D..F]  : 00; -- not used! [CR address = 0x001037-0x00103F]

END;
```

**VME-CHIP**  
**(Version 0x1007)**  
**of**  
**PSB-9U-card**  
**(9U-Version)**

H. Bergauer, K. Kastner, M. Padrta, A. Taurok



**Jan-06**

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## 1 Introduction

The VME-CHIP-PSB works with the VME64x chip PSB as controller for the VME-bus of the PSB-9U-card. There are VME-registers on it as the Registers for Programmable-chips-configuration, General registers, Chip ID / version registers and JTAG registers. The VME-accesses to the PSB-chip are made via this chip too.

## 2 VME chip of PSB-9U-card

### 2.1 Versionshistory

- V1000: first design. Error at RESET\_MODE. **DO NOT USE!!** (HB110805).
- V1001: based on V1000, but RESET\_MODE error corrected. **DO NOT USE!!** (HB110805).
- V1002: based on V1001, but PSB/MEM access (ENPSB, ENPSBMEM) made with DSSYNC for read and write accesses. (HB120805).
- V1003: based on V1002, but write/read for general-register and configuration-register implemented. (HB160805).
- V1004: based on V1003, but lines ASCYC, ASSYNC, ASPULS and D08\_E from VME64x-chip represent the CARD\_NR[3:0] – from jumpers S27-S24 on board. DSSYNC with two clock delays (ADDR\_DEC\_PSB\_V2\_2 and output-FF) used for read/write of PSB-chip.  
[VIEWDRAW: library P:\Lab3Lib..\vme\_chip\_lib used] (HB121005).
- V1005: based on V1004, but DTACK\_EXT and BERR\_EXT are used as negative active signals to VME64x-chip (because at power-up configuration of VME64X-CHIP is faster than configuration of VME-CHIP and therefore wrong DTACK and BERR signals are generated after configuration, which causes LEDs="on" of CAEN-controller). (HB201005)  
Because of changes in the VME64x-chip version, the CARD\_NR[3:0] comes from jumpers S31-S28 on board (HB071105).
- V1006: based on V1005, but error-counters for serial-link-chips implemented. (HB071105).
- **V1007:** based on V1006, but JTAG\_CTRL V1.5 implemented, because of Quartus 5.1 and EN\_JTAG is delayed to have proper setup-time for addresses, because of synchronous version of VME64x-chip. (HB050106).

### 2.2 Hardware

The VME-CHIP-PSB is an Altera EP1K100QC208-3.

### 2.3 Firmware

```
chip_id:      0x00018n21      (n = CARD_NR from jumpers S31 - S28)
version:      0x00001007
```

### 2.4 Features of the VME-CHIP-PSB (V1007)

- Cardnumber from VME64x-chip (from jumpers S31-S28 on board).
- Register for chip\_ID and version.
- Register for commands and status (see VME-CHIP-PSB address-table).
- Register for modes of serial-link-chips.
- Register to enable technical- and/or totem-trigger-bits.
- VME-access to PSB-chip with DSSYNC for read and write (two clock delays).
- "JTAG over VME" for configuration of FPGAs.
- Configuration of PSB-chip via VME (changes in hardware of mezz957 necessary!!!).

- DTACK and BERR generation from PSB-chip.
- Error-counters for serial-link-chips.

## 2.5 VME access

### 2.5.1 Base address

Base address of all GT-slaves is encoded on A31-A25 (A24 not used), because of address space of GTL-6U-card. See definition in VME64x-chip for PSB-9U.

### 2.5.2 AM and datatransfer

AM=0x0D and 0x09 „extended data access“ - for single access.

AM=0x0F and 0x0B „extended block transfer“ - for block transfer access.

D16 „word access“ - for all accesses.

See definitions in VME64x-chip for PSB.

## 2.6 Chip selection on PSB-9U-card

With the VME addresses A23-A20 the chip selection is done on the PSB-9U-card.

A23	A22	A21	A20	Chip-name
0	0	0	0	VME-CHIP-PSB
0	0	0	1	PSB-chip-registers
0	0	1	0	PSB-chip-memories

## 2.7 VME-CHIP-PSB register

### Registeraddresses:

A31..A24	A23..A20	A19..A05	A06..A01,(00)
8 bits		13bits	6bits
Base address	0000	XXXX	Registers

### 2.7.1 VME-CHIP-PSB address-table

The address-table lists the address-offset which has to be combined with the base-address of the card.

**A23-A00 => Register-name**

### Register for Programmable-chips-configuration:

- |             |   |
|-------------|---|
| 0x000000 => | CMD_ENPROG-register (write/read)        |
| 0x000002 => | CMD_NPROG-register (write/read)         |
| 0x000004 => | CMD_INIT-register (write/read)          |
| 0x000006 => | STAT_INIT-register (read)               |
| 0x000008 => | STAT_DONE-register (read)               |
| 0x00000A => | Configuration register PSB-chip (write) |

### General pulse registers:

- |             |                                |
|-------------|--------------------------------|
| 0x000010 => | Command pulse register (write) |
| 0x000012 => | Status pulse register (read)   |

**General registers:**

0x000014 =>	Command register (write/read)
0x000016 =>	Status register (read)

**Chip ID and version registers:**

0x000020 =>	chip_id_register_3 (read)
0x000022 =>	chip_id_register_2 (read)
0x000024 =>	chip_id_register_1 (read)
0x000026 =>	chip_id_register_0 (read)
0x000028 =>	version_register_3 (read)
0x00002A =>	version_register_2 (read)
0x00002C =>	version_register_1 (read)
0x00002E =>	version_register_0 (read)

**JTAG registers:**

0x000030 =>	tdo_register (write/read)
0x000032 =>	tdi_register (write/read)
0x000034 =>	tms0_register (write/read)
0x000036 =>	tms1_register (write/read)
0x000038 =>	cnt32_register (write/read)
0x00003A =>	mode0_register (write/read)
0x00003C =>	mode1_register (write/read)
0x00003E =>	mode2_register (write/read)

**Serial link mode registers:**

0x000040 =>	SERLINK0-register (write/read)
0x000042 =>	SERLINK1-register (write/read)
0x000044 =>	SERLINK2-register (write/read)
0x000046 =>	LOCKED-register (read)

**EN\_TTIN Register to enable Technical or Totem Trigger bits:**

0x000050 =>	EN_TTIN -register (write/read)
-------------	--------------------------------

**Error-counter Register for serial-link-chips (SERLINK):**

0x000060 =>	ERR_CNT_SERLINK_0-register (read)
0x000062 =>	ERR_CNT_SERLINK_1-register (read)
0x000064 =>	ERR_CNT_SERLINK_2-register (read)
0x000066 =>	ERR_CNT_SERLINK_3-register (read)
0x000068 =>	ERR_CNT_SERLINK_4-register (read)
0x00006A =>	ERR_CNT_SERLINK_5-register (read)
0x00006C =>	ERR_CNT_SERLINK_6-register (read)
0x00006E =>	ERR_CNT_SERLINK_7-register (read)

**Access to/from PSB-chip:**

0x1XXXXX =>	see PSB-chip-registers
0x2XXXXX =>	see PSB-chip-memories

## 2.7.2 Register for Programmable-chips-configuration

The PSB-chip (Virtex-II) is configurable by configuration device and by VMEbus instructions. The selection is made by jumpers. The register-definition for configuration by VMEbus shall be a standard. See P:\Lab3Lib\Altera\Lab3\_altera\sch\xilinx\_conf.

<b>Register names</b>	<b>D7..D1</b>	<b>D0</b>
CMD_ENPROG	-	ENPROG_PSB
CMD_NPROG	-	NPROG_PSB
CMD_INIT	-	INIT_PSB
STAT_INIT	-	INIT_PSB
STAT_DONE	-	DONE_PSB
CONF_PSB	-	configuration data

### 2.7.2.1 *CMD\_ENPROG*-register

**0x000000 => CMD\_ENPROG-register (write/read)**

Bit 0 of the CMD\_ENPROG-register allows sending the configuration bits via VME-bus to the PSB-chip.

### 2.7.2.2 *CMD\_NPROG*-register

**0x000002 => CMD\_NPROG-register (write/read)**

Data-bit 0 = 1 of this register set the NPROG-signal of PSB-chip active. Then it should be reset to '0'. Then the PSB-chip enters into the configuration procedure. The FPGA either waits for configuration data (slave mode) sent via VME or starts to read configuration bits from a serial PROM (master mode).

### 2.7.2.3 *CMD\_INIT*-register

**0x000004 => CMD\_INIT-register (write/read)**

Data-bit 0 = 1 of this register set the NINIT-signal of PSB-chip active.

### 2.7.2.4 *STAT\_INIT*-register

**0x000006 => STAT\_INIT-register (read)**

Read the status of the NINIT-signal of PSB-chip (data-bit 0)

### 2.7.2.5 *STAT\_DONE*-register

**0x000008 => STAT\_DONE-register (read)**

Read the status of the DONE-signal of PSB-chip (data-bit 0). After a successful configuration the PSB-chip sets DONE = 1.

### 2.7.2.6 Configuration register PSB-chip

**0x00000A => Configuration-register PSB-chip (write)**

The register is used to load the configuration bits into the PSB-chip (Virtex-II).

A write access to this register generates a CCLK and sends the data-bit 0 as DIN-signal to the PSB-chip, if the CMD\_ENPROG-register bit has been set before. The VME accesses are repeated until the last bit has been loaded into the PSB-chip.

### 2.7.3 General pulse registers

<b>Register names</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
Command_Pulse_Reg	SET_RUNNING (pulse)	RESET_PSB (pulse*)	RES_DCM_PSB (pulse)	PWRDWN_PSB (pulse)
Status_Pulse_Reg	RUNNING	LOCKED_LED	CLK_LOCKED_PSB	not used

\*) also generated by RESET\_MODE

<b>Register names</b>	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>
Command_Pulse_Reg	not used	not used	not used	not used
Status_Pulse_Reg	not used	not used	not used	not used

#### 2.7.3.1 Command pulse register

**0x000010 => Command-pulse-register (write)**

**D0:** **PWRDWN\_PSB = 1** sends a low active pulse to the PSB-chip setting it into power down mode. NPWRDWN\_B is sent as an open drain signal from the VME-PSB-chip to the PSB-chip.

Remark from data sheet:

*The power-down sequence enables a designer to set the device into a low-power, inactive state. The sequence is initiated by pulling the PWRDWN\_B pin Low. To monitor power-down status, observe the PWRDWN\_B pin. When asserted, power-down has completed. After a successful wake-up, the status pin de-asserts. While powered down, the only active pins are the PWRDWN\_B and DONE. All inputs are off and all outputs are 3-stated. While in the POWERDOWN state, the Power On Reset (POR) circuit is still active, but it does not reset the device if V<sub>CCINT</sub>, V<sub>CCO</sub>, or V<sub>CCAUX</sub> falls below its minimum value. The POR circuit waits until the PWRDWN\_B pin is released before resetting the device. Also, the PROG\_B pin is not sampled while the device is in the POWERDOWN state. The PROG\_B pin becomes active when the PWRDWN\_B pin is released. Therefore, the device cannot be reset while in the POWERDOWN state. The wake-up sequence is the reverse of the power-down sequence.*

**D1:** **RES\_DCM\_PSB = 1** sends a high active pulse to the PSB-chip, to forces the DCM module to lock.

**D2:** **RESET\_PSB = 1** sends a high active pulse to the PSB-chip for reset activities. (RESET\_MODE is another source for RESET\_PSB.)

**D3:** **SET\_RUNNING = 1** sends a high active pulse to set board in RUNNING mode.

#### 2.7.3.2 Status pulse register

**0x000012 => Status-pulse-register (read)**

**D0:** not used.

**D1:** **CLK\_LOCKED\_PSB = 1** indicates, that the DCM module of the PSB chip are locked to the 40 MHz clock.

*This status bit has to be checked immediately after the configuration of the PSB chip and before any other actions. If the chips do not lock then either the clock signal from the TIM board or the on-board oscillator are bad.*

**D2:** **LOCKED\_LED** is the status of an AND of all LOCKED-signals.

*The LOCKED\_LED signal will illuminate the front-panel LED only if all enabled Serial Receiver Chips are locked to the clock of incoming serial data and if the PSB Chip has locked to the system clock.*

**D3:** **RUNNING = 1** board is active.

If *RUNNING* = 0, send a *SET\_RUNNING* command via VME.

#### 2.7.4 General registers

<b>Register names</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
Command_Reg	V_SEL_CABLES	VME_CONF	EN_ROBUS	EN_CHLINK
Status_Reg	not used	STATUS_SEL_VME	not used	EN_CHLINK

<b>Register names</b>	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>
Command_Reg	not used	not used	not used	V_SEL_BACKPL
Status_Reg	not used	not used	JTAG_JUMPER	not used

##### 2.7.4.1 Command register

**0x000014 => Command-register (write)**

- D0:** EN\_CHLINK = 1 enables channel-link-chips, if CLK\_LOCKED\_PSB is active (signal NEN\_CHLINK active).
- D1:** EN\_ROBUS = 1 enables ROBUS (signal NEN\_ROBUS active).
- D2:** VME\_CONF = 1 enables configuration of PSB-chip via VME and switches external mux from PROM to VME.
- D3:** V\_SEL\_CABLES = 1 switches JTAG-chains to cables (MasterBlaster and Parallel-Cable-IV).
- D4:** V\_SEL\_BACKPL = 1 switches JTAG-chains to backplane connection via SCANPSC110 (if V\_SEL\_CABLES = 0).

Truthtable for D4 and D3:

<b>D4</b>	<b>D3</b>	
0	0	JTAG-chains via VME
X	1	JTAG-chains via cables
1	0	JTAG-chains via backplane

##### 2.7.4.2 Status register

**0x000016 => Status-register (read)**

- D0:** EN\_CHLINK is the inverted status of signal NEN\_CHLINK.
- D1:** not used.
- D2:** STATUS\_SEL\_VME = 1 indicates, that configuration of PSB-chip via VME is selected.  
*For configuration of PSB-chip via VME, set VME\_CONF = 1 in the Command-register.*
- D3:** not used.
- D4:** not used.
- D5:** JTAG\_JUMPER = 1 indicates, that SEL\_CABLE\_JTAG-jumper (JP50) is inserted. Therefore JTAG-chains are connected to cables (MasterBlaster and Parallel-Cable-IV).  
*For changing the sources of JTAG-chains, remove the jumper and make the selection with V\_SEL\_CABLES and V\_SEL\_BACKPL in the Command-register.*

## 2.7.5 Chip\_ID and version registers

### 2.7.5.1 Definitions

Chip\_id\_register and version\_register have fixed values in the hardware. These registers have read access only.

The versions 0x00000000 – 0x00000FFF are used for tests.

The versions 0x00001000 – 0xFFFFFFF are used for runs in CMS.

### 2.7.5.2 Settings

chip\_id: 0x00018x21

(x=CARD\_NR comes from jumpers S27-S24 on board)

version: 0x00001004

### 2.7.5.3 Chip\_ID and version registers addresses

**0x000020 => chip\_id\_register\_3 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
chip_ID [31..24]							

**0x000022 => chip\_id\_register\_2 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
chip_ID [23..16]							

**0x000024 => chip\_id\_register\_1 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
chip_ID [15..08]							

**0x000026 => chip\_id\_register\_0 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
chip_ID [07..00]							

**0x000028 => version\_register\_3 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
version [31..24]							

**0x00002A => version\_register\_2 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
version [23..16]							

**0x00002C => version\_register\_1 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
version [15..08]							

**0x00002E => version\_register\_0 (read)**

D7	D6	D5	D4	D3	D2	D1	D0
version [07..00]							

## 2.7.6 JTAG-registers

### 2.7.6.1 Definitions

JTAG registers are used to control JTAG-chains via VME-bus.

For details see JTAGController.vhd from Hannes Sakulin.

### 2.7.7 Serial link mode registers

<b>Register names</b>	<b>D15..D12</b>	<b>D11..D8</b>	<b>D7..D4</b>	<b>D3..D0</b>
SERLINK0	SEND_SYNC_PATTERN [3..0]	LINE_LOOPBACK [3..0]	TPWRDWN [3..0]	ENTR [3..0]
SERLINK1		RPWRDWN [7..0]		ENREC [7..0]
SERLINK2		not used		LOCAL_LOOPBACK [7..0]
LOCKED		not used		LOCKED [7..0]

Remarks:

23.805 AT corrected in table above NTPWRDWN to TPWRDWN, NRPWRDWN to RPWRDWN.

Index [7..0] means DS92LV16 chip number = channel number.

SEND\_SYNC\_PATTERN = 1 => transmitter sends SYNC patterns so that a receiver can synchronize to the incoming data stream.

LINE\_LOOPBACK = 1 => the serial received data are returned via the serial transmission line.

TPWRDWN = 1 => powers down the transmitter part of the chip (signal NTPWRDWN=0).

ENTR = 1 => enables the transmitter circuits of the chip.

LOCAL\_LOOPBACK = 1 => returns parallel Transmit-data to parallel Receiver lines.

RPWRDWN = 1 => powers down the receiver part of the chip (signal NRPWRDWN=0).

ENREC = 1 => enables the receiver circuits of the DS92LV16 chip.

- 0x000040 => SERLINK0-register (write/read)**
- 0x000042 => SERLINK1-register (write/read)**
- 0x000044 => SERLINK2-register (write/read)**
- 0x000046 => LOCKED-register (read)**

### 2.7.8 EN\_TTIN Register to enable Technical or Totem Trigger bits

Enables the LVDS receivers for Technical Trigger resp. Totem Trigger signals.

Disabled Receivers send bits 1111 = 'F'.

See also registers in PSB9U chip to switch between Parallel LVDS and Serial input channels.

<b>Register names</b>	<b>D15..D0</b>
EN_TTIN	EN_R[15..0]

EN\_Rxx = 1 => enables parallel LVDS receivers for Parallel cable xx (0 = default).

- 0x000050 => EN\_TTIN-register (write/read)**

## 2.7.9 Error-counter Register for serial-link-chips (SERLINK)

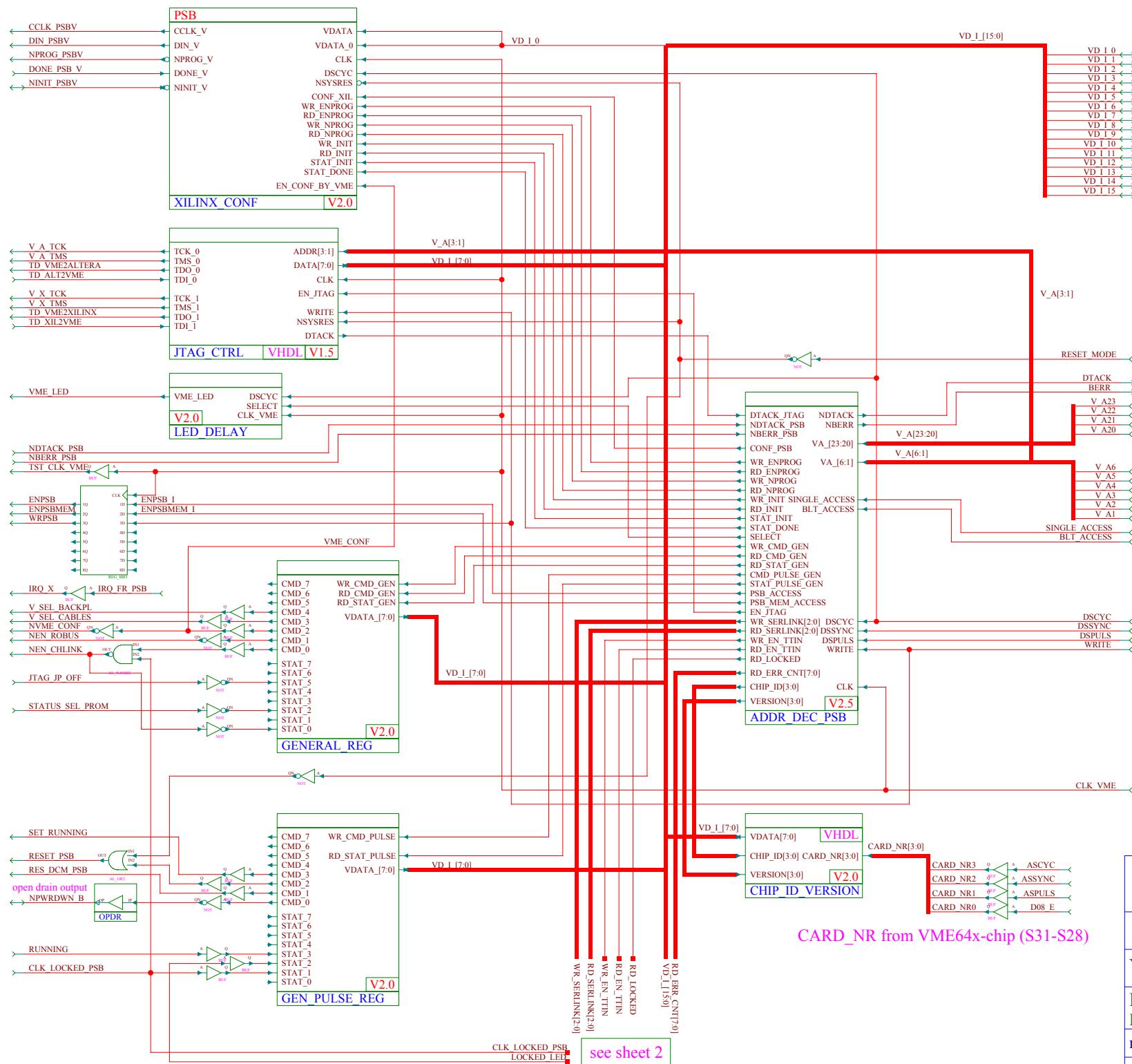
The Error-counter Register for serial-link-chips contains the number of missed LOCKED-signals of the serial-link-chip. If there is an overflow in the counter, the value remains at 0xFF. Reading the register causes a clear on the counter.

<i>Register names</i>	<b>D7..D0</b>
ERR_CNT_SERLINK_x	Errors caused by missing LOCKED-signal of serial-link-chip

**0x000060 =>   ERR\_CNT\_SERLINK\_0-register (read)**  
**0x000062 =>   ERR\_CNT\_SERLINK\_1-register (read)**  
**0x000064 =>   ERR\_CNT\_SERLINK\_2-register (read)**  
**0x000066 =>   ERR\_CNT\_SERLINK\_3-register (read)**  
**0x000068 =>   ERR\_CNT\_SERLINK\_4-register (read)**  
**0x00006A =>   ERR\_CNT\_SERLINK\_5-register (read)**  
**0x00006C =>   ERR\_CNT\_SERLINK\_6-register (read)**  
**0x00006E =>   ERR\_CNT\_SERLINK\_7-register (read)**

## 2.8 DTACK/BERR-generation

Writing to writeable registers and reading from readable registers generates a DTACK signal. Access to/from PSB-chip generates a DTACK and a BERR signal.



# VME-CHIP-PSB

## VME\_CHIP\_PSB

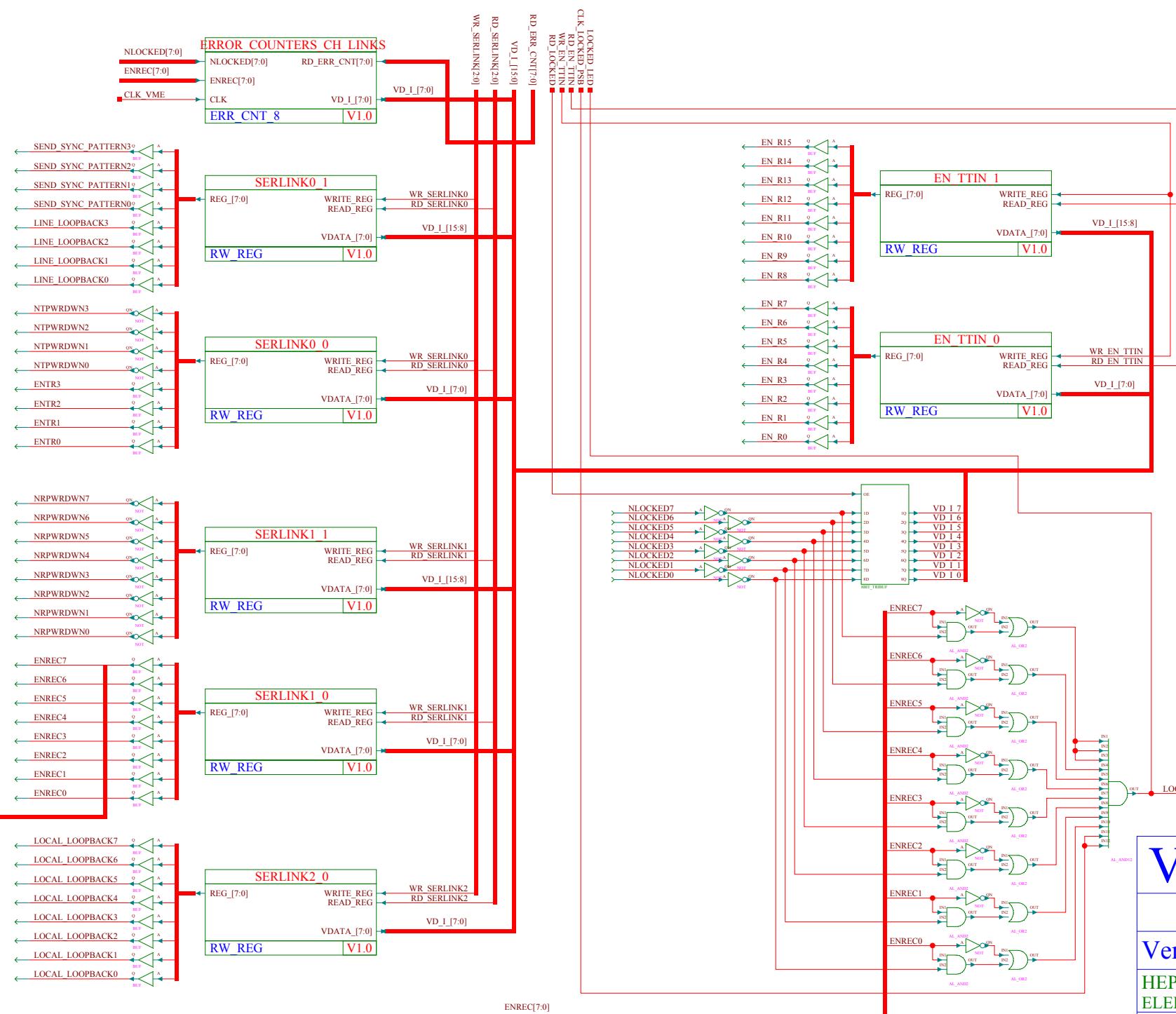
Version: V1007

HEPHY VIENNA  
ELEKTRONIK 1

sheet 1 of 2

modified by: HB 1-5-2006\_13:14

checked by: CHECKER 0-00-0000\_00:00



# VME-CHIP-PSB

## VME\_CHIP\_PSB

Version: V1007

HEPHY VIENNA  
ELEKTRONIK 1

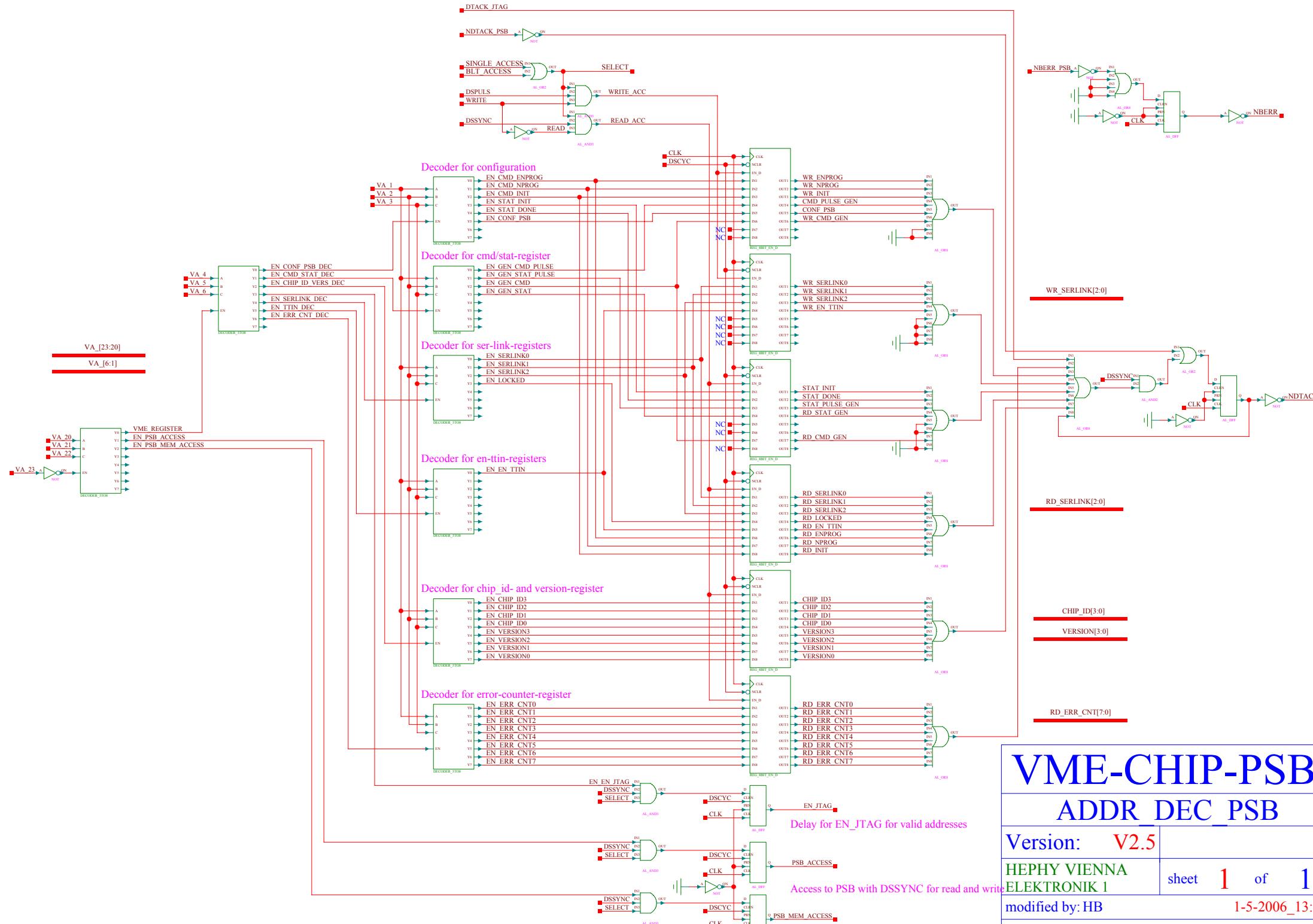
sheet 2 of 2

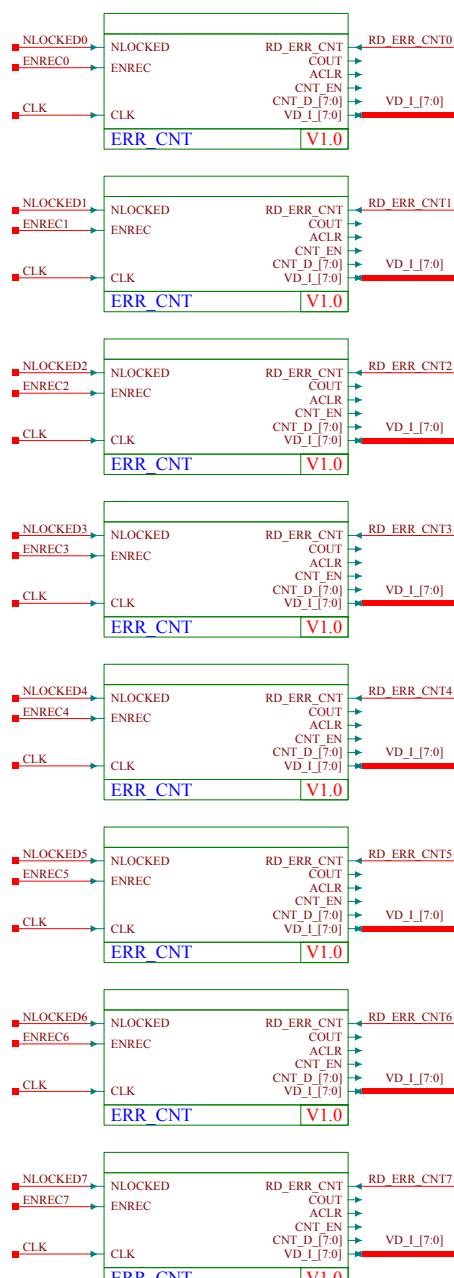
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checked by: CHECKER

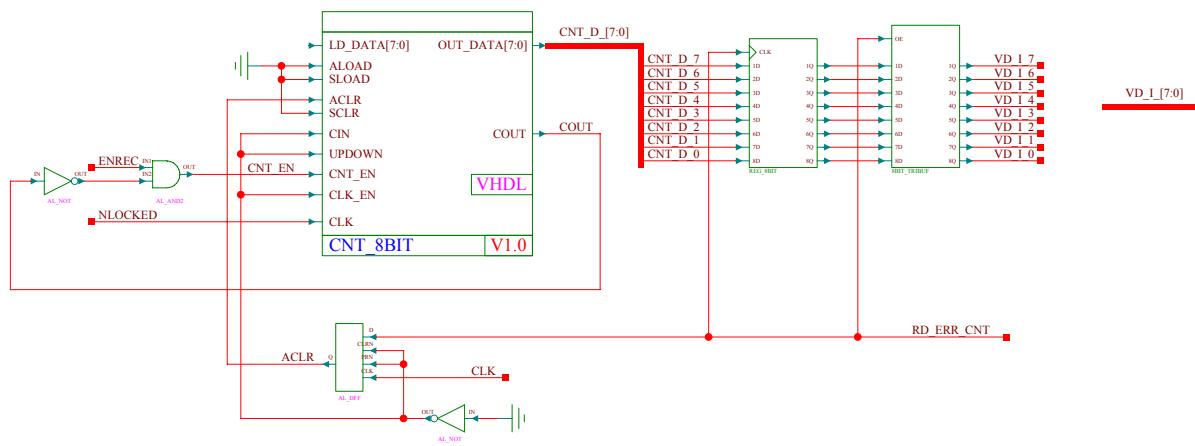
0-00-0000\_00:00





NLOCKED[7:0]  
ENREC[7:0]  
RD\_ERR\_CNT[7:0]

VME-CHIP-PSB	
ERR_CNT_8	
Version:	V1.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by: HB	11-7-2005_14:22
checked by: CHECKER	0-00-0000_00:00



VME-CHIP-PSB

ERR\_CNT

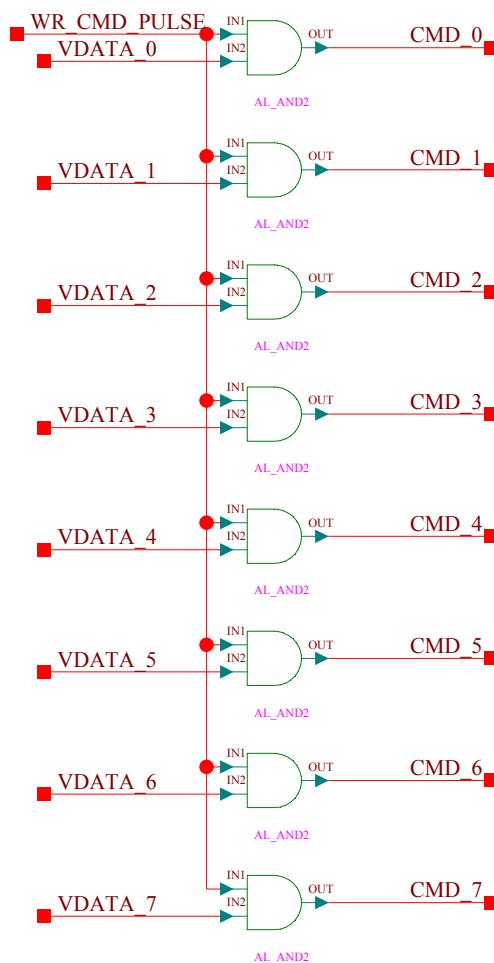
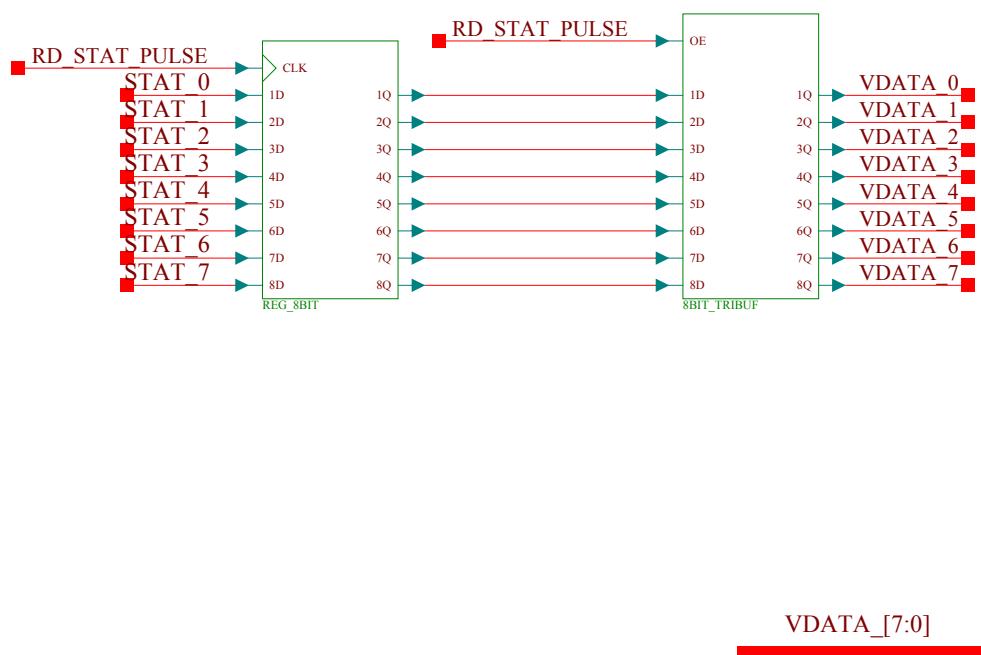
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HEPHY VIENNA  
ELEKTRONIK 1

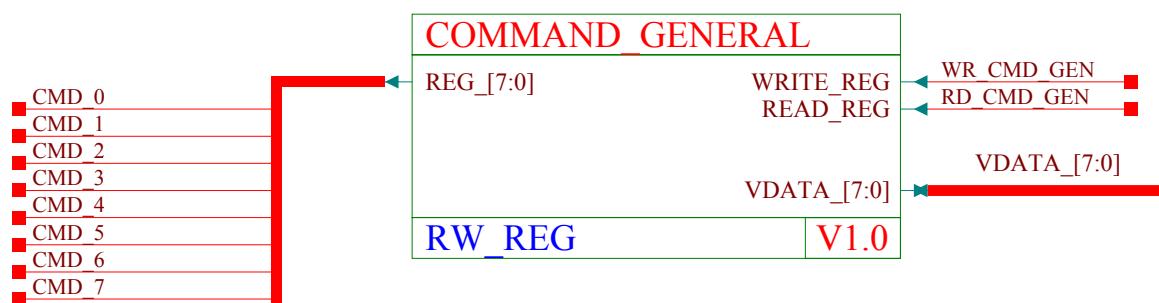
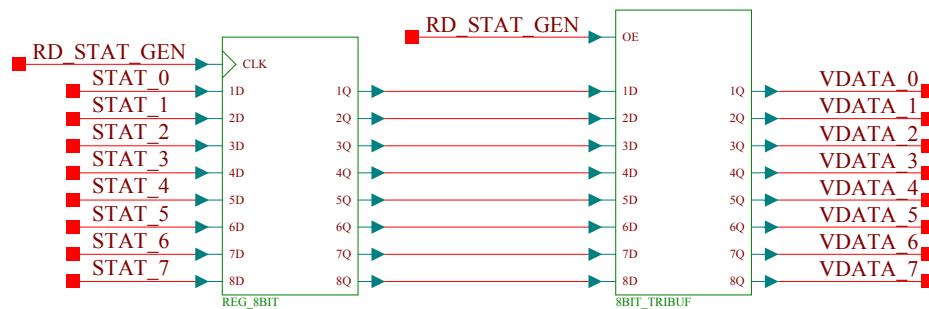
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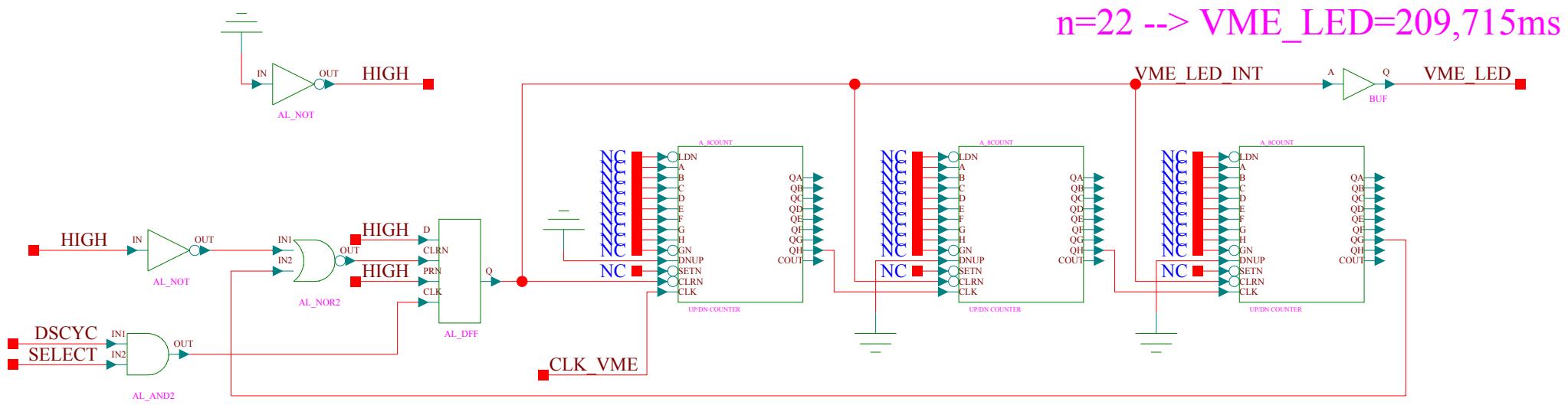
checked by: CHECKER 0-00-0000\_00:00



VME-CHIP	
GEN_PULSE_REG	
Version:	V2.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by HB	9-1-2005 10:29
checked by: CHECKER	0-00-0000 00:00



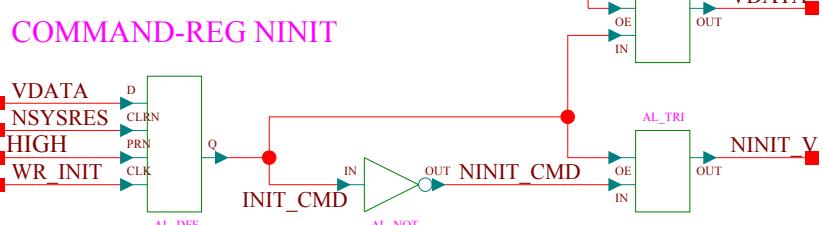
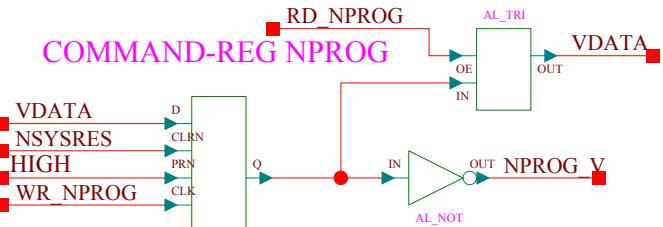
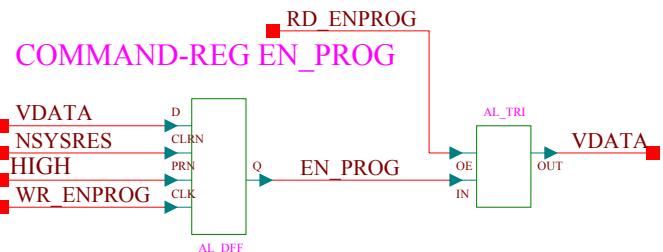
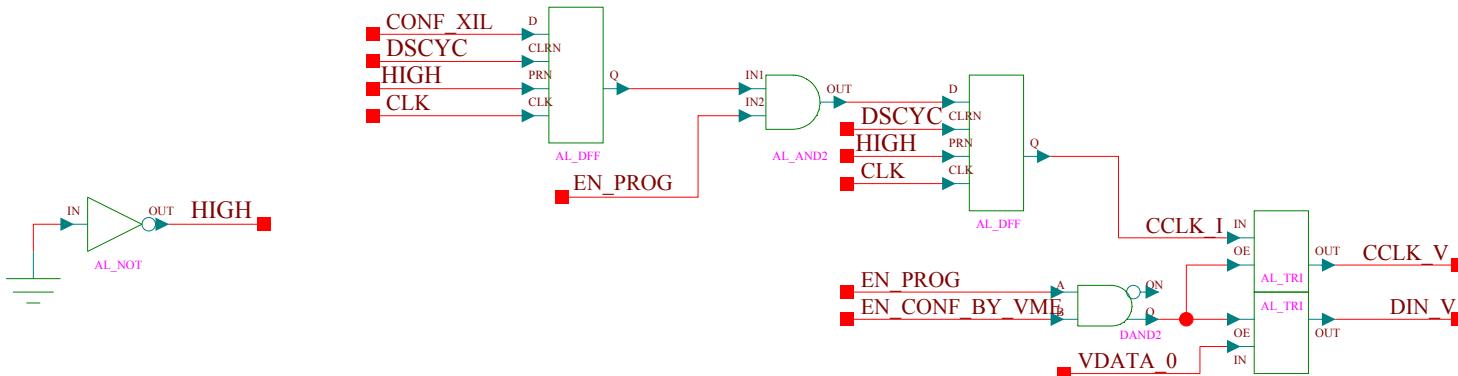
VME-CHIP	
GENERAL_REG	
Version:	V2.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by HB	9-1-2005 10:29
checked by: CHECKER	0-00-0000 00:00



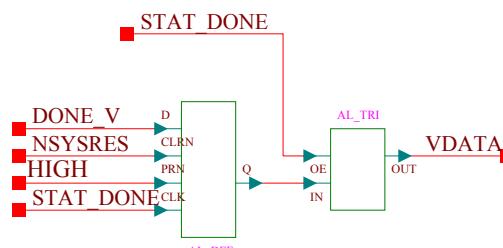
$$\text{Formel: } (2^{**}(n+1)-1)*25\text{ns} \quad (25\text{ns} = \text{CLK\_VME})$$

VME-CHIP	
LED_DELAY	
Version:	V2.0
HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
modified by HB	9-1-2005 10:32
checked by: CHECKER	0-00-0000 00:00

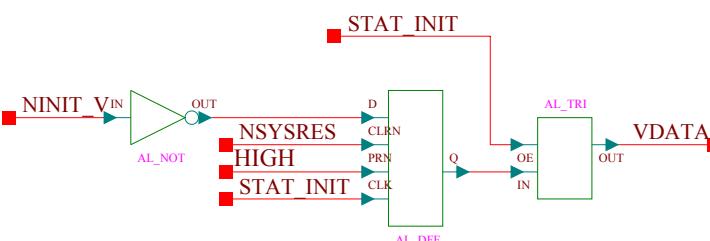
## CONFIGURATION OF XILINX CHIP (CCLK, DIN)



### STATUS-REG DONE



### STATUS-REG NINIT



**VME-CHIP**

**XILINX CONF**

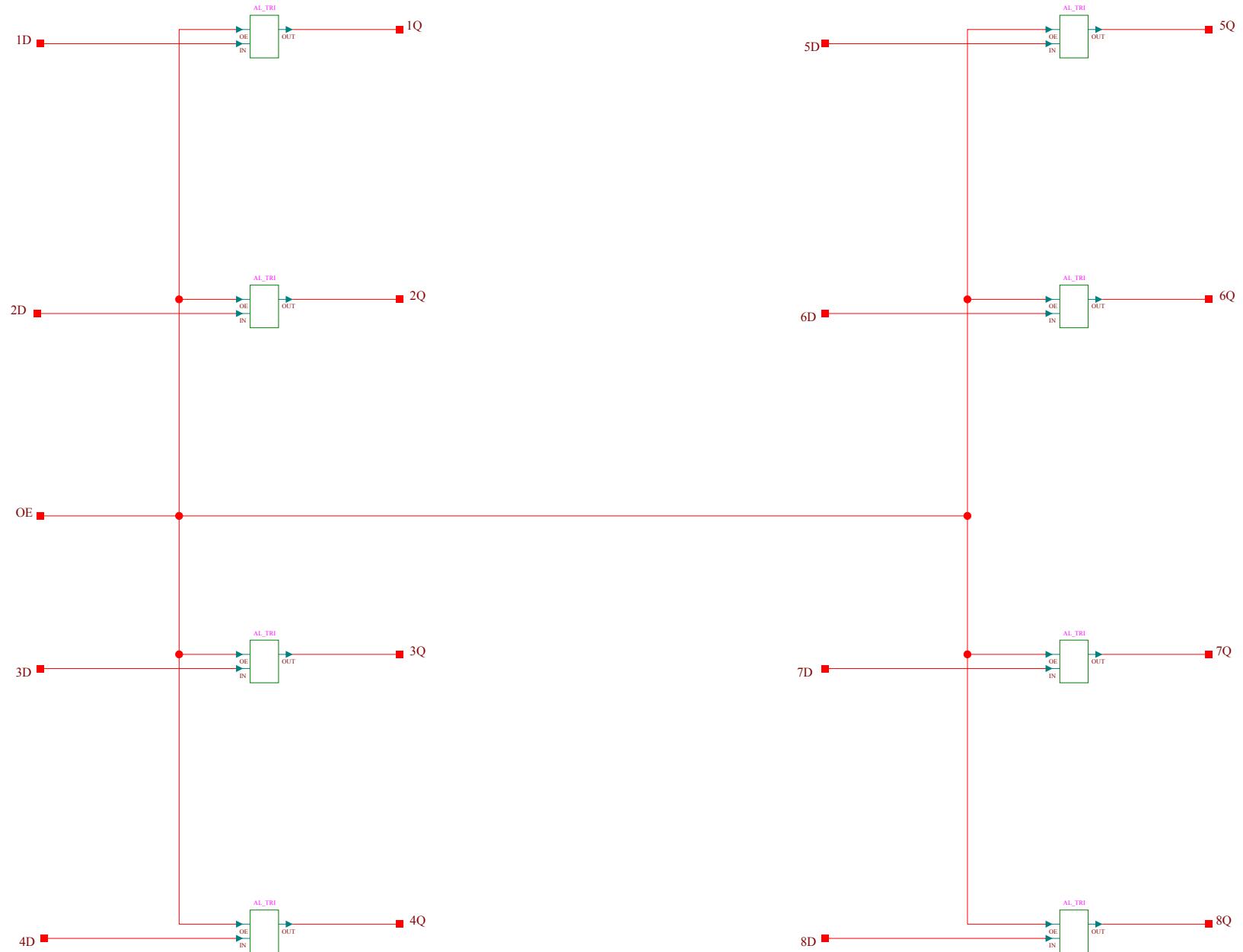
Version:	V2.0	Configuration
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HEPHY VIENNA ELEKTRONIK 1	sheet 1 of 1
------------------------------	--------------

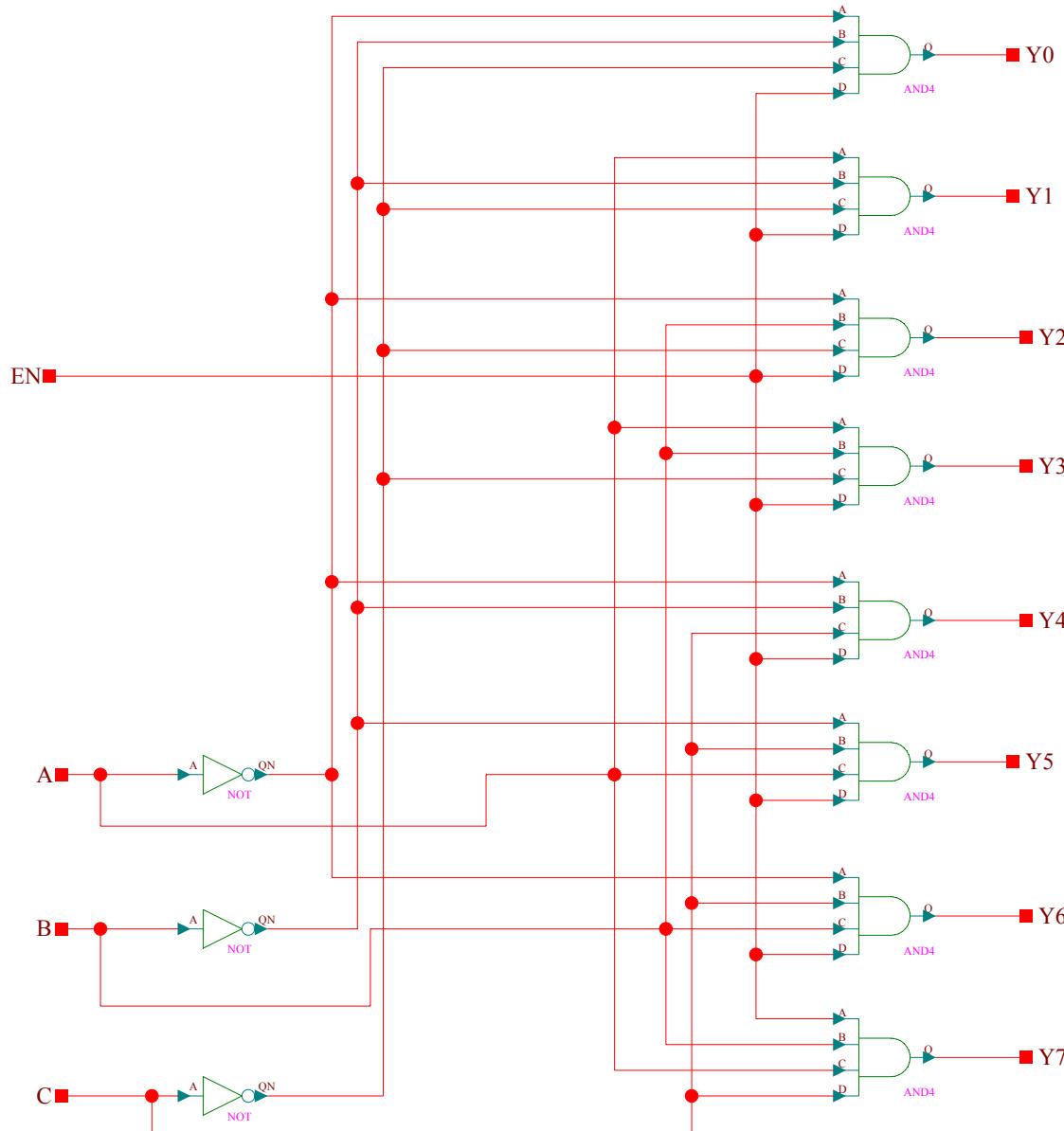
modified by HB 8-26-2005 14:23

checked by: CHECKER 0-00-0000 00:00

# 8bit\_tribuf

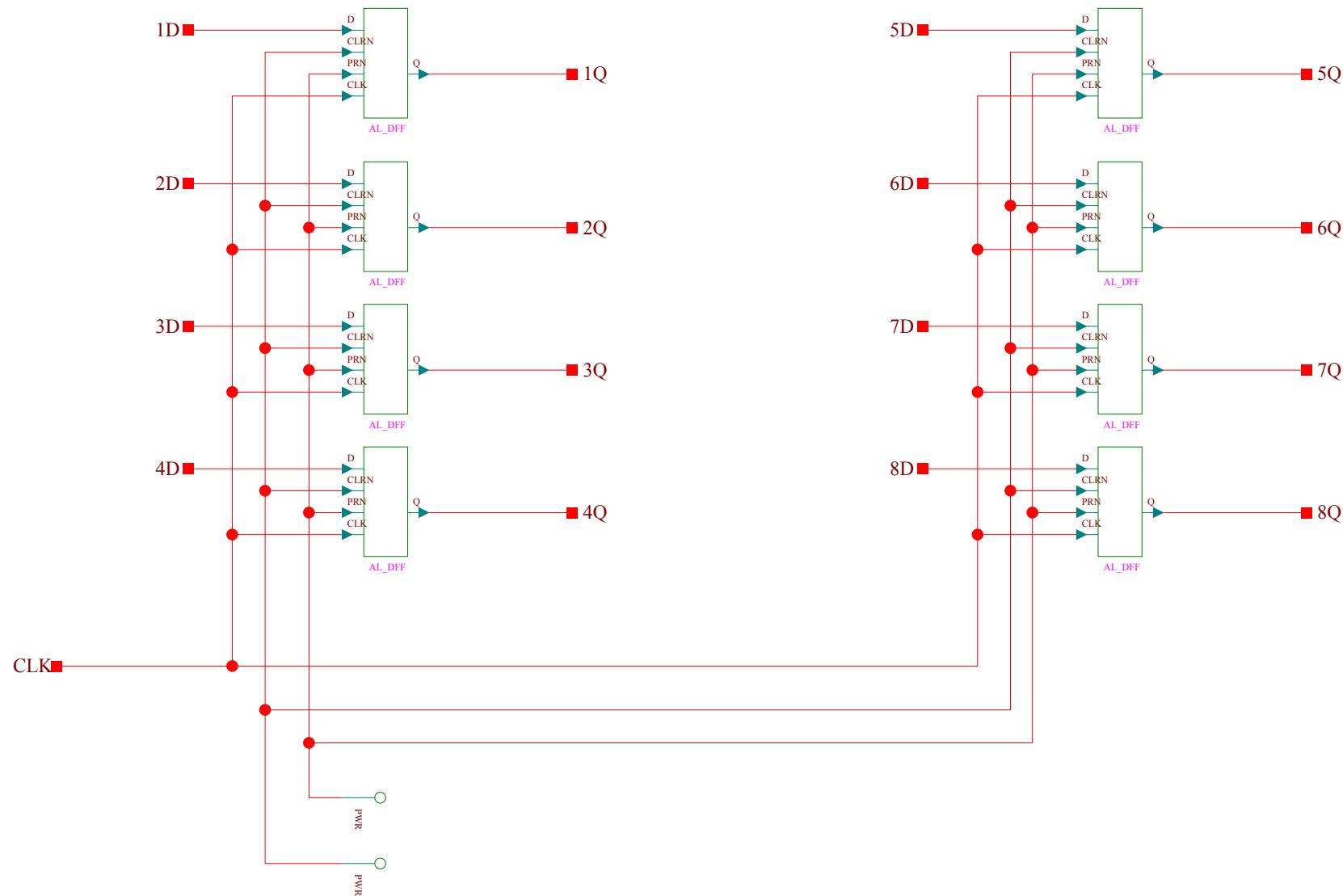


# decoder\_3to8

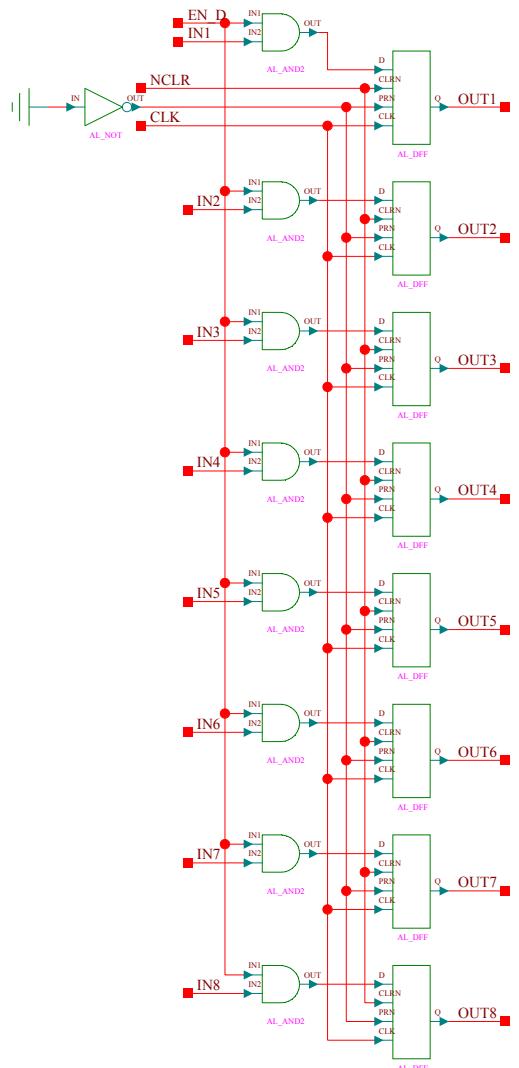


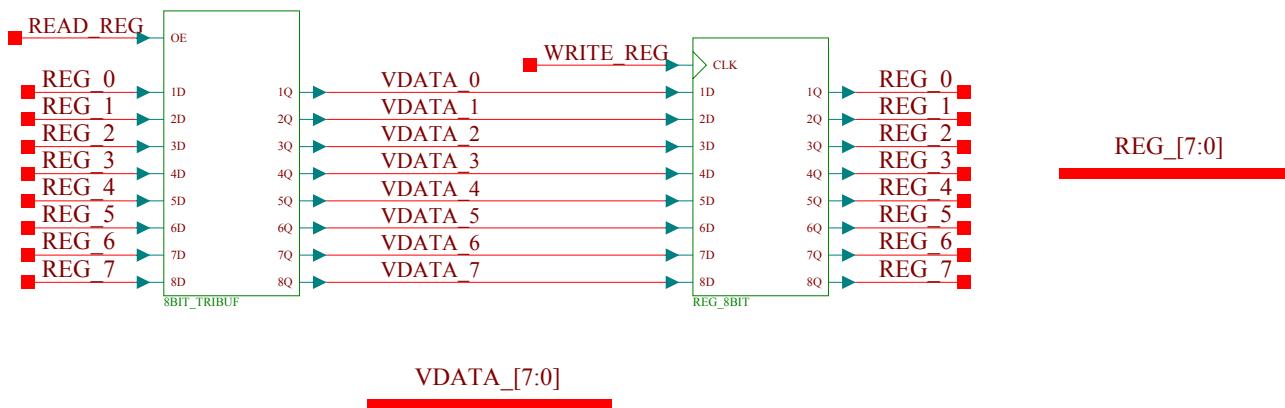
# reg\_8bit

8-bit register generated by LAB3



## reg\_8bit\_en\_d





**VME-CHIP**

**RW\_REG**

Version: **V1.0**

HEPHY VIENNA  
ELEKTRONIK 1

sheet **1** of **1**

modified by HB **9-9-2005 14:49**

checked by: CHECKER **0-00-0000 00:00**

```
-----
--  

-- LOGIC CORE: vme-chip logic  

-- MODULE NAME: chip_id_version  

-- INSTITUTION: Hephy Vienna  

-- DESIGNER: H. Bergauer  

--  

-- VERSION: V2.0  

-- DATE: 08 2005  

--  

-- FUNCTIONAL DESCRIPTION:  

-- chip_id and version register (read only)  

--  

-----  

LIBRARY ieee;  

USE ieee.std_logic_1164.ALL;  

LIBRARY altera;  

USE altera.maxplus2.ALL;  

USE work.constant pkg.ALL;  

ENTITY chip_id_version IS
    PORT(
        VDATA      : INOUT STD_LOGIC_VECTOR(7 DOWNTO 0);
        CARD_NR    : IN     STD_LOGIC_VECTOR(3 DOWNTO 0);
        CHIP_ID    : IN     STD_LOGIC_VECTOR(3 DOWNTO 0);
        VERSION    : IN     STD_LOGIC_VECTOR(3 DOWNTO 0));
END chip_id_version;  

ARCHITECTURE rtl OF chip_id_version IS
    -- CONSTANT for card_name and version defined in working-dir\vhdl !!!  

    SIGNAL chip_id_value : std_logic_vector(31 downto 0);
    CONSTANT cms_gt: STD_LOGIC_VECTOR(15 DOWNTO 0) := X"0001"; -- fixed code for GT-system = 0x0001
    -- card_nr will be delivered from VME64x-chip, HB250805
    CONSTANT chip_name: STD_LOGIC_VECTOR(3 DOWNTO 0) := X"2"; -- fixed code for chip_name = 0x2
    CONSTANT chip_nr: STD_LOGIC_VECTOR(3 DOWNTO 0) := X"1"; -- fixed code for chip_nr = 0x1
    BEGIN
        chip_id_value <= cms_gt & card_name & card_nr & chip_name & chip_nr;
      

    -- chip_id and version register (read only)
    tri_chip_id_3:
    FOR i IN 0 TO 7 GENERATE

```

```
call_chip_id_3: tri
PORT MAP(chip_id_value(i+24),
         chip_id(3),
         vdata(i));
END GENERATE tri_chip_id_3;

tri_chip_id_2:
FOR i IN 0 TO 7 GENERATE
    call_chip_id_2: tri
    PORT MAP(chip_id_value(i+16),
              chip_id(2),
              vdata(i));
END GENERATE tri_chip_id_2;

tri_chip_id_1:
FOR i IN 0 TO 7 GENERATE
    call_chip_id_1: tri
    PORT MAP(chip_id_value(i+8),
              chip_id(1),
              vdata(i));
END GENERATE tri_chip_id_1;

tri_chip_id_0:
FOR i IN 0 TO 7 GENERATE
    call_chip_id_0: tri
    PORT MAP(chip_id_value(i),
              chip_id(0),
              vdata(i));
END GENERATE tri_chip_id_0;

tri_version_3:
FOR i IN 0 TO 7 GENERATE
    call_version_3: tri
    PORT MAP(version_value(i+24),
              version(3),
              vdata(i));
END GENERATE tri_version_3;

tri_version_2:
FOR i IN 0 TO 7 GENERATE
    call_version_2: tri
    PORT MAP(version_value(i+16),
              version(2),
              vdata(i));
END GENERATE tri_version_2;
```

```
tri_version_1:  
FOR i IN 0 TO 7 GENERATE  
    call_version_1: tri  
    PORT MAP(version_value(i+8),  
              version(1),  
              vdata(i));  
END GENERATE tri_version_1;  
  
tri_version_0:  
FOR i IN 0 TO 7 GENERATE  
    call_version_0: tri  
    PORT MAP(version_value(i),  
              version(0),  
              vdata(i));  
END GENERATE tri_version_0;  
  
END ARCHITECTURE rtl;
```

```

-----
-- Title      : Top of JTAG Controller for vme-chip of GT-boards
-- Project    :
-----
-- File       : jtag_ctrl.vhd
-- Author     : H. Bergauer
-- Company   :
-----
-- Description: top module for VIEWDRAW of JTAG Controller
-----
-- $Date: 2006/01/05 08:54:17 $
-- $Revision: 1.5 $

library IEEE;
library work;
use IEEE.std_logic_1164.all;
use IEEE.numeric_std.all;
LIBRARY altera;
USE altera.maxplus2.ALL;

-- Entity Declaration
entity jtag_ctrl is
port (
    addr      : in  std_logic_vector(3 downto 1);
    data      : inout std_logic_vector(7 downto 0);
    clk       : in  std_logic;
    en_jtag   : in  std_logic;
    dssync    : in  std_logic;
    write     : in  std_logic;
    nsysres   : in  std_logic;
    dtack     : out std_logic;
    tck_0     : out std_logic;
    tck_1     : out std_logic;
    tms_0     : out std_logic;
    tms_1     : out std_logic;
    tdo_0     : out std_logic;
    tdo_1     : out std_logic;
    tdi_0     : in  std_logic;
    tdi_1     : in  std_logic
);
end;
-- Architecture declaration
architecture rtl of jtag_ctrl is
-- address parameters for JTAGController
constant base_address : integer := 0;
constant address_increment : integer := 2;
constant addr_high : integer := 3;
constant addr_low : integer := 1;
component JTAGController is
generic (
    base_address      : integer := 0; -- base address (in bytes)
    address_increment : integer := 2; -- increment (2 for word access,
                                      -- 4 for long word access)
    addr_high        : integer := 3; -- upper index of vme_addr vector
    addr_low         : integer := 1; -- lower index of vme_addr vector
);

```

```

port (□
  -- JTAG port□
  -- to be connected directly to I/O pins of chip□
  oTck : out std_logic; □
  oTms0 : out std_logic;□
  oTms1 : out std_logic;□
  oTdo : out std logic;□
  iTdi0 : in std logic;□
  iTdi1 : in std logic;□
  -- VME port□
  vme_addr : in std_logic_vector(addr_high downto addr_low); □
  vme_data : in std_logic_vector(15 downto 0); -- has to be at least 8 bit□
  vme_en : in std logic; -- should not be a pulse when writing□
  vme_wr : in std logic; -- state. must remain for at least two□
  -- clocks after enable goes to 0□
  vme_dtack : out std logic; -- not inverted□
  vme_data_out : out std_logic_vector(15 downto 0);□
  vme_en_out : out std logic;□
  -- Clock and control□
  clk : in std logic;□
  reset : in std logic); -- asynchronous reset, active high□
end component;□
-- signal vme_en_jtag : std logic;□
signal en_tri : std logic;□
signal tck : std logic;□
signal tdo : std logic;□
signal data_jtag : std_logic_vector(15 downto 0);□
signal data_in : std logic_vector(15 downto 0);□
signal data_out : std logic_vector(15 downto 0);□
signal sysres : std logic;□
begin□
  -- verändert HB191205 wegen Quartus 5.1 Fehlermeldung□
  en_tri <= en_jtag AND NOT write;□
  --data <= data_out(7 downto 0);□
  data_in <= X"00" & data(7 downto 0);□
  tck_0 <= tck;□
  tck_1 <= tck;□
  tdo_0 <= tdo;□
  tdo_1 <= tdo;□
  sysres <= NOT nsysres;□
  inst_jtag: JTAGController□
    generic map(base_address, address_increment, addr_high, addr_low)□
    port map(□
      oTck => tck,□
      oTms0 => tms_0,□
      oTms1 => tms_1,□
      oTdo => tdo,□
      iTdi0 => tdi_0,□
      iTdi1 => tdi_1,□
      vme_addr => addr,□
      vme_data => data_in,□
      -- vme_en => vme_en_jtag,□
      vme_en => en_jtag,□
      vme_wr => write,□
      vme_dtack => dtack,□
      vme_data_out => data_jtag,□
      clk => clk,□
      reset => sysres□
    );□

```

```
tri_loop:□
FOR i IN 0 TO 7 GENERATE□
    inst_tri: tri□
        PORT MAP(data_jtag(i), en_tri, data(i));□
END GENERATE tri_loop;□
□
end rtl;□
```

```

-----
-- Title      : JTAG Controller
-- Project    :
-----
-- File       : JTAGController.vhd
-- Author     : SAKULIN Hannes <hsakulin@dsy-srv3.cern.ch>
-- Company   :
-----
-- Description: Simplified version of a ScanPSC100 JTAG controller
-----
-- $Date: 2004/10/25 12:54:54 $
-- $Revision: 1.10 $

-- Revision-Description:
-- generic parameter for address width of vme_addr implemented (HB)

-- based on:
-- File name: Controller_soc2.vhd %
-- Title: VHDL Controller Chip for the PHTF Soc2%
-- Author: JEJr. %
-- This VHDL Modul of the Board's VME Controller%
-- Version | Author | Mod. Date | Change |
-- 1 | JEJr | 31.03.2004 | First design (derived from ETTF_contr_jxx) |

library IEEE;
library work;
use IEEE.std_logic_1164.all;
use IEEE.numeric_std.all;
USE IEEE.STD_LOGIC_UNSIGNED.ALL; -- for +- operators

-- Entity Declaration

entity JTAGController is
  generic (
    base_address      : integer := 0;      -- base address (in bytes)
    address_increment : integer := 2;      -- increment (2 for word access,
                                            -- 4 for long word access)
    addr_high         : integer := 3;      -- upper index of vme_addr vector
    addr_low          : integer := 1;      -- lower index of vme_addr vector
  );
  port (
    -- JTAG port
    -- to be connected directly to I/O pins of chip
    oTck : out std_logic;
    oTms0 : out std_logic;
    oTms1 : out std_logic;
    oTdo : out std_logic;
    iTdi0 : in  std_logic;
    iTdi1 : in  std_logic;

    -- VME port
    vme_addr      : in  std_logic_vector(addr_high downto addr_low);
    vme_data      : in  std_logic_vector(15 downto 0); -- has to be at least 8 bit
    vme_en        : in  std_logic;   -- should not be a pulse when writing
    vme_wr        : in  std_logic;   -- state. must remain for at least two
                                      -- clocks after enable goes to 0
    vme_dtack     : out std_logic;   -- not inverted
  );
end entity JTAGController;

```

```

vme_data_out    : out    std_logic_vector(15 downto 0);□
vme_en_out      : out    std_logic;□
  □
-- Clock and control□
clk              : in     std_logic;□
reset            : in     std_logic); -- asynchronous reset, active high□
  □
end;□
□
-----□
-- VME signals:□
-- □
-- the unit assumes that data and address are valid for the whole time□
-- that vme en is active□
-- □
-- the unit further assumes that vme_en is a synchronous signal (no□
-- asynchronous clear) as the falling edge of vme en is used to trigger actions.□
-----□
  □
  □
-----□
-- Architecture declaration□
-----□
  □
architecture behavioral of JTAGController is□
  □
  -- need the following attributes to force Synplify to use□
  -- input and output flip-flops□
  -- (currently does not work for TDI, TMS)□
  attribute syn_useioff           : boolean;□
  attribute syn_useioff of behavioral : architecture is true;□
  □
-- JTAG Registers□
  □
  signal mode0_reg : std_logic_vector( 7 downto 0);□
  signal mode1_reg : std_logic_vector( 7 downto 0);□
  signal mode2_reg : std_logic_vector( 7 downto 0);□
  signal cnt32_reg : unsigned (31 downto 0);□
  signal tms0_reg  : std_logic_vector( 7 downto 0);□
  signal tms1_reg  : std_logic_vector( 7 downto 0);□
  signal tdo_reg   : std_logic_vector( 7 downto 0);□
  signal tdi_reg   : std_logic_vector( 7 downto 0);□
  □
  □
-- JTAG Register Enable Signals□
  □
  signal ena        : std_logic;□
  signal mode0_ena : std_logic;□
  signal mode1_ena : std_logic;□
  signal mode2_ena : std_logic;□
  signal cnt32_ena : std_logic;□
  signal tms0_ena  : std_logic;□
  signal tms1_ena  : std_logic;□
  signal tdo_ena   : std_logic;□
  signal tdi_ena   : std_logic;□
  □
  signal tdi_ena_d : std_logic;□
  signal tdi_ena_d2: std_logic;□
  □
  signal tdi_stat : std_logic;□
  □
-- JTAG status signals□
  signal cnt_loaded    : std_logic;□
  signal tdo_empty     : std_logic;□
  signal tms0_empty    : std_logic;□
  signal tms1_empty    : std_logic;□
  signal tdi_full      : std_logic;□
  signal cnt_loaded_del: std_logic;□
  signal tdo_empty_del : std_logic;□

```

```

signal tms0_empty_del : std_logic;□
signal tms1_empty_del : std_logic;□
signal tdi_full_del   : std_logic;□
□
signal cnt_pointer : unsigned ( 1 downto 0);□
signal dtack_ff    : std_logic;□
□
signal tms0_a_exit : std logic;□
signal tms1_a_exit : std logic;□
□
--DTACK flip-flops□
□
signal tdo_rdy_ff : std_logic;□
signal tdi_rdy_ff : std logic;□
signal reg_rdy_ff      : std_logic;□
signal reg_rdy_ff_del  : std_logic;□
signal ds_del_sig      : std logic;□
□
□
-- JTAG Registers□
□
signal jtag_ck_cnt      : unsigned (2 downto 0);□
signal jtag_ck          : std logic;□
signal jtag_ck_pulse    : std_logic;□
□
signal shift_enable : std logic;□
□
□
signal tms01_sig : std logic; -- Memorize last TMS action□
□
□
signal cnt001 : std logic;□
□
□
signal tdo_enable      : std_logic;□
signal tdi_enable       : std_logic;□
signal cnt32_enable    : std_logic;□
signal tms0_enable     : std_logic;□
signal tms1_enable     : std_logic;□
signal auto_tms_h      : std_logic;□
signal int_reset        : std_logic;□
signal int_dtack        : std_logic;□
□
signal cnt_stat         : std_logic;□
signal cnt_stat_del    : std_logic;□
signal tms0_stat        : std_logic;□
signal tms0_stat_del   : std_logic;□
signal tms1_stat        : std_logic;□
signal tms1_stat_del   : std_logic;□
signal tdo_stat         : std_logic;□
signal tdo_stat_del    : std_logic;□
□
-- JTAG Outputs internal name□
□
signal stms0 : std_logic;□
signal stms1 : std_logic;□
signal stdo  : std_logic;□
signal stdi0 : std_logic;□
signal stdi1 : std_logic;□
□
□
function addr_match (□
  constant vme_addr : std_logic_vector;□
  constant address   : integer)           -- in bytes□
  return boolean is□
□
variable my_addr_vec : std_logic_vector(vme_addr'high downto 0);□
begin -- process vme_addr_decode□
  my_addr_vec := std_logic_vector( TO_UNSIGNED ( address, vme_addr'high+1 ) );□

```

```

    return my_addr_vec(addr_high downto addr_low) = vme_addr(addr_high downto addr_low);□
end;□
□
signal vme_en_d : std_logic;□
□
signal nreset : std_logic;□
signal vme_cycend_p : std_logic;□
□
begin -- Main□
□
nreset <= not reset;□
□
-----□
-- Address Decode□
-----□
□
tdo_ena <= vme_en when addr_match(vme_addr, base_address) else '0';□
tdi_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment) else '0';
tms0_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*2) else '0';
tms1_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*3) else '0';
cnt32_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*4) else '0';
mode0_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*5) else '0';
mode1_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*6) else '0';
mode2_ena <= vme_en when addr_match(vme_addr, base_address+ address_increment*7) else '0';
□
ena <= mode0_ena
      or mode1_ena
      or mode2_ena
      or ( tdi_ena and tdi_full )
      or cnt32_ena
      or tdo_ena
      or tms0_ena
      or tms1_ena;□
□
-----□
-- Synchronization□
-----□
□
Synchro : process (clk, nreset)□
□
begin
  if nreset = '0' then
    vme_cycend_p <= '0';□
    vme_en_d <= '0';□
  elsif clk'event and clk='1' then
    vme_en_d <= vme_en;□
    □
    if (( vme_en = '0' ) and ( vme_en_d = '1' )) then
      vme_cycend_p <= '1';□
    else
      vme_cycend_p <= '0';□
    end if;□
  end if;□
end process Synchro;□
□
-----□
-- Write registers□
-----□
□
write_reg: process (clk, reset) □
begin -- process write_reg
  if reset = '1' then
    mode0_reg           <= "00100000"; --HS
    mode1_reg           <= (others => '0');□
    mode2_reg (1 downto 0) <= (others => '0');□
  elsif clk'event and clk = '1' then -- rising clock edge
    if int_reset = '1' then

```

```

mode0_reg           <= "00100000"; --HS
mode1_reg           <= (others => '0'); 
-- do not reset mode2 as it is being written to
end if;
if (vme_wr = '1') then
  if (mode0_ena = '1' and vme_en_d = '0') then mode0_reg <= vme_data(7 downto 0); er
  if (mode1_ena = '1' and vme_en_d = '0') then mode1_reg <= vme_data(7 downto 0); er
  if (mode2_ena = '1' and vme_en_d = '0') then mode2_reg(1 downto 0) <= vme_data(1 c
end if;□
end if;□
end process write reg;□
-- mode registers are complete□
-----
-- Connect status signals to registers□
-----
tdo_enable    <= mode0_reg (7);□
tdi_enable    <= mode0_reg (6);□
cnt32_enable <= mode0_reg (5);□
tms0_enable   <= mode0_reg (4);□
tms1_enable   <= mode0_reg (3);□
auto tms h   <= mode0_reg (1);□
-- mode0, bit 0: loopback not implemented.□
□
  □
int_reset <= mode2_reg (1);□
  □
  □
-- mode2, bit 0: single step not implemented□
-- mode2, bit 2: update status not implemented (status is always updated)□
-- mode2, bit 3: continuous update not implemented (status is always updated)□
  □
mode2_reg (7) <= tdo_empty;□
mode2_reg (6) <= tdi_full;□
mode2_reg (5) <= not cnt_loaded;□
mode2_reg (4) <= tms0_empty;□
mode2_reg (3) <= tms1_empty;□
mode2_reg (2) <= shift_enable; --????□
□
  -- TBD: jtag mode 2 reg reset bit has to return to 0 after reset□
  -- mode2, bit0: Single step CNT32 not implemented.□
  -----
  -- Read registers□
  -----
  □
vme_data_out <=      ("00000000" & mode0_reg ) when mode0_ena = '1'□
  else ("00000000" & mode1_reg ) when mode1_ena = '1'□
  else ("00000000" & mode2_reg ) when mode2_ena = '1'□
  else ("00000000" & tdi_reg ) when ((tdi_ena = '1') and (tdi_full =
  else ("00000000" & std_logic_vector (cnt32_reg ( 7 downto 0 ))) when
  else ("00000000" & std_logic_vector (cnt32_reg ( 15 downto 8 ))) when
  else ("00000000" & std_logic_vector (cnt32_reg ( 23 downto 16 ))) when
  else ("00000000" & std_logic_vector (cnt32_reg ( 31 downto 24 ))) when
else (others => '0');□
  □
vme_en_out <= ena;□
  -----
  -- DTACK generation□
  -----
  □
  -- we do need a special dtack generation:□
  -- dtack is delayed if registers are not ready when□
  -- reading from tdi or writing to tms0/1, tdo and cnt32.□

```

```

-- HS : do not yet understand ds_synch story .□
Dtack_Synchro : process (clk, nreset)□
begin
  if nreset = '0' then□
    reg_rdy_ff <= '0';□
--    ds del sig <= '0';□
  elsif clk'event and clk='1' then□
    if ds_synch = "00" then□
      ds del sig <= '0';□
--    elsif ( not (ds_synch = "00" ) and valid_address = '1' ) then□
--      ds_del_sig <= '1';□
    end if;□
  --    if ds_synch = "00" then□
  --      reg rdy ff <= '0';□
  --    elsif ds_del_sig = '1' then□
    if ena = '0' then□
      reg rdy ff <= '0';□
    else□
      if ( tdi_ena or tdo_ena or tms0_ena or tms1_ena or cnt32_ena) = '1' then□
        reg rdy ff <= dtack ff;□
      else□
        reg_rdy_ff <= '1';□
      end if;□
    end if;□
  end if;□
  end process Dtack_Synchro;□
-- □
Dtack_del_proc : process ( clk, nreset)□
begin
  if ( nreset = '0' ) then□
    reg_rdy_ff_del <= '0';□
--    dtack_del <= '0';□
  elsif clk'event and clk='1' then□
    reg_rdy_ff_del <= reg_rdy_ff;□
--    dtack_del <= int_dtack;□
  end if;□
  end process Dtack_del_proc;□
int_dtack <= reg_rdy_ff_del and ena;□
vme_dtack <= int_dtack;□
-- generate dtack only when register is ready to be read/written□
-- HS: deadlocks: two successive writes to cnt without □
Jtag_dtack : process ( clk, nreset)□
begin
  if ( nreset = '0' ) then□
    dtack_ff <= '0';□
  elsif clk'event and clk='1' then□
    if ena = '1' then□
      if (( cnt32_ena = '1' ) and ( vme_wr = '1' ) and ( cnt_loaded = '0' )) then□
        dtack_ff <= '1';□
      elsif (( cnt32_ena = '1' ) and ( vme_wr = '0' )) then□

```

```

        dtack_ff <= '1';□
    end if;□
    □
    if (( tdo_ena = '1' ) and ( vme_wr = '1' ) and ( tdo_empty = '1' )) then□
        dtack_ff <= '1';□
    elsif (( tdo_ena = '1' ) and ( vme_wr = '0' )) then□
        dtack_ff <= '1';□
    end if;□
    □
    if (( tms0_ena = '1' ) and ( vme_wr = '1' ) and ( tms0_empty = '1' )) then□
        dtack_ff <= '1';□
    elsif (( tms0_ena = '1' ) and ( vme_wr = '0' )) then□
        dtack_ff <= '1';□
    end if;□
    □
    if (( tms1_ena = '1' ) and ( vme_wr = '1' ) and ( tms1_empty = '1' )) then□
        dtack_ff <= '1';□
    elsif (( tms1_ena = '1' ) and ( vme_wr = '0' )) then□
        dtack_ff <= '1';□
    end if;□
    □
    if (( tdi_ena = '1' ) and ( vme_wr = '0' ) and ( tdi_full = '1' )) then□
        dtack_ff <= '1';□
    elsif (( tdi_ena = '1' ) and ( vme_wr = '1' )) then□
        dtack_ff <= '1';□
    end if;□
    □
    else□
        dtack_ff <= '0';□
    end if;□
    □
    □
    end if;□
end process Jtag_dtack;□
    □
    □
    □
    □
    □
    -----
-- Generate JTAG Clock 40 MHz / 4 = 10 MHz□
-----
JTAG_Clock : process (clk, nreset)□
begin
    □
    if ( nreset = '0' ) then□
        □
        jtag_ck_cnt      <= (others => '0');□
        jtag_ck          <= '0';□
        jtag_ck_pulse    <= '0';□
        □
    elsif clk'event and clk='1' then□
        □
        if ( shift_enable = '1' ) then□
            jtag_ck_cnt <= jtag_ck_cnt + 1;□
        end if;□
        □
        if ( shift_enable = '0' ) then□
            jtag_ck_cnt <= (others => '0');□
        end if;□
        □
        jtag_ck <= jtag_ck_cnt (2);□
        □
        -- pulse on rising JTAG clock□
        if (( jtag_ck_cnt (2) = '1' ) and ( jtag_ck = '0' )) then□
            jtag_ck_pulse <= '1';□

```

```

else
  jtag_ck_pulse <= '0';
end if;

-- end if;
end process JTAG_Clock;

-----
-- memorize last TMS operation
-----

TMSmem : process (clk, nreset)
begin
  if ( nreset = '0' ) then
    tms01_sig <= '0';
  elsif clk'event and clk='1' then
    if tms0_enable = '1' then
      tms01_sig <= '0';
    elsif tms1_enable = '1' then
      tms01_sig <= '1';
    end if;
  end if;
end process TMSmem;

cnt001 <= '1' when ( cnt32_reg = "00000000000000000000000000000001" ) else '0';

-----
-- 32 bit counter
-----

Counter : process (clk, nreset)
begin
  if ( nreset = '0' ) then
    cnt32_reg      <= (others => '0');
    cnt_pointer    <= (others => '0');
    cnt_stat       <= '0';
    cnt_stat_del   <= '0';
    cnt_loaded     <= '0';
    cnt_loaded_del <= '0';
    tms0_a_exit    <= '0';
    tms1_a_exit    <= '0';
  elsif clk'event and clk='1' then
    if int_reset = '1' then
      cnt32_reg      <= (others => '0');
      cnt_pointer    <= (others => '0');
      cnt_stat       <= '0';
      cnt_stat_del   <= '0';
      cnt_loaded     <= '0';
      cnt_loaded_del <= '0';
      tms0_a_exit    <= '0';
      tms1_a_exit    <= '0';
    end if;
  end if;

  --
  -- Load counter
  --
  if (( vme_wr = '1' ) and ( cnt32_ena = '1' ) and ( cnt_loaded = '0' )) then
    cnt_stat <= '1';
    case cnt_pointer is
      when "00"  => cnt32_reg ( 7 downto 0 ) <= unsigned ( vme_data ( 7 downto 0 ) );
      when "01"  => cnt32_reg ( 15 downto 8 ) <= unsigned ( vme_data ( 7 downto 0 ) );
      when "10"  => cnt32_reg ( 23 downto 16 ) <= unsigned ( vme_data ( 7 downto 0 ) );
      when "11"  => cnt32_reg ( 31 downto 24 ) <= unsigned ( vme_data ( 7 downto 0 ) );
    end case;
  end if;
end process;

```

```

        when others => cnt32_reg ( 7 downto 0 )      <= unsigned ( vme_data ( 7 downto 0 ) )
    end case;□
end if;□
□
--□
-- Increment pointer at end of VME cycle□
--□
if ( ( vme_cycend_p = '1' ) and ( cnt_stat = '1' ) ) then□
    cnt_pointer      <= cnt_pointer + 1;□
    cnt_stat         <= '0';□
    if cnt_pointer = "11" then□
        cnt_loaded_del <= '1';□
    end if;□
end if;□
□
cnt_loaded <= cnt_loaded_del;□
□
if cnt_loaded = '1' then□
    cnt_pointer <= (others => '0');□
end if;□
□
--□
-- count down□
--□
if ( ( jtag_ck_pulse = '1' ) and ( shift_enable = '1' ) ) then□
    cnt32_reg      <= cnt32_reg - 1;□
    if cnt001 = '1' then□
        cnt_loaded_del <= '0';□
    end if;□
end if;□
□
--□
-- auto TMS high□
-- □
if ( ( auto_tms_h = '1' ) and ( cnt001 = '1' ) and ( cnt_loaded = '1' ) ) then□
    if tms01_sig = '0' then□
        tms0_a_exit <= '1';□
    else□
        tms1_a_exit <= '1';□
    end if;□
end if;□
□
if ( cnt32_reg = "0000000000000000000000000000000000000000000000" ) then□
    tms0_a_exit <= '0';□
    tms1_a_exit <= '0';□
end if;□
□
end if;□
end process Counter;□
□
-----□
-- TMS 0□
-----□
tms0 : process (clk, nreset)□
□
    variable tms0_bytcnt : unsigned ( 3 downto 0 );□
□
begin□
□
    if ( nreset = '0' ) then□
        tms0_reg      <= (others => '0');□
        tms0_empty     <= '1';□
        tms0_empty_del <= '1';□
        tms0_bytcnt := (others      => '0');□
        tms0_stat      <= '0';□
        tms0_stat_del  <= '0';□
    end if;□

```

```

elsif clk'event and clk='1' then
  if int_reset = '1' then
    tms0_reg      <= (others => '0');□
    tms0_empty    <= '1';□
    tms0_empty_del <= '1';□
    tms0_bytcnt := (others      => '0');□
    tms0_stat     <= '0';□
    tms0_stat_del <= '0';□
  end if;□
□
  tms0_empty <= tms0_empty del;□
□
-- load TMS0 register
if ( vme_wr and tms0_ena ) = '1' and tms0_empty = '1' then
  tms0_reg      <= vme_data ( 7 downto 0);□
  tms0_stat_del <= '1';□
end if;□
□
tms0_stat <= tms0_stat_del;□
□
if (( tms0_stat = '1' ) and ( vme_cycend_p = '1' )) then
  tms0_bytcnt := "1000";□
  tms0_empty_del <= '0';□
  tms0_stat_del <= '0';□
end if;□
□
if (( jtag_ck_pulse = '1' ) and ( shift_enable = '1' ) and ( tms0_enable = '1' )) th
  tms0_reg <= '0' & tms0_reg ( 7 downto 1);□
□
  tms0_bytcnt := tms0_bytcnt - 1;□
□
  if tms0_bytcnt = "0000" then
    tms0_empty_del <= '1';□
  end if;□
end if;□
  if cnt_loaded_del = '0' then
    tms0_empty_del <= '1';□
  end if;□
end if;□
end process tms0;□
□
stms0 <= tms0_reg (0) or tms0_a_exit;□
□
-----
-- TMS 1
-----
tms1 : process (clk, nreset)□
□
  variable tms1_bytcnt : unsigned ( 3 downto 0 );□
□
begin
  if ( nreset = '0' ) then
    tms1_reg      <= (others => '0');□
    tms1_empty    <= '1';□
    tms1_empty_del <= '1';□
    tms1_bytcnt := (others      => '0');□
    tms1_stat     <= '0';□
    tms1_stat_del <= '0';□
  end if;
  elsif clk'event and clk='1' then
    if int_reset = '1' then
      tms1_reg      <= (others => '0');□
      tms1_empty    <= '1';□
      tms1_empty_del <= '1';□
      tms1_bytcnt := (others      => '0');□
      tms1_stat     <= '0';□
    end if;
  end if;
end process;

```

```

    tms1_stat_del <= '0';□
end if;□
□
tms1_empty <= tms1_empty_del;□
□
if ( vme_wr and tms1_ena ) = '1' and tms1_empty = '1' then□
    tms1_reg      <= vme_data ( 7 downto 0);□
    tms1_stat_del <= '1';□
end if;□
□
tms1_stat <= tms1_stat_del;□
□
if (( tms1_stat = '1' ) and ( vme_cycend_p = '1' )) then□
    tms1_bytcnt := "1000";□
    tms1_empty_del <= '0';□
    tms1_stat_del <= '0';□
end if;□
if (( jtag_ck_pulse = '1' ) and ( shift_enable = '1' ) and ( tms1_enable = '1' )) then□
    tms1_reg <= '0' & tms1_reg ( 7 downto 1);□
□
tms1_bytcnt := tms1_bytcnt - 1;□
□
if tms1_bytcnt = "0000" then□
    tms1_empty_del <= '1';□
end if;□
end if;□
if cnt_loaded = '0' then□
    tms1_empty_del <= '1';□
end if;□
end if;□
end process tms1;□
□
stms1 <= tms1_reg (0) or tms1_a_exit;□
□
-----□
-- TDO□
-----□
tdo : process (clk, nreset)□
□
variable tdo_bytcnt : unsigned ( 3 downto 0 );□
□
begin□
□
if ( nreset = '0' ) then□
    tdo_reg      <= (others => '0');□
    tdo_empty     <= '1';□
    tdo_empty_del <= '1';□
    tdo_bytcnt := (others      => '0');□
    tdo_stat      <= '0';□
    tdo_stat_del <= '0';□
□
elsif clk'event and clk='1' then□
    if int_reset = '1' then□
        tdo_reg      <= (others => '0');□
        tdo_empty_del <= '1';□
        tdo_bytcnt := (others      => '0');□
        tdo_stat      <= '0';□
        tdo_stat_del <= '0';□
    end if;□
□
    tdo_empty <= tdo_empty_del;□
□
if ( vme_wr and tdo_ena ) = '1' and tdo_empty = '1' then□
    tdo_reg      <= vme_data ( 7 downto 0);□
    tdo_stat_del <= '1';□
end if;□
□
    tdo_stat <= tdo_stat_del;□

```

```

if tdo_stat = '1' and vme_cycend_p = '1' then
  tdo_bytcnt := "1000";□
  tdo_empty_del <= '0';□
  tdo_stat_del <= '0';□
end if;□

if (( jtag_ck_pulse = '1' ) and ( shift_enable = '1' ) and ( tdo_enable = '1')) then
  tdo_reg <= '0' & tdo_reg ( 7 downto 1);□

  tdo_bytcnt := tdo_bytcnt - 1;□

  if tdo_bytcnt = "0000" then
    tdo_empty_del <= '1';□
  end if;□
end if;□

if cnt_loaded = '0' then
  tdo_empty_del <= '1';□
end if;□
end if;□
end process tdo;□

stdo <= tdo_reg (0);□

-----
-- TDI
-----
tdi : process (clk, nreset)□
variable tdi_bytcnt : unsigned ( 3 downto 0 );□
begin
  if ( nreset = '0' ) then
    tdi_reg <= (others => '0');□
    tdi_full_del <= '0';□
    tdi_full <= '0';□
    tdi_bytcnt := "1000";□
    -- tdi_ena_d <= '0';□
    -- tdi_ena_d2 <= '0';□
    tdi_stat <= '0';□
  elsif clk'event and clk='1' then
    if int_reset = '1' then
      tdi_reg <= (others => '0');□
      tdi_full_del <= '0';□
      tdi_full <= '0';□
      tdi_bytcnt := "1000";□
      tdi_stat <= '0';□
    end if;□
  end if;
  -- delay tdi_ena so that it is still valid during vme_cycend_p
  -- tdi_ena_d <= tdi_ena;           □
  -- tdi_ena_d2 <= tdi_ena_d;        □
  -- vme_wr stays on bus longer, do not need to delay
  -- set stat if there is a read on the TDI register
  if (( vme_wr = '0' ) and ( tdi_ena = '1' ) and ( tdi_full = '1' )) then
    tdi_stat <= '1';□
  end if;□
  -- if stat is set, clear full on end of cycle
  if ( (tdi_stat = '1') and (vme_cycend_p = '1')) then
    tdi_stat <= '0';□
    tdi_full_del <= '0';□
    tdi_bytcnt := "1000";□
  end if;□

```

```

    tdi_full <= tdi_full_del; -- Delay full signal by one clock
    if (( jtag_ck_pulse = '1' ) and ( shift_enable = '1' ) and ( tdi_enable = '1' )) then
        tdi_reg ( 6 downto 0 ) <= tdi_reg ( 7 downto 1 );
        if tms01_sig = '0' then
            tdi_reg ( 7 ) <= stdi0;
        else
            tdi_reg ( 7 ) <= stdi1;
        end if;
        tdi_bytcnt := tdi_bytcnt - 1;
        -- HS: condition unnecessary? would not get here if shift_enable was 0
        if (( tdi_bytcnt = "0000" ) or (shift_enable = '0')) then
            tdi_full_del <= '1';
        end if;
    end if;

    -- stop shifting if at last JTAG clock pulse
    if (( jtag_ck_pulse = '1' ) and ( cnt001 = '1' ) and ( tdi_enable = '1' ))then
        tdi_full_del <= '1';
    end if;
end if;

-- HS: why different stop conditions? cnt_loaded, cnt_loaded_del, cnt001
end process tdi;

-----Shift Enable-----
-- HS: shift enable, when counter loaded _AND_ one of the following:
--      TMS0 enabled and not empty
--      TMS1 enabled and not empty
--      TDO enabled and not empty _AND_ TDI enabled and not full
-- only works if TDO and TDI are enabled and if TDI is actually read out
shift_en_proc : process (clk, nreset)
begin
    if ( nreset = '0' ) then
        shift_enable <= '0';
    elsif clk'event and clk='1' then
        if cnt_loaded = '1' then
            if (tms0_enable = '1') and (tms0_empty = '0' ) then
                shift_enable <= '1';
            elsif ((tms1_enable = '1') and (tms1_empty = '0' )) then
                shift_enable <= '1';
            elsif ((tdo_enable = '1') and (tdo_empty = '0' )
                    and (tdi_enable = '1') and (tdi_full = '0' )) then
                shift_enable <= '1';
            else
                shift_enable <= '0';
        end if;
    end if;
end process;

```

```
    end if;□
  else□
    shift_enable <= '0';□
  □
    end if;□
  end if;□
end process shift_en_proc;□
□
-----□
-- Test clock generation□
-----□
□
-- HS: why invert the clock ??□
-- internal operations shpuld happen on falling edge, external ones on rising□
-- edge. □
□
tclk generation : process (clk, nreset)□
□
begin□
□
  if ( nreset = '0' ) then□
    □
      oTck <= '0';□
    □
    elsif clk'event and clk='1' then□
      if shift enable = '1' then□
        oTck <= not jtag_ck;□
      else□
        oTck <= '0';□
      end if;□
    end if;□
  □
end process tclk_generation;□
□
□
□
-----□
□
oTdo <= stdo;□
oTms0 <= stms0;□
oTms1 <= stms1; □
stdi0 <= iTdi0; □
stdi1 <= iTdi1;           -- Separate TDI inputs (as long no tri-state at ETTF_F
□
□
end behavioral;□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
□
```

```

-----
--                                         --
-- LOGIC CORE: GTL-module vme chip logic   --
-- MODULE NAME: cnt_8bit                   --
-- INSTITUTION: Hephzibah Vienna          --
-- DESIGNER: H. Bergauer                  --
--                                         --
-- VERSION: V1.0                          --
-- DATE: 11 2005                         --
--                                         --
-- FUNCTIONAL DESCRIPTION:               --
-- 8-bit counter                         --
--                                         --
LIBRARY ieee;□
USE ieee.std_logic_1164.ALL;□
LIBRARY lpm;□
USE lpm.lpm_components.ALL;□
□
ENTITY cnt_8bit IS□
  PORT(□
    ld_data : IN      STD_LOGIC_VECTOR(7 DOWNTO 0);□
    clk      : IN      STD_LOGIC;□
    clk_en   : IN      STD_LOGIC;□
    cnt_en   : IN      STD_LOGIC;□
    updown   : IN      STD_LOGIC;□
    cin      : IN      STD_LOGIC;□
    aclr     : IN      STD_LOGIC;□
    sclr     : IN      STD_LOGIC;□
    aload    : IN      STD_LOGIC;□
    sload    : IN      STD_LOGIC;□
    cout     : OUT     STD_LOGIC;□
    out_data : OUT     STD_LOGIC_VECTOR(7 DOWNTO 0));□
END cnt_8bit;□
□
ARCHITECTURE rtl OF cnt_8bit IS□
BEGIN□
  □
  inst cnt: lpm_counter□
    GENERIC MAP(LPM_WIDTH => 8,□
                LPM_TYPE => "LPM_COUNTER")□
    PORT MAP(data => ld_data,□
              clock => clk,□
              clk_en => clk_en,□
              cnt_en => cnt_en,□
              updown => updown,□
              cin => cin,□
              aclr => aclr,□
              sclr => sclr,□
              aload => aload,□
              sload => sload,□
              cout => cout,□
              q => out_data);□
  □
END ARCHITECTURE rtl;□

```